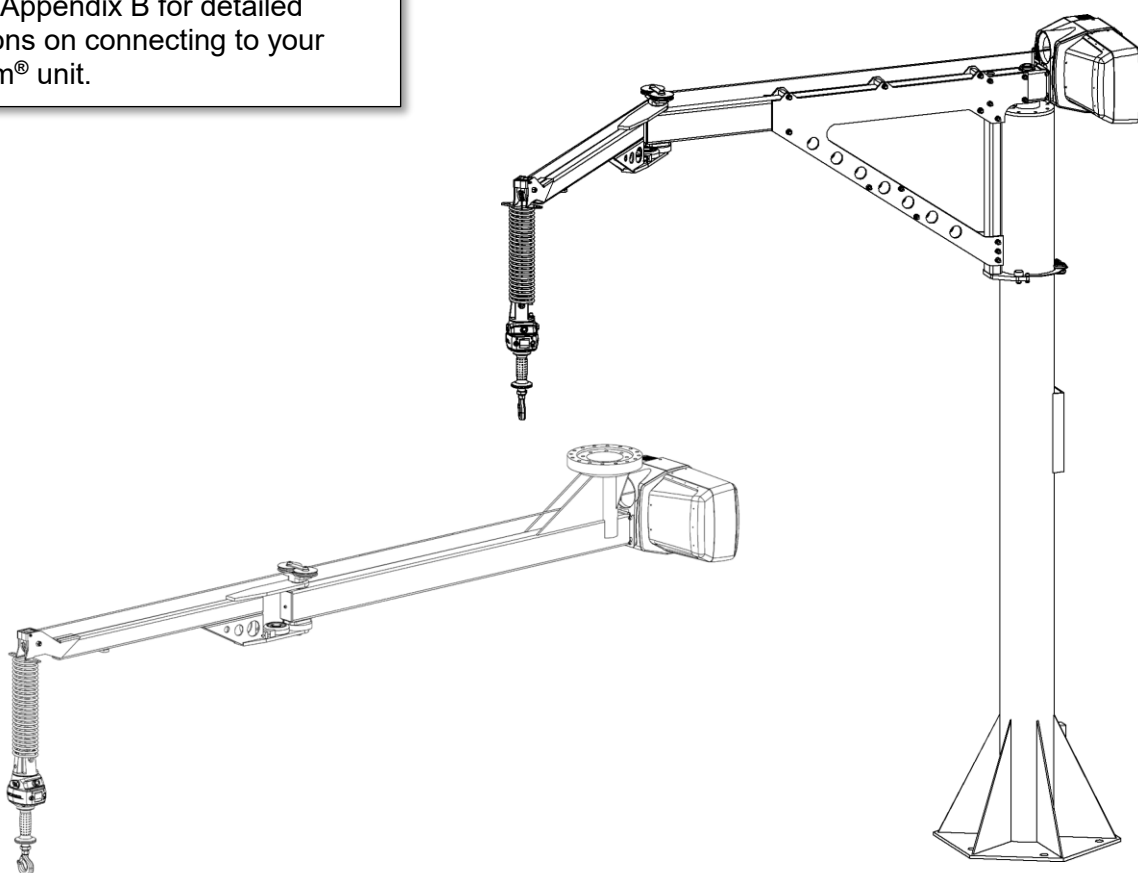


Default Settings for your Gorbel Easy Arm® unit:

- ☐ *AP SSID:* G-Force AP Order Number
- ☐ *AP Password:* Order Number
- ☐ *Station SSID:* G-Force STA
- ☐ *Station Password:* mypassword

Refer to Appendix B for detailed instructions on connecting to your Easy Arm® unit.

Installation, Operation, & Maintenance Manual



Distributed by Ergonomic Partners

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Tel: (314) 884-8884

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Easy Arm® Q2 & iQ2 Series

Gorbel® Customer Order No. / Serial No. _____

Gorbel® Dealer _____

For the latest version of this manual, go to:
<https://www.ergonomicpartners.com/gorbel-easy-arm>

Date _____
Month _____ Year _____

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SAFE HOIST OPERATING GUIDELINES

General

There is no one single factor that is more important for minimizing the possibility of personal injury to the operator and those working in the area, or damage to property, equipment, or material than being familiar with the equipment and using Safe Operating Practices.

Hoists/trolleys are designed for lifting and transporting of material only. Under no circumstances, either during initial installation or in any other use, should the hoist be used for lifting or transporting personnel.

No operator should be permitted to use the equipment that is not familiar with its operation, is not physically or mentally fit, or has not been schooled in safe operating practices. The misuse of hoists can lead to certain hazards which cannot be protected against by mechanical means; hazards which can only be avoided by the exercise of intelligence, care, and common sense.

Safe Operating Practices also involve a program of periodic inspection and preventative maintenance (covered in a separate section). Part of the operator's training should be an awareness of potential malfunctions/hazards requiring adjustments or repairs, and bringing these to the attention of supervision for corrective action.

Supervision and management also have an important role to play in any safety program by ensuring that a maintenance schedule is adhered to, and that the equipment provided for the operators is suitable for the job intended without violation of one or more of the rules covering safe operating practices and good common sense.

The Safe Operating Practices shown are taken in part from the following publications:

- American National Standard Institute (ANSI)
- Safety Standards for Cranes, Derricks, Hoists
- ANSI B30.2 - Overhead and Gantry Cranes
- ANSI B30.16 - Overhead Hoists

Do's and Don'ts (Safe Operation of Hoists)

The following are Do's and Don'ts for safe operation of overhead hoists. A few minutes spent reading these rules can make an operator aware of dangerous practices to avoid and precautions to take for his own safety and the safety of others. Frequent examinations and periodic inspections of the equipment as well as a conscientious observance of safety rules may save lives as well as time and money.

DON'TS - HOISTS

1. Never lift or transport a load until all personnel are clear and do not transport the load over personnel.
2. Do not allow any unqualified personnel to operate hoist.
3. Never pick up a load beyond the capacity rating appearing on the hoist. Overloading can be caused by jerking as well as by static overload.
4. Never carry personnel on the hook or the load.
5. Do not operate hoist if you are not physically fit.
6. Do not operate hoist to extreme limits of travel of cable without first checking for proper limit switch action.

7. Avoid sharp contact between two hoists or between hoist and end stop.
8. Do not tamper with or adjust any parts of the hoist unless specifically authorized to do so.
9. Never use the load cable as a sling.
10. Do not divert attention from load while operating hoist.
11. Never leave a suspended load unattended.
12. Do not use limit switch(es) for normal operating stop(s). These are safety devices only and should be checked on a regular basis for proper operation.
13. Never operate a hoist that has an inherent or suspected mechanical or electrical defect.
14. Do not use load cable as a ground for welding. Never touch a live welding electrode to the load cable.
15. Do not jog controls unnecessarily. Hoist motors are generally high torque, high slip types. Each start causes an inrush of current greater than the running current and leads to overheating and current failure, or burnout, if continued to excess.
16. Do not operate hoist if load is not centered under hoist.
17. Do not operate hoist if cable is twisted, kinked, or damaged.
18. Do not remove or obscure label.
19. Do not permanently activate operator present sensor.

DO'S - HOISTS

1. Read and follow manufacturer's instruction, installation, and maintenance manuals. When repairing or maintaining a hoist, use only manufacturer's recommended parts and materials.
2. Read and follow all instruction and warning information on or attached to a hoist.
3. Remove the hoist from service and thoroughly inspect and repair, as necessary, if unusual performance or visual defects (such as peculiar noise, jerky operations, travel in improper direction, or obviously damaged parts) are noticed.
4. Establish a regular schedule of inspection and maintain records for all hoists with special attention given to hooks, load cables, brakes, and limit switches.
5. Check operation of brakes for excessive drift.
6. Never lift loads over people, etc.
7. Check for damaged hooks and load cable.
8. Keep load cable clean and well maintained.
9. Check the load cable for improper seating, twisting, kinking, wear, or other defects before operating the hoist.
10. Make sure a load clears neighboring stockpiles, machinery, or other obstructions when raising, lowering, or traveling the load.
11. Center hoist over the load before operating.
12. Avoid swinging of load or load hook when traveling the hoist.
13. Be sure the load attachment is properly seated in the saddle of the hook. Balance load properly before handling. Avoid hook tip loading.
14. Pull in a straight line, so that neither hoist body nor load cable are angled around an object.
15. Take up slack slowly.
16. Know the hand signals for hoisting, cross travel, and crane travel if working with cab-operated hoists or cranes. Operators should accept signals of only those persons authorized to give them.

WARNINGS

IMPORTANT SAFETY INSTRUCTIONS

WARNINGS

1. All operators should read the Easy Arm® Installation and Operation Manual before operating the unit.
2. Check wire rope for improper seating, twisting, kinking, wear, or defects before operating.
3. Check the coil cord for improper seating, twisting, kinking, wear, or defects before operating. Any of the described conditions will seriously reduce the life of the coil cord and lead to premature failure.
4. Press the G-Force® logo button for Float Mode (option) with only the load weight hanging from the unit. Additional external forces applied to the load during initiation of Float Mode will result in the load drifting.
5. Avoid repeatedly impacting the Easy Arm® into the rotation stops.
6. The Easy Arm® does not meet “wash-down” environment requirements. The Easy Arm® does not meet “explosion proof” requirements.
7. Ensure that the slide handle is supported properly in remote mounted handle applications by mounting the slide handle at both the top and bottom mounting points.
8. Do not mount any objects to the Easy Arm® slide handle grip (i.e. switches). Additional objects may interfere with the travel of the sliding handle grip and affect the overall speed and functionality of the unit.
9. Do not mount any load bearing components to the blue housing of the Easy Arm® slide handle, pendant handle, or actuator assembly.

TOOLING INTEGRATION GUIDELINES

1. All tooling must be retained to the G360™ assembly utilizing the M16 thread and locking pin provided. The locking pin is optional on Slide Handle and Wire Rope Swivel assemblies if proper inspection and maintenance procedures are followed.
2. Do not mount anything to the Easy Arm® handle housing. Use supplied brackets, valves, and switches whenever possible.
3. In-line tooling must always be centered directly under the hand controller.
4. Tooling design which does not keep the tooling level; and balanced in both the loaded and unloaded condition may induce a bending force on the handle and/or collector assembly which may reduce the life and/or performance of the handle and/or collector assembly.
5. Do not mount anything to the sliding portion of the Easy Arm® hand controller.
6. Do not alter or add conductors to the Easy Arm® coil cord.
7. Use only Gorbels' slide on air hose (slides over coil cord) to supply air power to end effector tooling. Gorbels cannot guarantee performance or functionality of other methods of supplying air power to end effector tooling.
8. All cables used in a remote mounted handle configuration must be properly clamped and/or strain-relieved to prevent premature failure of the Easy Arm® or customer tooling.

INTRODUCTION

Thank you for choosing a Gorbels® Easy Arm® Crane** to solve your material handling needs. The innovative design and heavy-duty construction of the Easy Arm® will provide a superior quality product that will offer years of long term value. A Gorbels® Easy Arm® will provide many years of dependable service by following the installation and maintenance procedures described herein.

** U.S. Patent No's: 5,865,426, 6,299,139, & 6,386,513, Other Patents Pending

CE certification is only applicable to systems directly wired to manufactures suggested voltage.

Dimensions contained in this installation manual are for reference only and may differ for your particular application.

WARNING

Only competent erection personnel familiar with standard fabrication practices should be employed to install the Easy Arm® because of the necessity of properly interpreting these instructions. Gorbels is not responsible for the quality of workmanship employed in the installation of this hoist according to these instructions. Contact Gorbels, Inc., at 600 Fishers Run, P.O. Box 593, Fishers, New York 14453, for additional information if necessary.

WARNING

Equipment described herein is not designed for, and should not be used for, lifting, supporting, or transporting humans. Failure to comply with any one of the limitations noted herein can result in serious bodily injury and/or property damage. Check Federal, State and Local regulations for any additional requirements.

WARNING

Gorbels Inc. authorizes use of wire rope only as supplied by Gorbels for any Easy Arm® equipment. Use of other than Gorbels supplied wire rope shall void Gorbels's warranty of the product.

WARNING

Prior to installation, consult a qualified structural engineer to determine if your support structure is adequate to support the loadings created during normal operation of the Easy Arm®.

WARNING

Reference American Institute of Steel Construction (AISC) Manual of Steel Construction (9th edition), Part 5, Specification for Structural Joints using ASTM A325 or A490 Bolts (section 8.d.2) for proper procedure to follow when using any torque tightening methods.

WARNING

Easy Arm® cannot be used as a ground. A separate ground wire is required. For example, systems with 3-phase power require 3 conductors plus one ground wire.

WARNING

Do not field modify the Easy Arm® actuator or handles in any way. Any modification, without the written consent of Gorbels, Inc., will void warranty.

WARNING

The jog switch buttons are for system maintenance and load testing only, and should not be manipulated during normal operation of the Easy Arm®. Operation of the jog switch buttons during normal operation increases the risk of personal injury to the operator.

WARNING

The unique serial number for this unit can be found on the front cover of this manual or on a sticker attached to the back of the head assembly. Always have this serial number available during all correspondence regarding your Easy Arm® crane, or when ordering repair parts.

WARNING

Maximum Operational Ambient Temperature is 50°C (122°F).

INSTALLATION

STEP 1 - PRE-ASSEMBLY

- 1.1 Read entire installation manual **before** installing the crane.
- 1.2 Check packing list to ensure no parts have been lost prior to initiating assembly of crane.
- 1.3 Tools and materials (by others) typically needed to assemble crane:
 - Torque wrench with metric sockets
 - Metric Allen wrenches
 - Grout (Non-Shrink Precision Grout)
 - Lifting device to lift heavy mast and arm assembly
 - Hand tools
 - Ladders / man lifts
 - Level
- 1.4 For Floor Mounted Easy Arm®, identify crane size, anchor bolt load, and footer width and depth.

CAPACITY	HUH	SPAN	MODEL NUMBER (Q or iQ)	MIN. FOOTER DEPTH	MIN. FOOTER WIDTH	ANCHOR BOLT LOAD (KIPS)
165#	6'	6'	EA-F-165-6-6	6"	48"	0.94
		8'	EA-F-165-6-8	6"	48"	1.32
		10'	EA-F-165-6-10	6"	60"	1.72
		12'	EA-F-165-6-12	6"	60"	0.99
		14'	EA-F-165-6-14	6"	60"	1.23
	8'	6'	EA-F-165-8-6	6"	48"	0.94
		8'	EA-F-165-8-8	6"	48"	1.32
		10'	EA-F-165-8-10	6"	60"	0.79
		12'	EA-F-165-8-12	6"	60"	0.99
		14'	EA-F-165-8-14	6"	60"	1.23
	10'	6'	EA-F-165-10-6	6"	48"	0.94
		8'	EA-F-165-10-8	6"	48"	0.59
		10'	EA-F-165-10-10	6"	60"	0.79
		12'	EA-F-165-10-12	6"	60"	0.99
		14'	EA-F-165-10-14	6"	60"	1.23
	11'	6'	EA-F-165-11-6	6"	48"	0.94
		8'	EA-F-165-11-8	6"	48"	0.59
		10'	EA-F-165-11-10	6"	60"	0.79
		12'	EA-F-165-11-12	6"	60"	0.99
		14'	EA-F-165-11-14	6"	60"	1.23
330#	6'	6'	EA-F-330-6-6	6"	60"	0.71
		8'	EA-F-330-6-8	6"	60"	1.02
		10'	EA-F-330-6-10	6"	72"	1.37
		12'	EA-F-330-6-12	6"	72"	1.71
		14'	EA-F-330-6-14	6"	72"	2.07
	8'	6'	EA-F-330-8-6	6"	60"	0.71
		8'	EA-F-330-8-8	6"	60"	1.02
		10'	EA-F-330-8-10	6"	72"	1.37
		12'	EA-F-330-8-12	6"	72"	1.71
		14'	EA-F-330-8-14	6"	72"	2.07
	10'	6'	EA-F-330-10-6	6"	60"	0.71
		8'	EA-F-330-10-8	6"	60"	1.02
		10'	EA-F-330-10-10	6"	72"	1.37
		12'	EA-F-330-10-12	6"	72"	1.71
		14'	EA-F-330-10-14	6"	72"	2.07
	11'	6'	EA-F-330-11-6	6"	60"	0.71
		8'	EA-F-330-11-8	6"	60"	1.02
		10'	EA-F-330-11-10	6"	72"	1.37
		12'	EA-F-330-11-12	6"	72"	1.71
		14'	EA-F-330-11-14	6"	72"	2.07

Chart 1A. Floor Mounted Easy Arm® Footer Depth, Width and Anchor Bolt Loadings.

STEP 1 - PRE-ASSEMBLY (CONTINUED)

1.4 Continued:

CAPACITY	HUH	SPAN	MODEL NUMBER (Q or iQ)	MIN. FOOTER DEPTH	MIN. FOOTER WIDTH	ANCHOR BOLT LOAD (KIPS)
660#	6'	8'	EA-F-660-6-8	6"	72"	1.41
		10'	EA-F-660-6-10	8"	72"	1.87
		12'	EA-F-660-6-12	24"	60"	0.96
		14'	EA-F-660-6-14	24"	60"	1.17
	8'	8'	EA-F-660-8-8	6"	72"	1.41
		10'	EA-F-660-8-10	8"	72"	1.87
		12'	EA-F-660-8-12	24"	60"	0.96
		14'	EA-F-660-8-14	24"	60"	1.17
	10'	8'	EA-F-660-10-8	6"	72"	1.41
		10'	EA-F-660-10-10	8"	72"	1.87
		12'	EA-F-660-10-12	24"	60"	0.96
		14'	EA-F-660-10-14	24"	60"	1.17
	11'	8'	EA-F-660-11-8	6"	72"	1.41
		10'	EA-F-660-11-10	8"	72"	1.87
		12'	EA-F-660-11-12	24"	60"	0.96
		14'	EA-F-660-11-14	24"	60"	1.17

Chart 1A. Floor Mounted Easy Arm® Footer Depth, Width and Anchor Bolt Loadings.

- 1.5** The Under Hung unit is designed to be mounted to a platform using eight (8) M16 x 2.0mm pitch, hex head cap screws and lockwashers. The top mounting surface is part of a large bearing which allows the main pivoting movement of the unit. The bearing is provided with 16 tapped holes on a 10.63 inch diameter bolt circle. The mounting platform must also have a center hole for the power cable to pass through.

The required fastener length will depend upon the design of the mounting platform. The length should allow for the lockwasher thickness, the mounting plate thickness, and a minimum of one inch insertion into the tapped hole.

Please refer to **chart 1B** for the minimum bolt loads. A class 10.9 fastener (or better) is recommended.

The mounting platform should be level and should have a flat mating surface. A level platform provides a vertical axis of rotation for the bearings and prevents drifting of the arms. If the platform is moveable there should be some provision in the design to prevent the tilting of the mounting surface due to large moment loads (e.g. limit vertical movement of trolley wheels). The flatness of the mating surface is required to ensure the smooth operation of the bearing.

CAPACITY	SPAN	MODEL NUMBER (Q2 or iQ2)	MOUNTING BOLT LOAD
165#	6'	EA-U-165-6	930#
	8'	EA-U-165-8	1250#
	10'	EA-U-165-10	1580#

Chart 1B. Under Hung Easy Arm® Mounting Bolt Loads.

STEP 1 - PRE-ASSEMBLY (CONTINUED)

- 1.6 Prior to installing the Easy Arm®, it is a good idea to familiarize yourself with the main components.

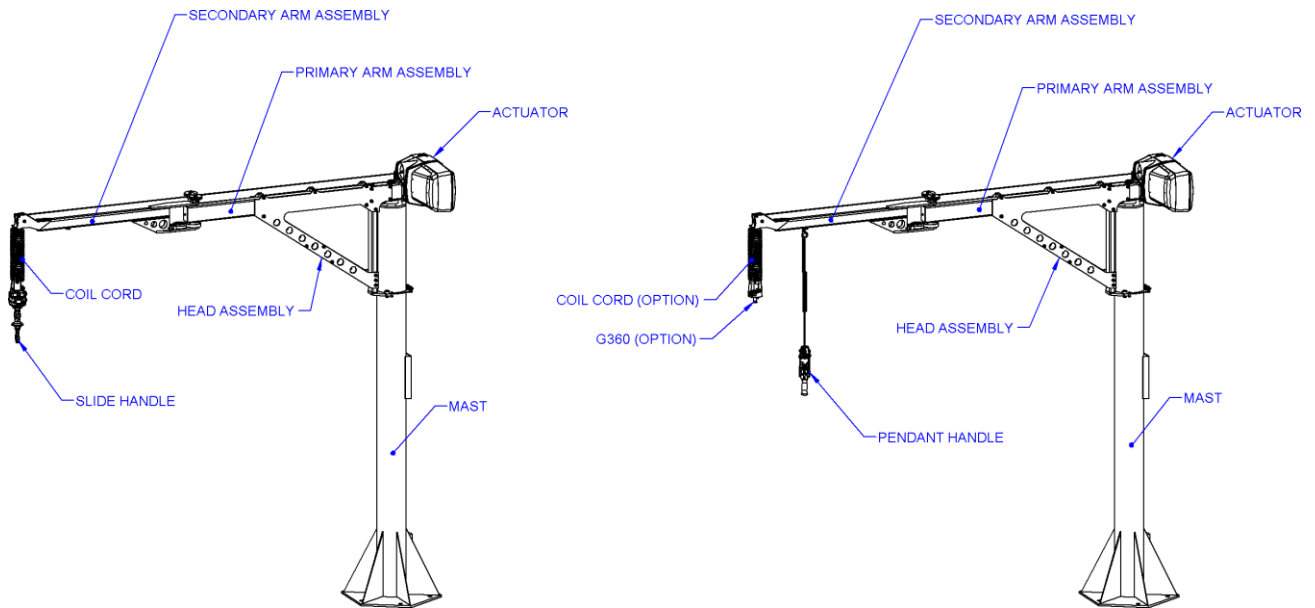


Diagram 1A. Main Floor Mounted Easy Arm® Components.

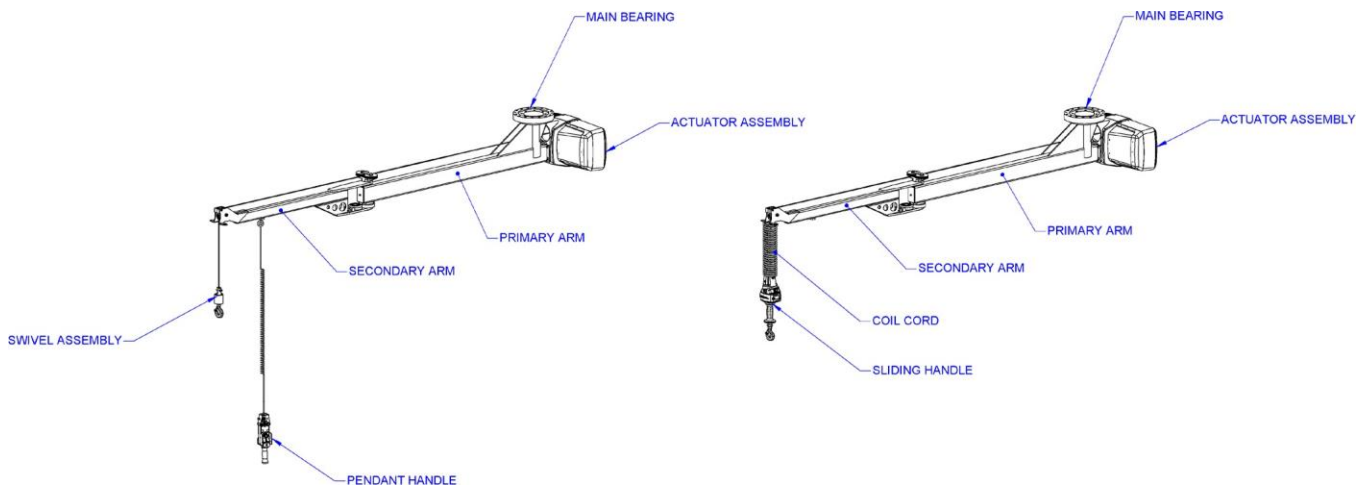


Diagram 1B. Main Under Hung Easy Arm® Components.

STEP 2 - UNPACKING THE EASY ARM®

➡ **TIP:** Packing list can be found in plastic pocket attached to shipping box.

- 2.1 Carefully remove banding straps from the shipping box and remove top (**diagram 2A**).
- 2.2 Remove sleeve from packaging (**diagram 2B**).
- 2.3 Remove packaging supports (**diagram 2C**).
CAUTION: arm assembly must be supported once packaging supports are removed.
- 2.4 Using a proper lifting device, lift the Easy Arm® out of the packaging box using the included eyebolts (**diagrams 2D and 2E**). Do not do this until you are ready to install the system.

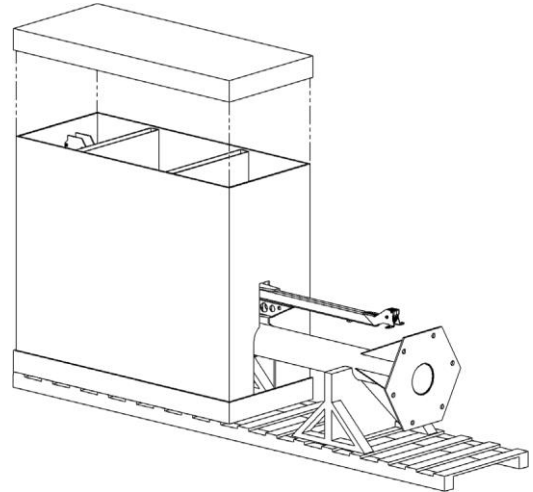


Diagram 2A. Packaging top removal.

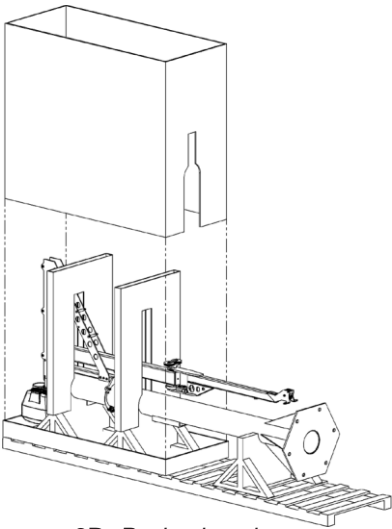


Diagram 2B. Packaging sleeve removal.

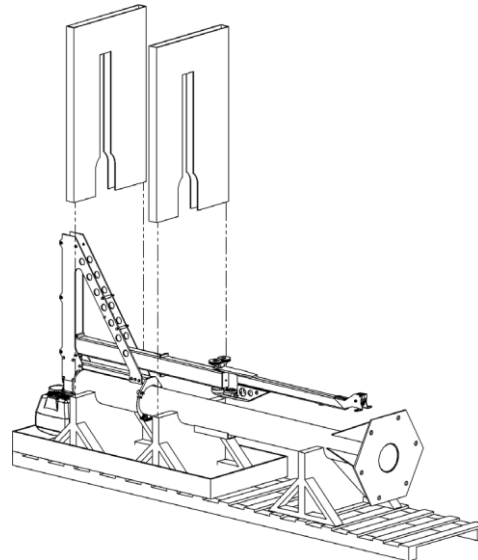


Diagram 2C. Packaging support removal.

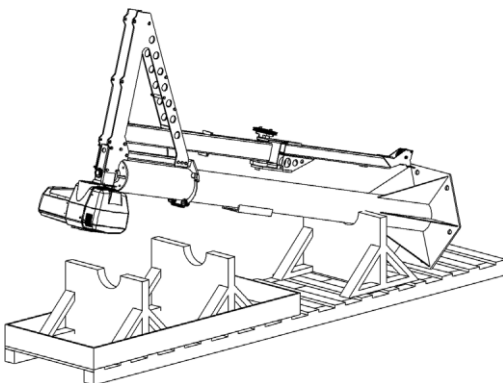


Diagram 2D. Easy Arm® assembly removal from packaging.

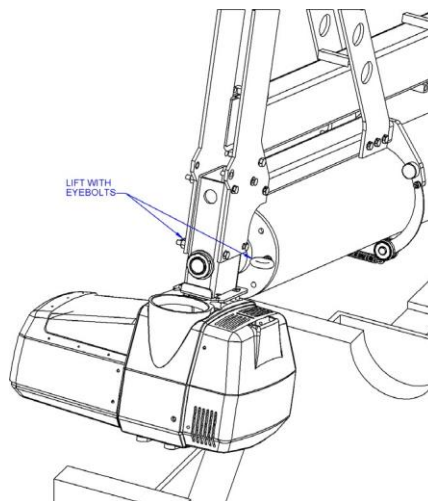


Diagram 2E. Easy Arm® assembly removal from packaging.

STEP 3 - FLOOR MOUNTED SYSTEM (MAST) INSTALLATION

WARNING

Do not proceed if your support structure does not meet the loading requirements determined in **Step 1.4**.

Note: Easy Arm® Crane foundation requirements are based on soil pressure of 2500# per square foot. Concrete pressure recommended for jib crane foundation is 3000# per square inch of compressive force, with no cracks or seams in a square footer width as dimensioned in **chart 1A**, page 4.

Note: Chemical (epoxy) anchor bolts are recommended because of the vibrating loads caused by the impact of the hoist stopping and starting under load.

Note: A minimum 6"-thick reinforced concrete floor is required for 165# and 330# installations.

3.1 INSTALLING ANCHOR BOLTS

WARNING

Units with span and height under hook under 18' use a square baseplate.

3.1.1 165 lb. (75 kg) units:

A) Anchor bolts (by others) for **square** base plates must:

- be 3/4" in diameter.
- be embedded a minimum of 4-1/2" into floor (**diagram 3A**).
- have minimum of two threads above nut after installation.

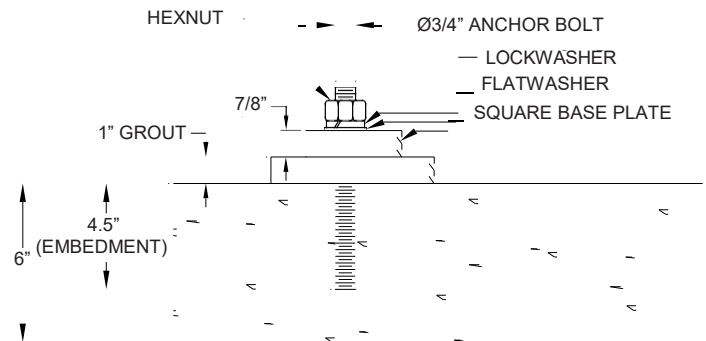


Diagram 3A. Typical square base plate anchor bolt embedment.

B) Anchor bolts (by others) for **hexagonal** base plates must:

- be 3/4" or 1" in diameter.
- be embedded a minimum of 4-1/2" into floor (**diagram 3A**).
- have **minimum** of two threads above nut after installation.

C) Drill holes in concrete floor using pre-drilled holes in base plate of **diagram 3B** or **3C**,

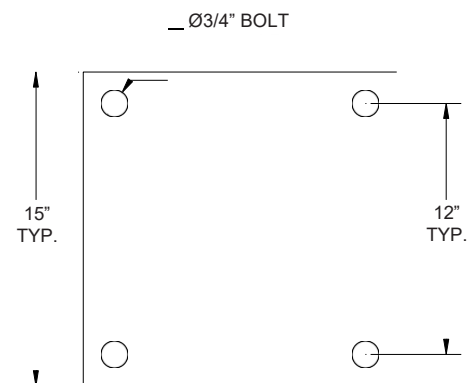


Diagram 3B. Square base plate pattern.

depending on your baseplate configuration, as a guide (use drill bit size recommended by anchor bolt manufacturer).

- D) Install anchor bolts (Grade 5 or better) and hardware (by others) according to manufacturer's installation directions and requirements.
- E) Proceed to Step 3.2, page 10, for mast installation and plumbing.

STEP 3 - FLOOR MOUNTED SYSTEM (MAST) INSTALLATION (CONTINUED)

3.1 INSTALLING ANCHOR BOLTS (CONTINUED)

3.1.2 330 lb. (150 kg) units and 660 lb. (300 kg) units with spans of 10' or less:

A) Anchor bolts (by others) for **hexagonal** base plates must:

- be 1" or 1-1/4" in diameter.
- be embedded a minimum of 4-1/2" into floor.
- have **minimum** of two threads above nut after installation.

B) Drill holes in concrete floor using pre-drilled holes in baseplate of **diagram 3C** or **diagram 3D** as a guide (use drill bit size recommended by anchor bolt manufacturer).

C) Install anchor bolts (Grade 5 or better) and hardware (by others) according to manufacturer's installation directions and requirements.

D) Proceed to Step 3.2, page 10, for mast installation and plumbing.

3.1.3 660 lb. (300 kg) units with spans greater than 10':

A) Pour the footing, according to the footing dimensions in **diagrams 3E** and **3F** with the anchor bolts (J-bolts) in place. There should be between 4" and 6" of anchor bolt exposed above the floor level.

Note: Foundation/concrete must cure 7 days prior to mast installation. Foundation/concrete must cure 28 days prior to using crane to full capacity.

B) Once the concrete has cured, cover the base plate with one (1") inch of grout.

Note: Grout is required to ensure the jib base plate has full contact support to the floor/footing. Shimming/leveling nuts under the base plate are acceptable methods that would aid plumbing of the mast assembly prior to setting the jib mast on the grout bed (shimming/ leveling nuts by others).

Grout must be a non-shrink, high compressive machinery type grout.

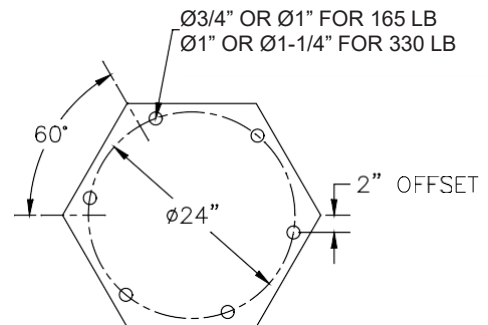


Diagram 3C. 6 bolt base bolt pattern.

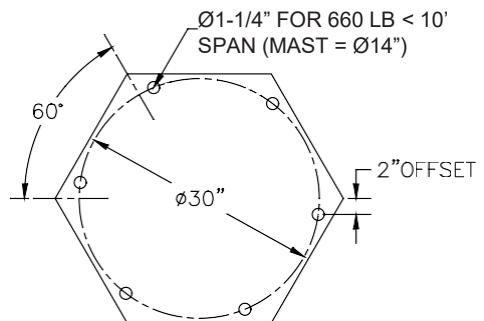


Diagram 3D. 6 bolt base bolt pattern.

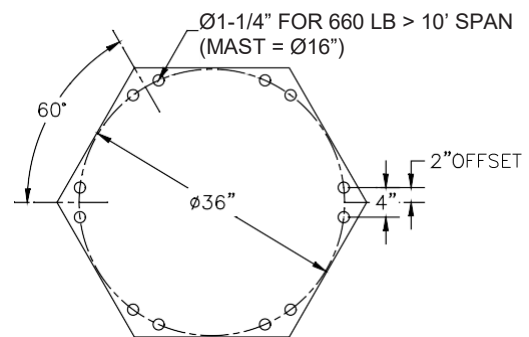


Diagram 3E. 12 bolt base bolt pattern.

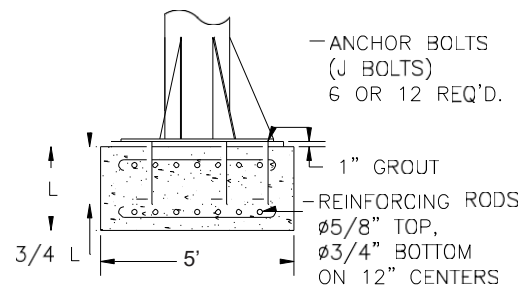


Diagram 3F. 660# Easy Arm base plate foundation.

C) Proceed to Step 3.2, page 10, for mast installation and plumbing.

STEP 3 - FLOOR MOUNTED SYSTEM (MAST) INSTALLATION (CONTINUED)

WARNING

Mast pin must be plumb to prevent arm assembly from drifting.

3.2 INSTALLING AND PLUMBING MAST

- A) Cover entire base-plate area with one inch of non-shrink precision grout. Set mast in place.
- B) Hold a level against the mast (**diagram 3G**).
- C) Pick a starting point and plumb the mast by adjusting the mast at the base-plate. Check the plumb of the mast every 60°.
- D) Once the main pivot pin is plumb **and grout has cured**, tighten bolts until base-plate is completely seated in grout.

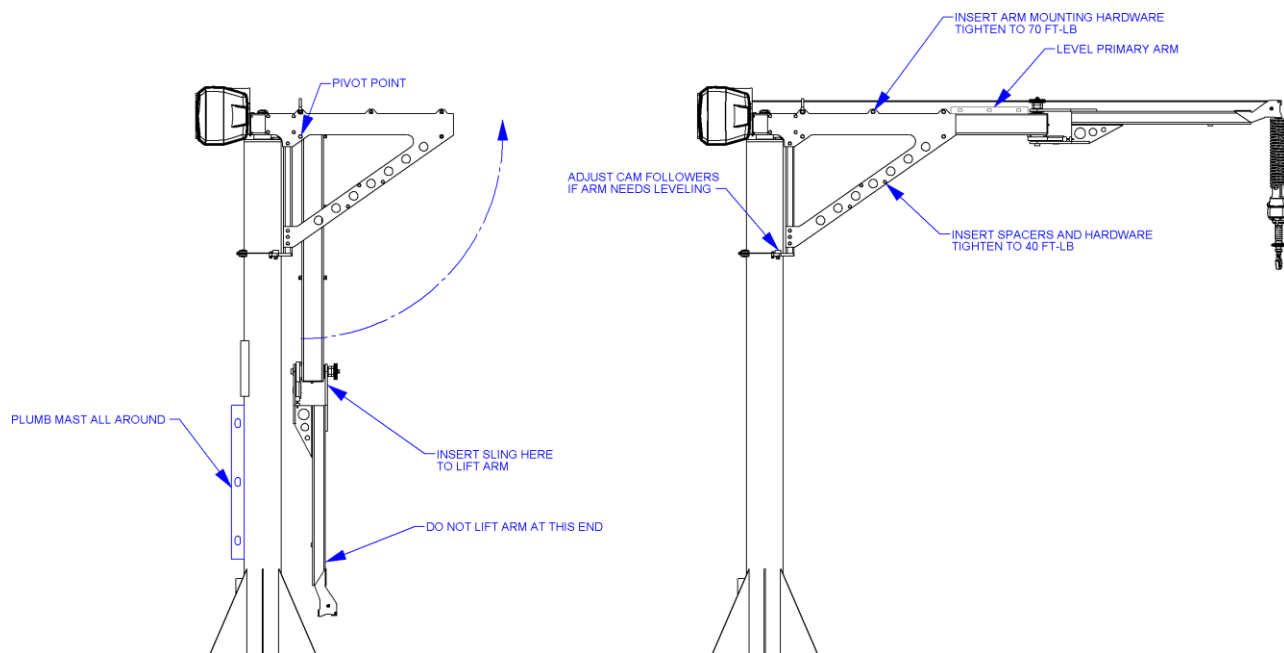


Diagram 3G. Plumbing the mast.

660 LB. EASY ARM ONLY:

- E) Prior to erecting mast, fish electrical cable and air hose (option) through mast and pivot pin (**diagram 3H**).

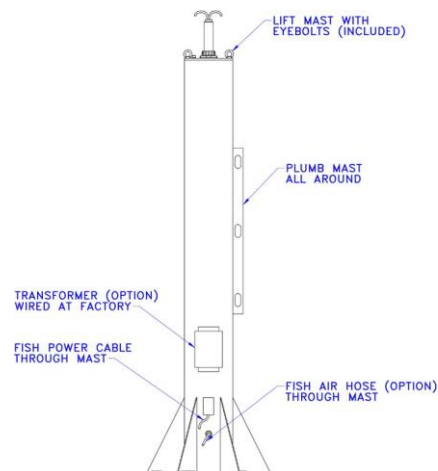


Diagram 3H. 660# Easy Arm mast installation.

STEP 4 - FLOOR MOUNTED ARM ASSEMBLY

➡ **TIP:** Wire rope will be loose to accommodate the shipping of the unit with the arm assembly rotated. **DO NOT** bend or kink the wire rope during assembly. Be careful not to pinch any wires or connectors between the arm assembly and head side plates during installation.

165 LB./330 LB. ARM ASSEMBLY:

4.1.1 Loosen and remove the arm mounting hardware from the head assembly. Using a proper lifting device, rotate the arm assembly up into the horizontal position (**diagram 4A**). Once arm is properly in place, reassemble the arm mounting hardware. **DO NOT** torque down the mounting hardware at this time.

4.1.2 Place a level across the primary arm (**diagram 4B**). Adjust the arm assembly up or down as required, utilizing the eccentric cam followers. To raise the arm, rotate cam followers to increase the gap between the cam follower plate and the mast. To lower the arm assembly, rotate cam followers to decrease the gap between the cam follower plate and the mast.

4.1.3 When the arm assembly has been leveled, torque down the arm assembly mounting hardware.

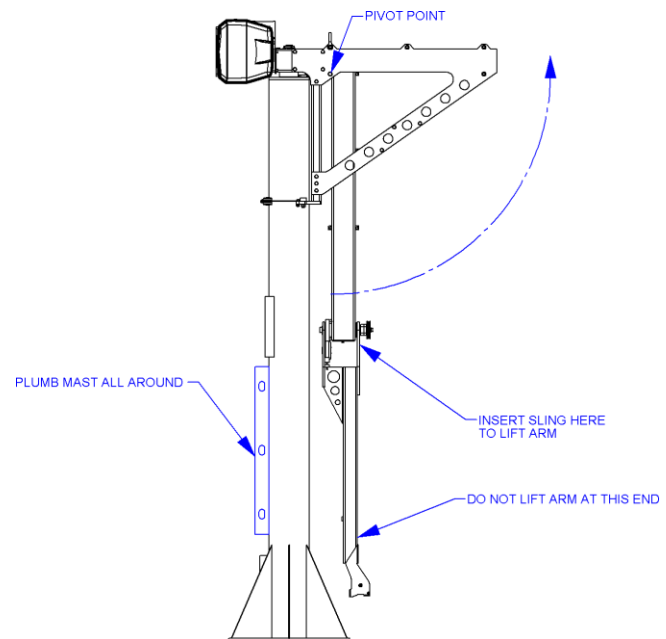


Diagram 4A. Final arm assembly installation.

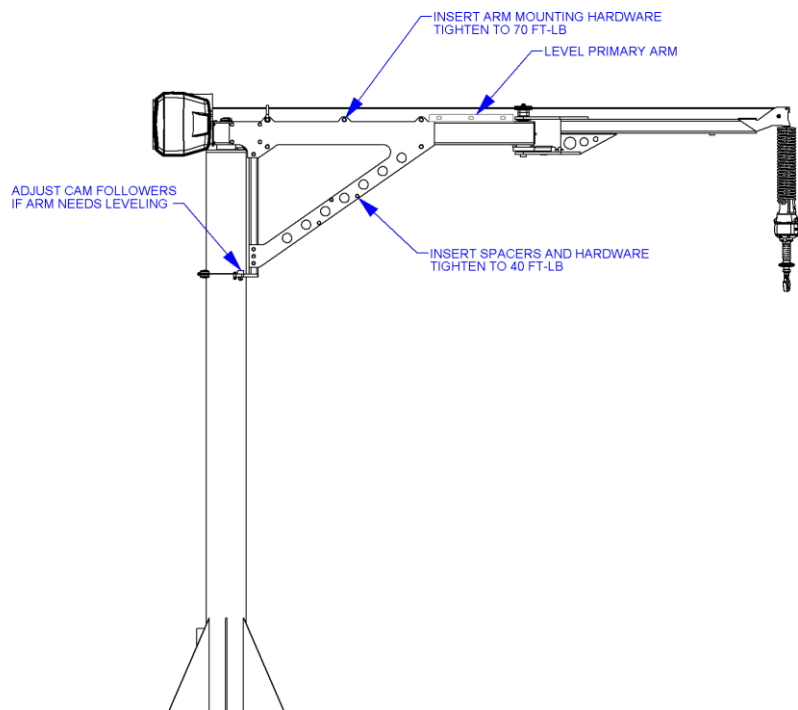


Diagram 4B. Arm assembly-leveling adjustment.

STEP 4 - FLOOR MOUNTED ARM ASSEMBLY (CONTINUED)

➡ **TIP:** Wire rope will be loose to accommodate the shipping of the unit with the arm assembly rotated. **DO NOT** bend or kink the wire rope during assembly. Be careful not to pinch any wires or connectors between the arm assembly and head side plates during installation.

660# ARM ASSEMBLY

4.2.1 Using safe and appropriate means, lift arm assembly by included eyebolts. Ensuring arm is level, lower onto mast while feeding power cord and air hose through arm tube. Align rotation stop bar with pocket in bumper block as arm is lowered (**diagram 4C**).

Note: Take care not to impact threads on mast pin while lowering arm.

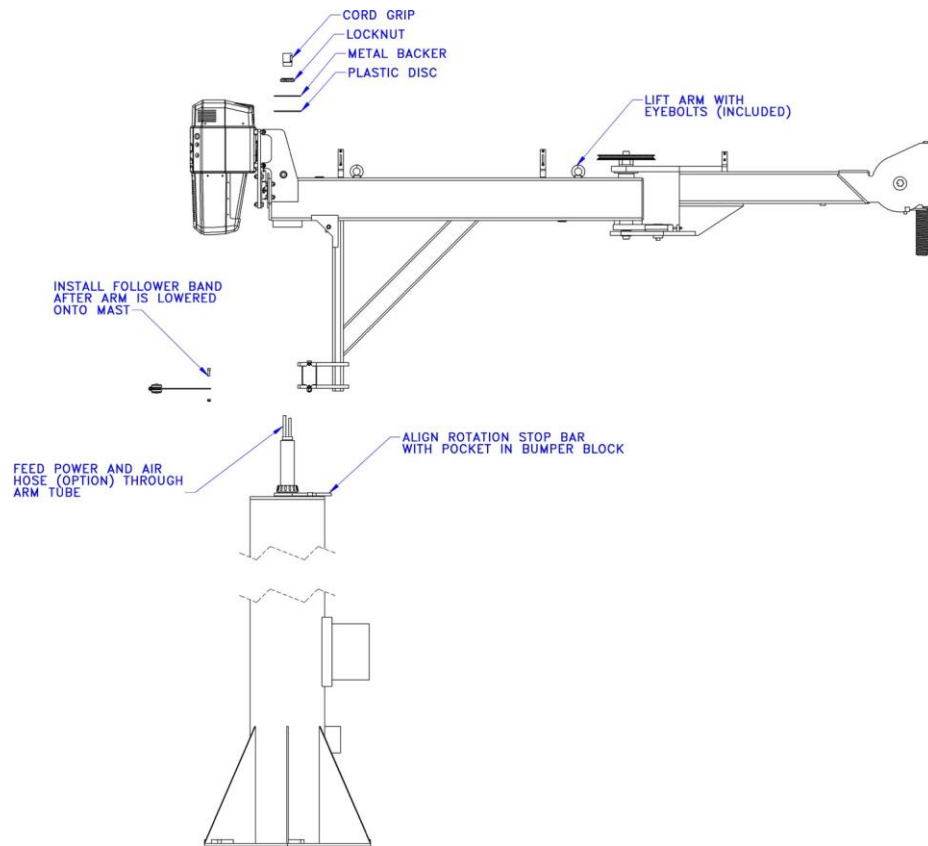


Diagram 4C. Aligning arm with mast.

4.2.2 Feed power cable and air hose through plastic friction disc, backer plate, locknut and cord grip. Tighten locknut until play is removed from friction disc. Install electrical connector, splice air hose, and install retaining clips. Install follower band onto mast behind trunnion rollers (**diagram 4D**).

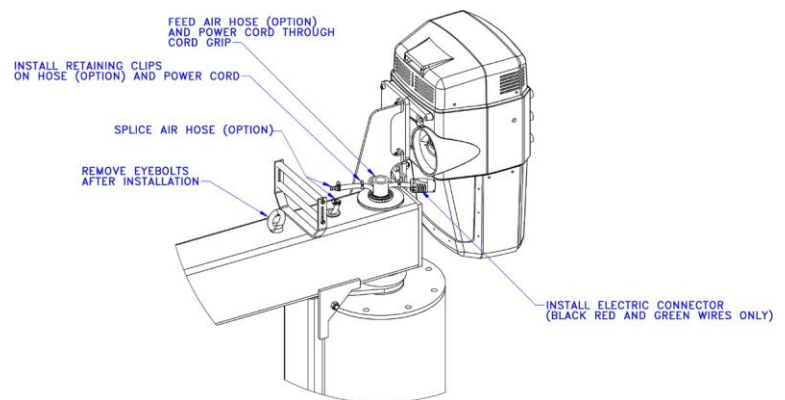


Diagram 4D. Installing electrical connector.

STEP 4 - FLOOR MOUNTED ARM ASSEMBLY (CONTINUED)

➡ **TIP:** Wire rope will be loose to accommodate the shipping of the unit with the arm assembly rotated. **DO NOT** bend or kink the wire rope during assembly. Be careful not to pinch any wires or connectors between the arm assembly and head side plates during installation.

660 LB. ARM ASSEMBLY:

4.2.3 Remove eyebolts from arm. Refer to *diagram 4E* to adjust trunnion rollers until arm is level.

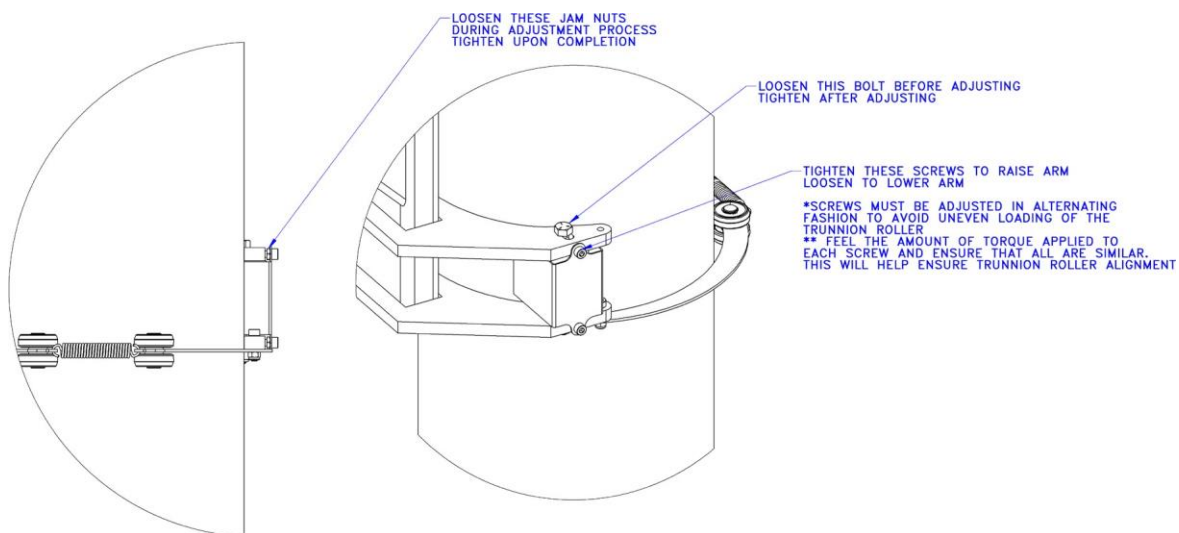


Diagram 4E. *Trunnion roller adjustment.*

STEP 5 - UNDER HUNG SYSTEM INSTALLATION

➡ **TIP:** Wire rope will be loose to accommodate the shipping of the unit. **DO NOT** bend or kink the wire rope during assembly. Be careful not to pinch any wires or connectors.

STOP!

Do not proceed if your support structure does not meet the loading requirements determined in **Step 1.5**.

- 5.1 The primary and secondary arms are wrapped with a cardboard sleeve during shipping. Leave the sleeve in place to prevent relative motion of the arms until after the unit is mounted to the platform.
- 5.2 The crane has a high center of gravity relative to the bottom surfaces of the arms. When lifting the unit from the packaging take precautions to prevent the assembly from rolling on its side.
- 5.3 Raise the unit up to the mounting platform and thread the power supply cable (and optional air hose) through the center hole in the platform (**diagram 5A**). Insert fasteners through the platform and into the tapped holes of the main bearing. Keep the unit supported by crane or fork truck until all fasteners have been properly tightened.
- 5.4 Once the unit is secure, reroute the electrical cables and air hose (if included) along the bottom of the primary arm using the clamps provided. The slack switch cable and coil cord extension should pass through the secondary arm. The optional air hose follows the bottom of the secondary arm.

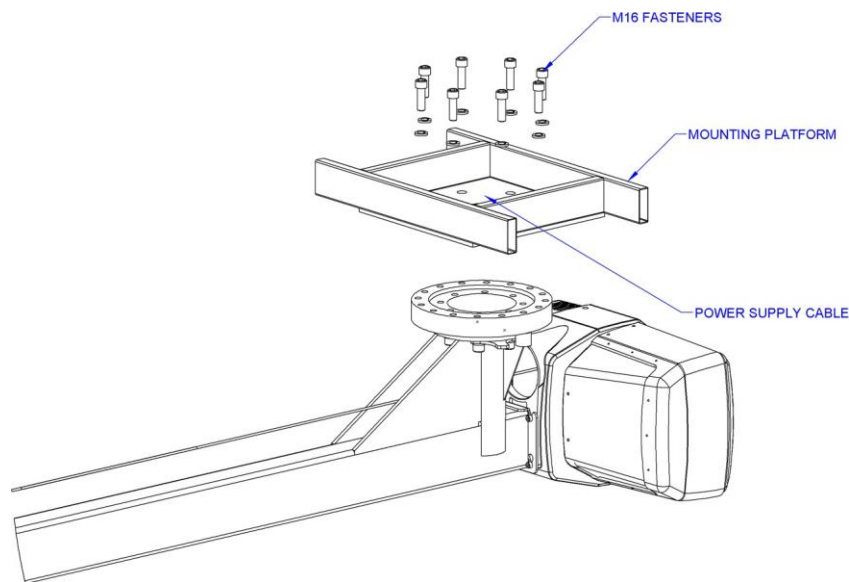


Diagram 5A. Installing Under Hung Easy Arm®.

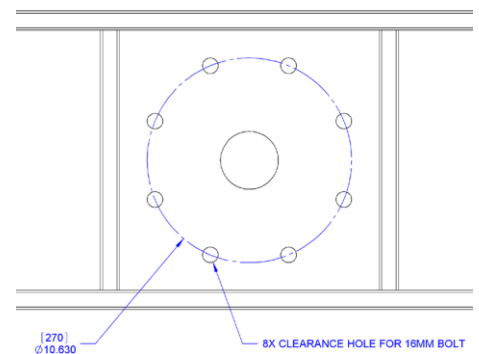


Diagram 5B. Bolt Pattern for Under Hung Easy Arm®.

STEP 6A - IN-LINE SLIDE & IN-LINE FORCE SENSING HANDLE INSTALLATION

- 6A.1** Ensure the wire rope is still fed through the center of the coil cord. Hold the slide handle just below the coil cord.
- 6A.2** Center the coil cord footer between the ears of the slide handle swivel. **Note:** Make sure the fin of the coil cord footer is on the opposite side of the slide handle connector.
- 6A.3** Remove the 16mm shoulder bolt from the coil cord footer and wire rope and allow the coil cord

footer and wire rope to slide down into the slide handle swivel.

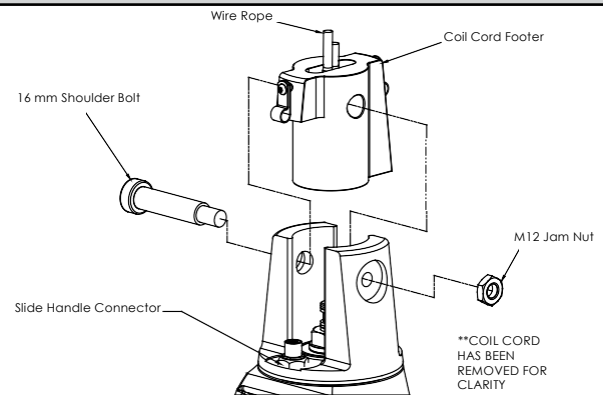


Diagram 6A1. Slide Handle, Shoulder Bolt and Coil Cord

- 6A.4** Once the wire rope, coil cord footer and slide handle swivel are aligned, replace the 16mm shoulder bolt, thereby capturing the wire rope, coil cord footer and slide handle (**diagram 6A1**).
- 6A.5** Thread the coil cord connector into the slide handle connector (**diagram 6A1**).
- 6A.6** Thread the M12 jam nut onto the 16mm shoulder bolt.
- 6A.7** Check that the coils of the coil cord are centered around the wire rope when properly installed.
- 6A.8** **Optional:** Install the hook or tooling through the retaining nut and lock washer. The included flat washer is unnecessary in this application. Use the open pilot hole on the Slide Handle Retaining Nut and a #21 drill bit to drill a hole completely through the threads of the hook and the

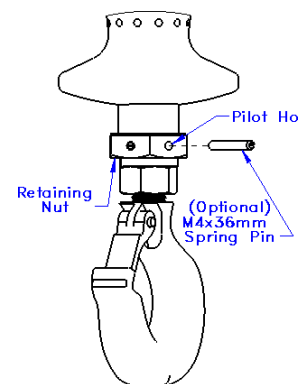


Diagram 6A2. Slide Handle with Optional Pin.

opposite side of the nut. Hammer the included M4x36mm spring into the hole until it is flush with the surface of the nut (**diagram 6A2**).

- 6A.9** Continue to Step 7 on page 21.

STEP 6B - REMOTE MOUNTED SLIDE HANDLE INSTALLATION

- 6B.1** Ensure the wire rope is still fed through the center of the coil cord. Hold the G360™ swivel just below the coil cord assembly.
- 6B.2** Center the coil cord footer between the ears of the G360™ swivel. **Note:** Make sure the fin of the coil cord footer is on the opposite side of the G360™ connector.
- 6B.3** Remove the 16mm shoulder bolt from the coil cord footer and wire rope and allow the coil cord footer and wire rope to slide down into the G360™ swivel.

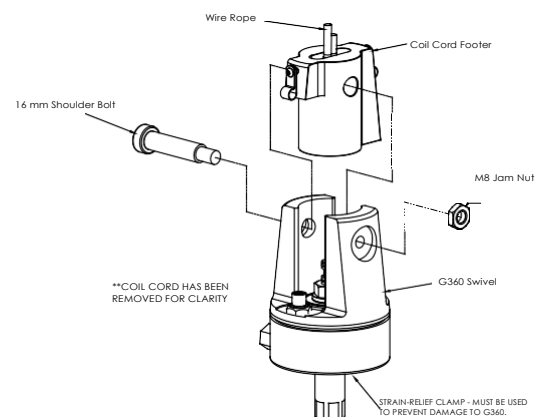


Diagram 6B1. G360™, Shoulder Bolt and Coil Cord.

STEP 6B - REMOTE MOUNTED SLIDE HANDLE INSTALLATION (CONTINUED)

6B.4 Once the wire rope, coil cord footer and G360™ swivel are aligned, replace the 16mm shoulder bolt thereby capturing the wire rope, coil cord footer and G360™ swivel (**diagram 6B1**, page 15).

6B.5 Thread the coil cord connector into the G360™ connector (**diagram 6B1**, page 15).

6B.6 Thread M12 jam nut onto the 16mm shoulder bolt.

6B.7 Check that the coils of the coil cord

are centered around the wire rope when properly installed.

6B.8 A pilot hole is provided for the locking pin. Attach tooling to G360™ utilizing M16 thread. The tool bolt/rod thread should be beyond pilot hole of shaft when fully engaged. Using a #21 drill bit, drill through the tool bolt/rod thread and out the other side of G360™ shaft. Hammer pin into place thereby locking tooling to G360™ (**diagram 6B2**).

6B.9 Assemble the remote mounted slide handle inside the remote mount bracket using the hardware provided (**diagram 6B3**).

Note: This step is best completed on a workbench prior to mounting handle to tooling.

WARNING

Remote mounted G-Force® handles must be mounted at both the top and bottom of the handle assembly. Failure to mount the remote mounted handle at top and bottom can result in poor performance and/or premature component failure.

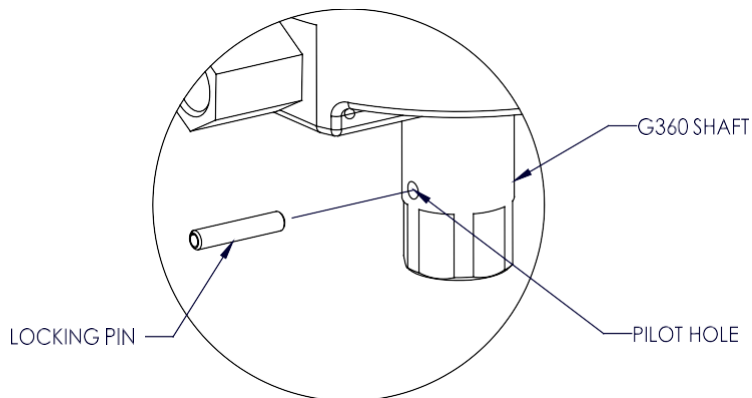


Diagram 6B2. Tooling Installation.

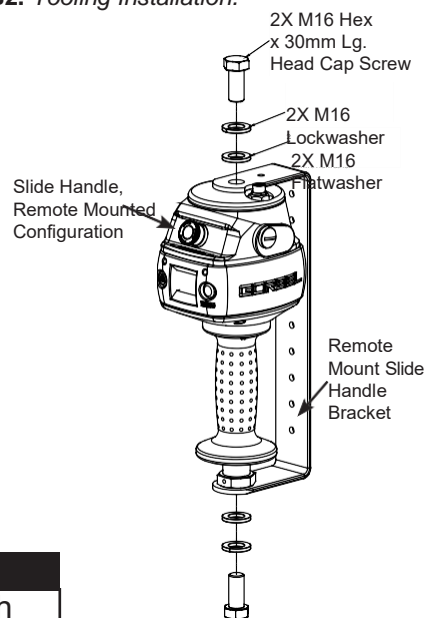


Diagram 6B3. Remote Mounted Slide Handle, Exploded View

6B.10 Attach the remote mounted handle with bracket to the tooling.

Assure that the mounting arrangement does not affect the operating function of the slide handle.

6B.11 Connect the extension cable from the G360™ to the remote mounted slide handle. Securely clamp the remote mount coil cord extension cable to the tooling as needed.

CAUTION

All cables used in a remote mounted handle configuration must be properly clamped and/or strain-relieved to prevent premature failure of the Easy Arm® or customer tooling.

CAUTION

Take care to avoid looping excess cable at locations where the loop could catch on foreign objects.

6B.12 Continue to Step 7 on page 21.

STEP 6C - SUSPENDED PENDANT HANDLE INSTALLATION

- 6C.1** Assure that the coils of the pendant handle coil cord are centered around the pendant handle wire rope.
- 6C.2** Remove the eyebolt from suspended pendant cable assembly using the threaded connector.
- 6C.3** Thread the eyebolt into the bottom of the actuator assembly as shown (**diagram 6C1**).
- 6C.4** Reattach the suspended pendant cable assembly to the eyebolt via the threaded connector.
- 6C.5** Adjust the suspended pendant cable assembly so that there is a service loop in the wiring cable and there is no tension in the wire cable.
- 6C.6** Thread the cable assembly connector into the actuator connector (**diagram 6C1**).

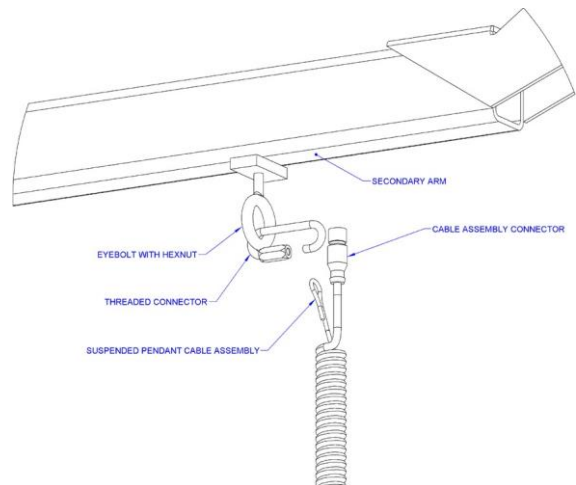


Diagram 6C1. Assembly of Suspended Pendant Cable Assembly to Bottom of Actuator Assembly.

- 6C.7** Remove the cotter pin and clevis from the wire rope swivel assembly.
- 6C.8** **Optional:** Install the hook or tooling with the washer, lock washer and nut in the orientation shown (**diagram 6C2**) then use the pilot hole and a #21 drill bit to drill through the hook threads, a minimum of 36mm deep. Use a hammer to insert the M4x36mm spring pin into the hole until it is flush with the surface of the swivel assembly (**diagram 6C3**).
- 6C.8** Reinsert the clevis and cotter pin capturing the wire rope thimble in the swivel assembly (**diagram 6C3**).
- 6C.9** Continue to Step 7 on page 21.

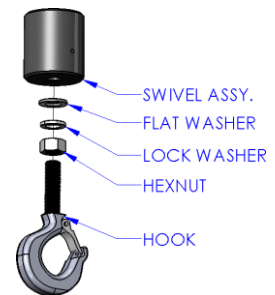


Diagram 6C2. Hook installation.

Note: On suspended pendant equipped systems, the wire rope swivel assembly must be installed before AC power is applied to the system or a limit switch error will occur (501 / 11000) error codes). To clear this fault you will have to (must be done in this order):

1. Install wire rope swivel assembly or other weighted device on wire rope.
2. Disconnect AC power from the system (using the e-stop will not work).
3. Reconnect the AC power and wait approximately one minute for system to power on completely.

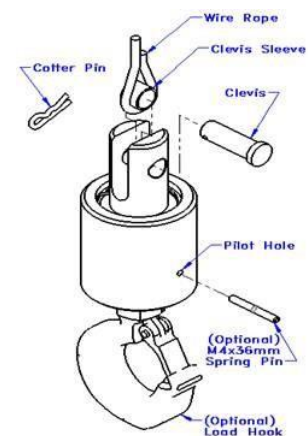


Diagram 6C3. Cotter Pin, Clevis, Wire Rope Swivel Assembly and Wire Rope Thimble.

STEP 6D - REMOTE MOUNTED PENDANT HANDLE INSTALLATION

- 6D.1** Ensure the wire rope is still fed through the center of the coil cord. Hold the G360™ swivel just below the coil cord.
- 6D.2** Center the coil cord footer between the ears of the G360™ swivel. **Note:** Make sure the fin of the coil cord footer is on the opposite side of the G360™ connector.
- 6D.3** Remove the 16mm shoulder bolt from the coil cord footer and wire rope and allow the coil cord footer and wire rope to slide down into the G360™ swivel.

STEP 6D - REMOTE MOUNTED PENDANT HANDLE INSTALLATION (CONTINUED)

6D.4 Once the wire rope, coil cord footer and G360™ swivel are aligned, replace the 16mm shoulder bolt thereby capturing the wire rope, coil cord footer and G360™ swivel (**diagram 6D1**).

6D.5 Thread the coil cord connector into the G360™ connector (**diagram 6D1**).

6D.6 Thread the M12 jam nut onto the 16mm shoulder bolt.

6D.7 Check that the coils of the coil cord are centered around the wire rope when properly installed.

6D.8 A pilot hole is provided for the locking pin. Attach tooling to G360™ utilizing M16 thread. The tool bolt/rod thread should be

beyond pilot hole of shaft when fully engaged. Using a #21 drill bit, drill through the tool bolt/rod thread and out the other side of G360™ shaft. Hammer pin into place thereby locking tooling to G360™ (**diagram 6D2**).

6D.9 Attach the pendant handle bracket directly to the tooling. Assume that the mounting arrangement does not affect the operating function of the pendant handle. **Note:** If necessary, a collar clamp mounting bracket option can be used to attach the pendant handle to the tooling (**diagram 6D3**).

6D.10 Connect the extension cable from the G360™ to the remote mounted pendant handle. Securely clamp the remote mount coil cord extension cable to the tooling as needed.

CAUTION

All cables used in a remote mounted handle configuration must be properly clamped and/or strain-relieved to prevent premature failure of the Easy Arm® or customer tooling.

CAUTION

Take care to avoid looping excess cable at locations where the loop could catch on foreign objects.

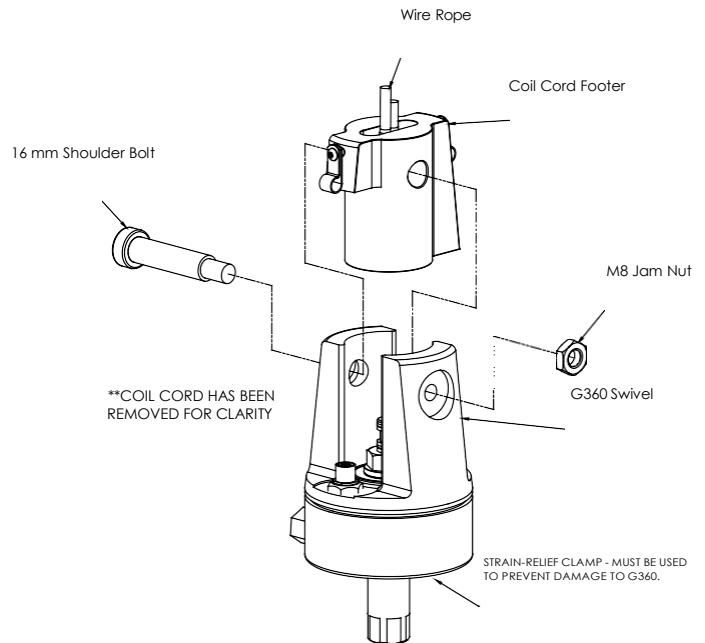


Diagram 6D1. G360™, Shoulder Bolt and Coil Cord.

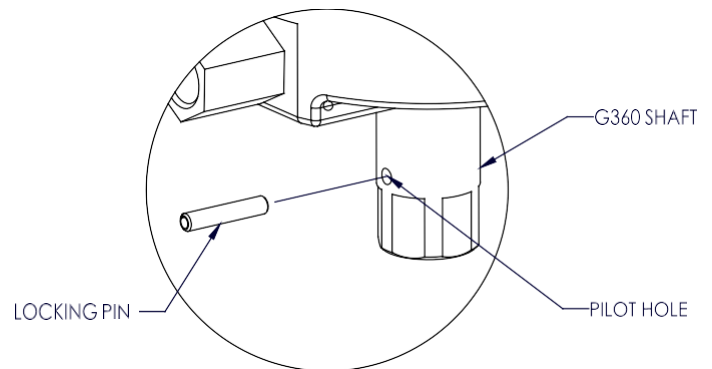


Diagram 6D2. Tooling Installation.

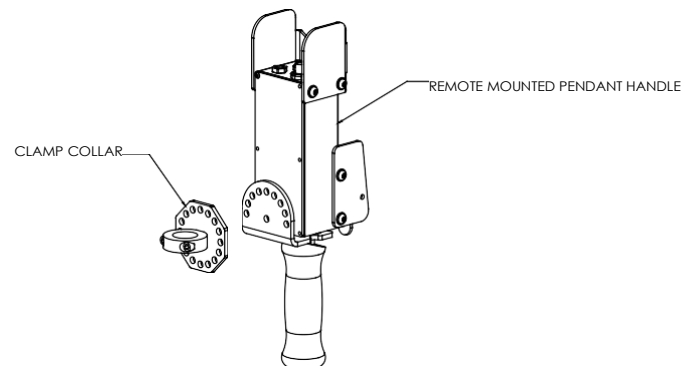


Diagram 6D3. Remote Mounted Pendant Handle with Collar Clamp Mounting Bracket (Option).

6D.11 Continue to Step 7 on page 21.

STEP 6E - REMOTE MOUNT FORCE SENSING SLIDE HANDLE INSTALLATION

- 6E.1** Follow Steps 6B.1 through 6B.7 on pages 15 and 16 to install G360™.
- 6E.2** Bracket (by others) must be sized to fit the handle it will be holding and rigid enough to resist the forces exerted on it (**diagram 6E1**).
- 6E.3** Using the included M16 hardware, fasten both ends of the handle to the bracket. Attach bracket to tooling if necessary.
- 6E.4** Connect cable from G360™ to handle top. Clamp the cable to tooling to prevent it from being snagged.
- 6E.5** Continue to Step 7 on page 21.

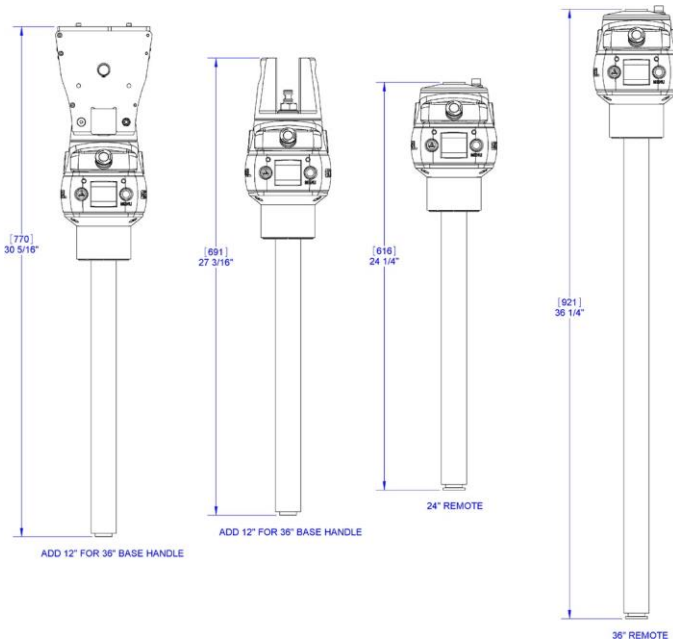


Diagram 6E1. Force Sensing Slide Handle bracket sizes.

Sensing Handle and one traditional handle is a supported configuration.

Note: Due to the nature of the Force Sensing Slide Handle, excessive twisting of the grip may be interpreted as intended motion. For best results, only push and pull the handle grip while avoiding twisting (**diagram 6E3**).

Note: To avoid damaging the handle, do not apply more than 200 lbs (90 kg) to the grip or handlebars.

Note: Remote handles must be mounted rigidly in order to function

correctly. For Slide handles, the mounting holes on the tooling must be aligned to avoid any binding of the handle and the bolts at each end of the handle must be tightened enough to prevent motion but not induce bending. The included rubber washers must be mounted between the handle and tooling to prevent binding. Additionally the handle must be captured via the hole in the top cap to prevent rotation (see **diagram 6E2** for suggested bracket dimensions). For Hub handles, the back of the handle body must be securely fastened to the tooling.

Note: Do not attach anything to the grip of the Slide Force Sensing Handle as performance will be degraded.

Note: Changing the orientation of the handle (tilting) while the system is live may be interpreted as intent to move. It is recommended that the handle remains vertical at all times during use.

Note: When taring the handle, care must be taken not to apply force to the grip or handlebars as subsequently removing the force will be interpreted as intent to move. For optimal performance, re-taring the handle periodically may be necessary. The interval will depend on usage.

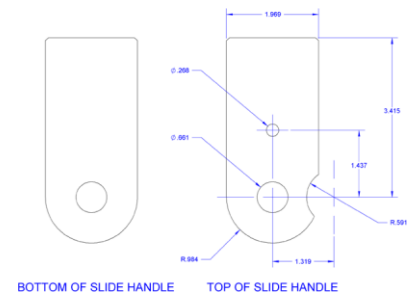


Diagram 6E2. Remote handle mounting dimensions.

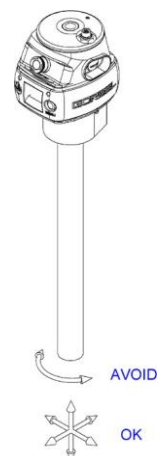


Diagram 6E3. Proper use of Force Sensing Handle grip.

STEP 6F - REMOTE MOUNT FORCE SENSING HUB HANDLE INSTALLATION

WARNING

This handle is only intended for remote mount applications and must not be used for transmitting lifting loads.

6F.1 Follow Steps 6B.1 through 6B.7 on pages 15 and 16 to install G360™.

6F.2 Mount Hub body to tooling rigidly to resist forces exerted on it. Optional mounting plate 74136 is available. See **diagram 6F1** for dimensions for mounting directly to tooling.

6F.3 Attach handlebars to Hub. Handlebar kit

(74630) is available or handlebars may be fabricated (by others). Optional handlebar mounting plate 74138 (with clamp collars) or 74141 (plain for modification by integrator) are available. See **diagram 6F2** for dimensions for fabricating a custom solution.

6F.4 Connect cable from G360™ to handle top. Clamp the cable to tooling to prevent it from being snagged.

6F.5 Continue to Step 7 on page 19.

Note: The system cannot support two Force Sensing Handles running simultaneously on one G-Force®. If dual handles are required, one Force Sensing Handle and one traditional handle is a supported configuration.

Note: Handlebars and attachments for Remote Force Sensing Hub Handles must not exceed 25 lb (11.3 kg). For optimal performance, handlebar assemblies should be as light as possible. Handlebar weight in excess of 10 lbs (4.5 kg) will detract from net capacity of the G-Force®.

Note: For optimal performance and to reduce the risk of damaging the handle, handlebars on Remote Force Sensing Hub Handles should not exceed 24" (0.6m) (12" or 0.3m in either direction) in width or 24" (0.6m) from the face of the handlebar mounting plate (**diagram 6F3**).

Note: To avoid damaging the handle, do not apply more than 200 lbs (90 kg) to the grip or handlebars.

Note: Remote handles must be mounted rigidly in order to function correctly. For Slide handles, the mounting holes on the tooling must be aligned to avoid any binding of the handle and the bolts at each end of the handle must be tightened enough to prevent motion but not induce bending. The included rubber washers must be mounted between the handle and tooling to prevent binding. Additionally, the handle must be captured via the hole in the top cap to prevent rotation (see **diagram 6E2**, page 19, for suggested bracket dimensions). For Hub handles, the back of the handle body must be securely fastened to the tooling.

Note: When taring the handle, care must be taken not to apply force to the grip or handlebars as subsequently removing the force will be interpreted as intent to move. .

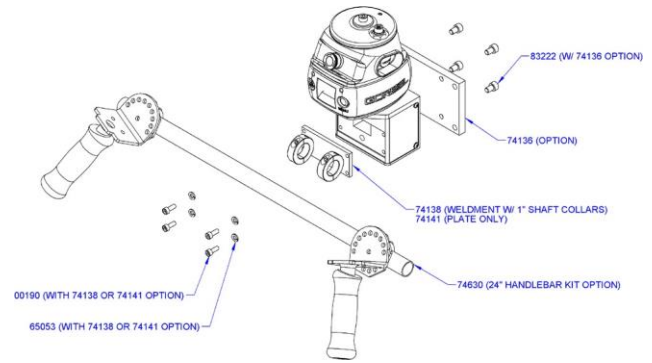


Diagram 6F1. Mounting handlebar and mounting plate.

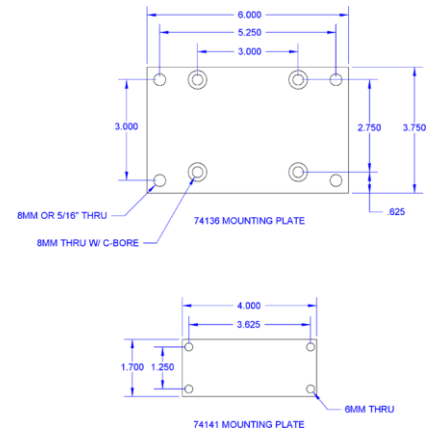


Diagram 6F2. Mounting plate dimensions.

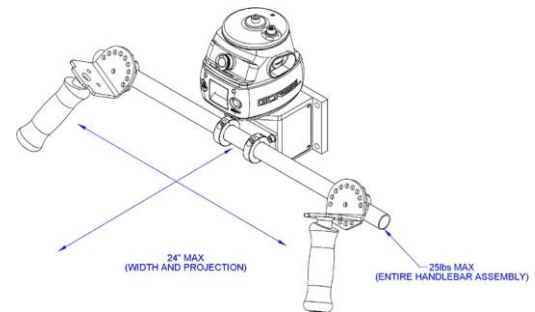


Diagram 6F3. Handlebar dimensions.

STEP 7 - ELECTRICAL POWER CONNECTION

➡ **TIP:** Do not connect to main power until all assembly is complete.

STANDARD:

- 7.1 Prior to final wiring, inspect the entire system to assure that all connections are seated and strain relieved properly, and are without kinks or bends. Verify the following connections:
- a) Coil cord to handle or G360™ collector
 - b) Coil cord to coil cord extension (located internal of the secondary arm tube)
 - c) Coil cord extension to actuator assembly
 - d) Slack switch connection at slack switch
 - e) Slack switch connection at actuator assembly
 - f) Power to actuator assembly
- 7.2 Connect a 220 VAC single-phase power source through a disconnect switch (by others) to the junction box on the mast.

WARNING

If your system displays drive faults 7219 and 4005 either when it powers on or when you attempt to lift or lower a load it means the AC power is too low. Even though the specification is 220 VAC +/- 10%, the power available at the system may be very close to the low end of the specification because of its proximity to the power source. The closer to the nominal 220 VAC you are supplying to the system the less likely you'll experience any problems related to the AC voltage.

TRANSFORMER (OPTIONAL):

110 VAC (Step Up - Standard Option)

- 7.3 System will be supplied with a transformer mounted directly to the mast and a 10' long input power cord pre-wired to the secondary side of the transformer. Connect a 110 VAC single-phase power source through a disconnect switch (by others) to the power cord.

460 VAC (Step Down - Non-Standard Option)

- 7.4 Customer must wire primary power directly to the transformer.

STEP 8 - INITIAL POWER-UP

➡ **TIP:** Do not depress the operator present switch on the sliding handle during startup.

- 8.1 Turn on the disconnect switch (by others) to apply power to the Easy Arm®. When power is detected, "POWER ON" is displayed on the OLED.
- 8.2 Disengage the emergency stop (E-StOP ENGAGED) button located on the face of the handle.
- 8.3 During the system power up the OLED at the handle will display "G-FORCE INITIALIZING". If you are using a Force Sensing Handle, after power is applied to the system and the unit has booted, fault 11009 will usually be displayed indicating that the handle needs to be tared. See page 37 for taring procedure.
- 8.4 Once the system is on-line and ready, "G-FORCE READY TO LIFT" will be displayed on the OLED.

STEP 8 - INITIAL POWER-UP (CONTINUED)

- 8.5
- **Standard Operation - Slide Handle Configuration:** Grasp the handle grip to run the unit up and down. Do this several times to get a feel for the unit. The OLED displays RUN MODE HANDLE.
 - **Standard Operation - Pendant Handle Configuration:** Depress the up and down levers to run the unit up and down. Do this several times to get a feel for the unit. The OLED displays RUN MODE PENDANT.

See the Lift Functionality section on page 29 for complete details on handle operation.

➡ **TIP:** The operator should always keep their hand under the operator present sensor on the slide handle while operating the unit in standard mode. If the hand is frequently moved away from the operator present sensor it will result in jerky movement from the unit.

- 8.6 After proper lift operation has been verified, test the rotation of the arms about their pivot points. Begin with the primary arm pivot. Using the handle, rotate the arm assembly and note the feel of the rotation of the primary arm. If the arm is too loose, tighten the friction brake located on the top of the mast. This is done by tightening the bearing locknut. If the arm is too difficult to rotate, loosen the friction brake by loosening the bearing locknut. Repeat this procedure until you are satisfied with the rotation of the primary arm.

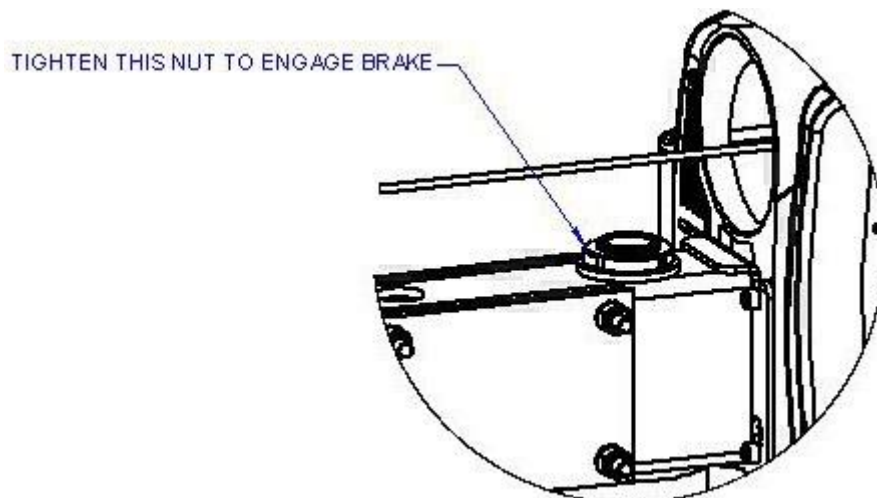


Diagram 8A. Primary arm friction brake adjustment.

STEP 8 - INITIAL POWER-UP (CONTINUED)

- 8.7** Using the handle, rotate the arm assembly and note the feel of the rotation of the secondary arm. If the arm is too loose, tighten the friction brake located on the pivot block at the knuckle end of the arm assembly. This is done by loosening the jam nut and tightening down the setscrew with a clockwise rotation. If the arm is too difficult to rotate, loosen the friction brake. Loosen the jam nut and back the setscrew off by rotating it counter-clockwise. Repeat this procedure until you are satisfied with the rotation of the secondary arm.

TIGHTEN THESE SCREWS TO ENGAGE BRAKE

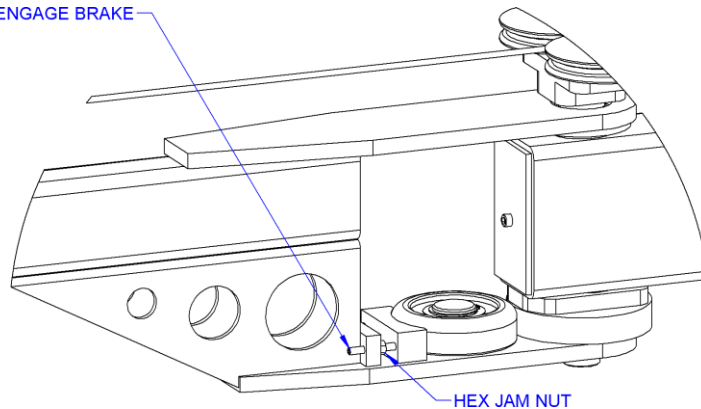


Diagram 8B. Secondary arm friction brake adjustment.

- 8.8** With both the primary and secondary arms adjusted, rotate the crane through its full range of travel and take note of any interference. Determine the desired range of the Easy Arm® and set the rotation stop bolt to limit continuous rotation.

MOVE THIS BOLT TO ANOTHER HOLE ON MAST TOP PLATE TO CHANGE ROTATION STOP POSITION

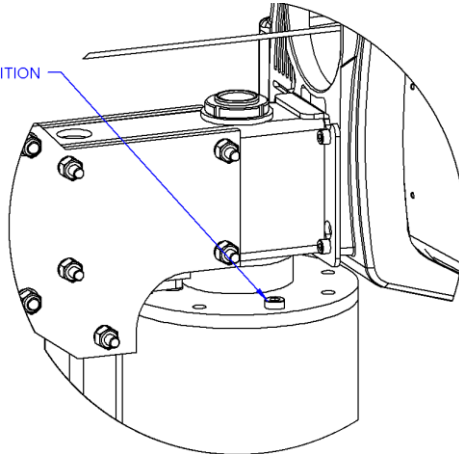


Diagram 8C. Floor mounted arm assembly rotation stop installation.

ROTATION STOP PLATE

ROTATION STOP SLEEVE

M16 HARDWARE

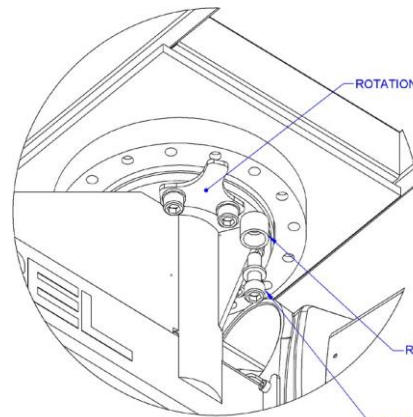


Diagram 8D. Under Hung arm assembly rotation stop installation.

WARNING

Failure to properly set the rotation stop bolt to limit primary arm rotation to 375° will result in excessive twisting of the main power cord into the actuator assembly and will result in reduced life of the cable.

- 8.9** Finally, test the operation of any special tooling that may have been integrated to the Easy Arm® unit.

WARNING

Gorbel, Inc. does not provide integrated tooling for the Easy Arm®. All tooling related questions should be directed to the tooling manufacturer or supplier.

STEP 9 - AIR CONNECTION (OPTION)

➡ **TIP:** Do not connect to air power until all assembly is complete.

- 9.1 Verify the connection between the air hose and the nycoil air hose in the coil cord.
- 9.2 Verify that the air hose is clamped properly to the arm assembly and that there are no kinks in the hose.
- 9.3 For Floor Mounted units, connect air source to the airline input located at the base of the mast assembly. The standard input airline requires a 1/2" NPT female connector.

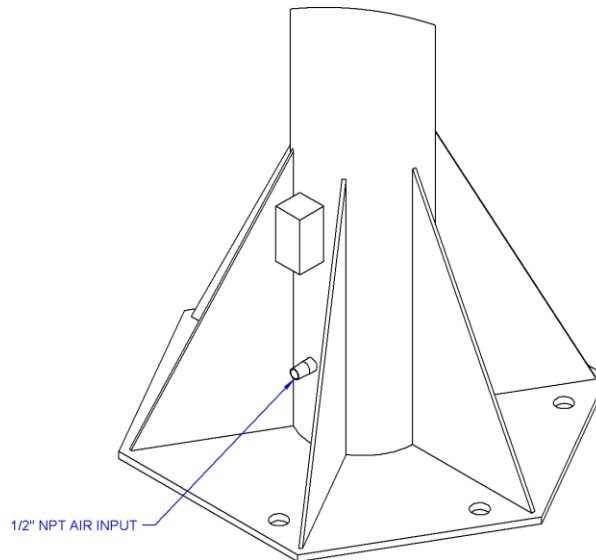


Diagram 9A. Airline inlet.

- 9.4 For Under Hung units, verify that there is a proper loop in the air hose at the knuckle pivot joint of the arm assembly. If the loop does not exist, the air hose will prevent the arm from rotating freely.

660 LB. EASY ARM ONLY:

- 9.5 Air hose terminates via a barbed air fitting with 1/2" NPT female thread through a grommet in the mast. Interface with shop air necessary.

STEP 10 - FLOOR MOUNTED PORTABLE BASE INSTALLATION (OPTION)

- 10.1 Fill portable base with concrete (by others) that meets or exceeds 3000psi of compressive force.
- 10.2 Follow the mast installation instructions (a) through (h) from **Step 3.2** to mount the mast to the portable baseplate.
- 10.3 Adjust the portable base as required using the four (4) adjustable legs located in each corner.

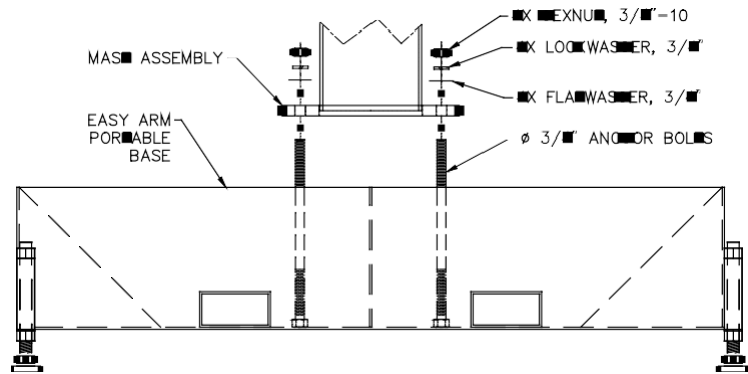


Diagram 10A. Column to portable base assembly.

Note: Portable base shown in diagram is for 165 lb. (75 kg) Easy Arm® with square baseplate. Hex baseplate for 165 lb. (75 kg) Easy Arm® uses (6) 3/4" anchor bolts and 330 lb. (150 kg) Easy Arm® uses (6) 1" anchor bolts.

STEP 11 - UNDER HUNG COLLECTOR (OPTION)

- 11.1 After the crane has been attached to the mounting platform, remove four of the M16 mounting screws and lockwashers as shown in **diagram 11A** to make room for the collector mounting bracket. Make sure the crane is firmly attached by the remaining four screws.
- 11.2 Do not tighten the 5/16 nuts holding the collector to the bracket. The collector unit should be free to rotate a small amount relative to the collector bracket. Position the assembly over the collector shaft. Locate the assembly so that the electrical conduit entrance of the

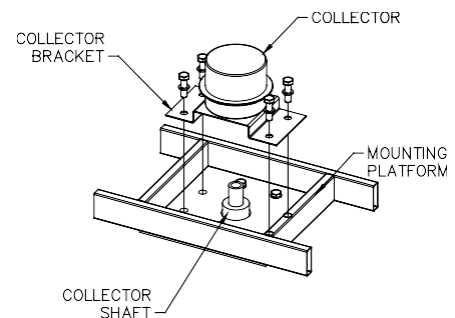


Diagram 11A. Collector Assembly.

collector is in a suitable position. Slide the collector over the collector shaft and push down so that the collector bracket sits firmly on the mounting platform.

➡ **TIP:** If the collector is not free to rotate, loosen the locknuts on the bottom of the assembly until some movement is possible.

- 11.3 Replace and tighten the four M16 mounting screws and lockwashers.
- 11.4 On the lower half of the collector there is a setscrew access port. Remove the plastic port cover and tighten the two setscrews within the assembly. This will enable the collector shaft to drive the inner portion of the collector unit. You will need to rotate the crane to locate each of the two setscrews. Replace the setscrew access port cover.

STEP 12 - FLOAT MODE

- 12.1** Float Mode may be activated by simply pressing the G-Force® logo button on the left-hand side of the handle (**diagram 12A**). Below is a simple exercise to practice if you are not familiar with the Float feature. (This exercise assumes an in-line slide handle is being used).

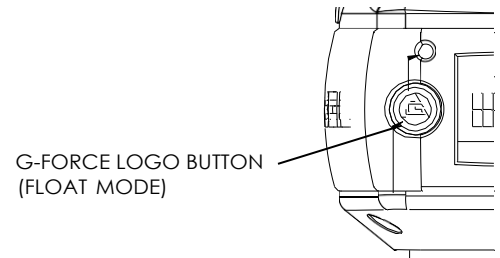


Diagram 12A. Float Mode Button - Slide Handle.

- A) Grasp the handle grip and lift an object weighing at least 20 lbs. (9 kg) to a comfortable height in front of you.
- B) Let go of the handle grip.
- C) Press the G-Force® logo button on the handle. **Note:** Do not hold onto the load. Applying an upward or downward force on the handle or load while initiating Float Mode will give the unit a false reading and cause excessive drift.
- D) After Float Mode is initialized, the LED light will turn on and the handle with payload should not be moving. The OLED will display RUN MODE FLOAT.
- E) Now grasp the load.
- F) To move the load down, put vertical pressure on the load downward, towards the floor. To move the load up, lift up on the load, towards the ceiling. **Note:** The direction and speed of travel is now being controlled by the amount of force that the operator exerts directly onto the load. The higher the force exerted on the load, the faster the unit moves. **Note:** An over-speed detection routine checks if Float Mode reaches 90% of the maximum fully loaded lifting speed and shuts the unit down. It safely limits the maximum speed of travel in Float Mode.

CAUTION

Actuating the operator present switch while in Float Mode will cause the unit to exit Float Mode.

- G) Run the unit up and down several times (at least 20 times in each direction) to assure proper operation. Float Mode should provide a smooth feel.
- H) Repeat this exercise until you become comfortable with Float Mode.

WARNING

NEVER remove the load from the G-Force® while still in Float Mode. The control system will interpret the removal of the load as operator intent to lift the load. Therefore, the unit will begin to drift up. The speed of the unit drift directly correlates to the weight that was removed from the unit. The heavier the weight, the faster the unit will travel.

WARNING

In Float Mode, the live load weight CANNOT be increased or decreased because this will cause unwanted motion. Float Mode must be reinitiated each time the weight of the live load is changed.

WARNING

If external forces are applied to the load while Float Mode is being initiated, the G-Force® will calculate a baseline weight that is higher or lower than the actual weight being lifted. When the external force is removed, the load will begin to drift in the opposite direction of the load that was applied.

STEP 13 - FINAL STEPS

13.1 The speed, acceleration, and other features of the Easy Arm® can be adjusted using the Program Menu available at the handle. ***See the Program Mode section on page 33 for complete details on modifying and programming features. See page 60 for mechanical adjustment should the need arise due to tooling changes, wear, etc.***

13.2 Please contact the Gorbel® factory (585-924-6262) if any of the following occur.
DO NOT ATTEMPT TO REPAIR UNIT YOURSELF.

- Excessive noise
- Unexpected operation
- Change in performance
- Damage or excessive wear to unit components
- Questions about the unit arise

Please do not be limited by these items only.

13.3 Keep Packing List, Installation & Operation Manual, Drawings, and any other inserts filed together in a safe place for future reference.

STEP 14 - EXPANSION I/O BLOCK MOUNTING INSTRUCTIONS (OPTION)

➡ **TIP:** Expansion I/O block mounting instructions only apply to iQ2 units with an I/O block.

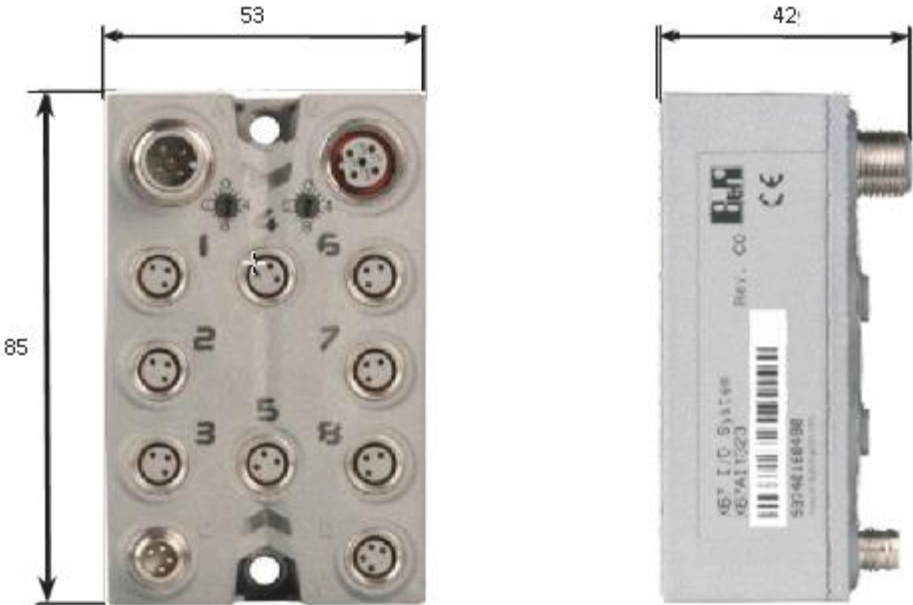


Diagram 14A. Expansion I/O block dimensions (millimeters).

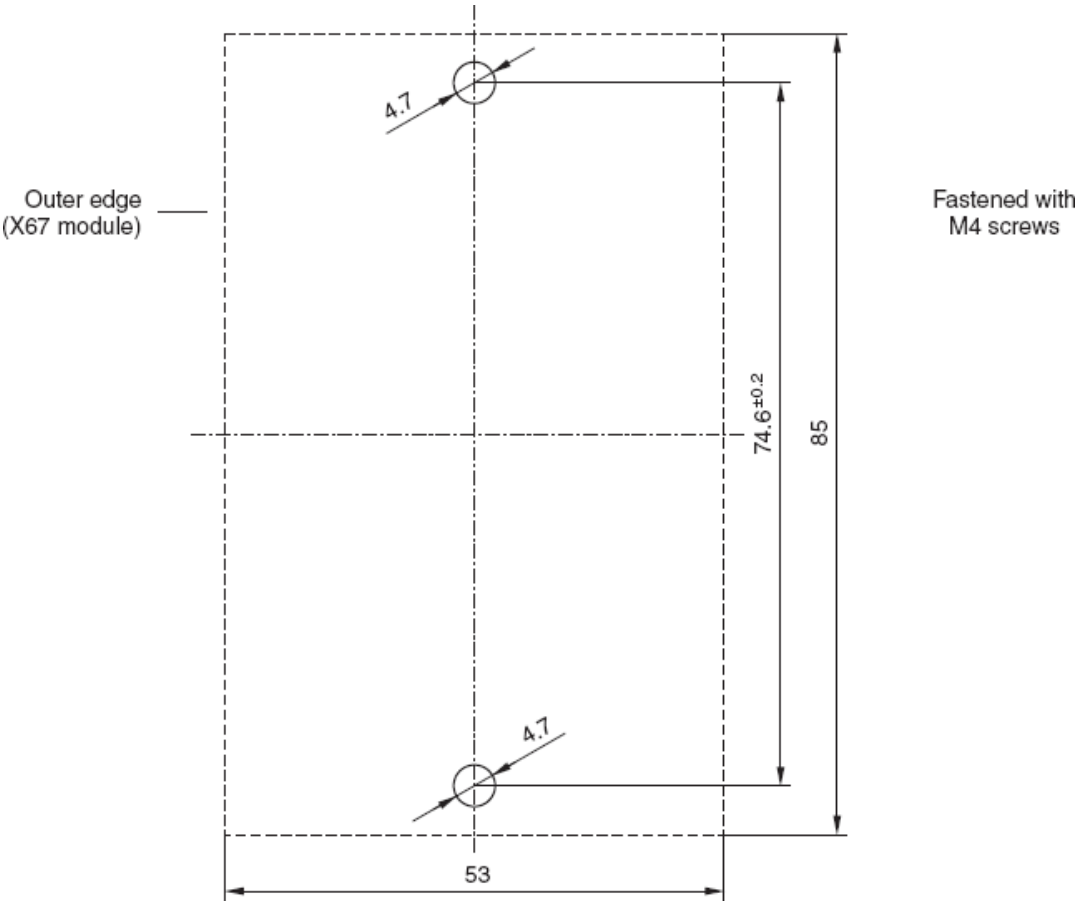


Diagram 14B. Screw fastener drilling template.

LIFT FUNCTIONALITY

Standard Operation - Slide Handle Configuration:

When the device is in the standard operational mode, the sliding grip of the handle controller commands the z-axis (vertical) direction and speed of the lift (**diagram A**). The handle grip has a center neutral position and can slide up and down to provide up and down speed commands to the control system. The further the handle grip is displaced from the neutral position the faster the servo movement to lift or lower the load. The operator controls the slide handle location by grasping the handle grip and moving it up and down as if it were an extension of the operator's arm. The lift moves slightly slower when a load is lifted, thereby giving the operator some feel for the weight of the load.

For safety, an operator present sensor (OPS) within the slide handle must be activated by the operator before the motor will activate (**diagram A**). If the operator removes their hand from the OPS' line-of-sight, the Easy Arm payload is brought to a safe stop.

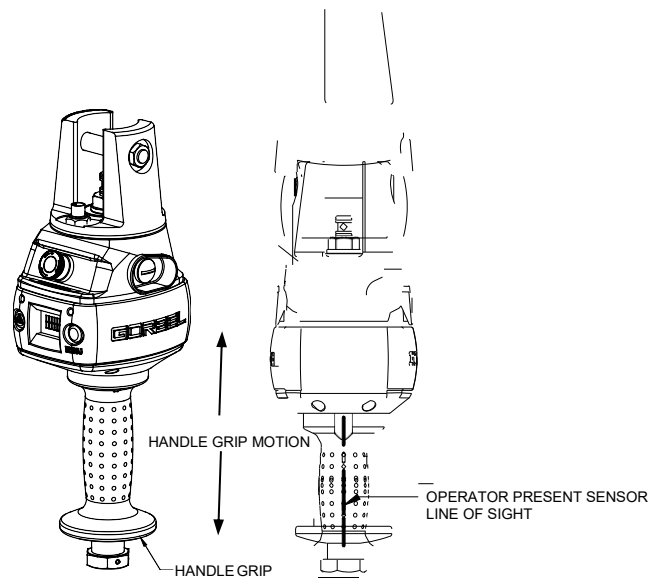


Diagram A. Slide Handle - Handle Grip and Operator Present Sensor Line-of-Sight.

WARNING

Do not mount any objects to the Easy Arm sliding handle grip (i.e. switches). Additional objects may interfere with the travel of the sliding handle grip and affect the overall speed and functionality of the unit.

Standard Operation - Pendant Handle Configuration: When the device is in the standard operational mode, the up and down levers command the z-axis direction and speed of the lift (**diagram C**, page 29). The further the up or down lever is depressed, the faster the servo movement to raise or lower the load.

Standard Operation - Force Sensing Slide Handle: The grip on the handle is connected to a force sensing device so that when the user applies force up or down along the central axis of the handle this is interpreted as intent to move. Speed of the unit is proportional to the amount of force applied. Forces in lateral directions are not detected.

Note: There is no traditional OPS. When the force applied to the handle exceeds a small threshold, the unit activates.

Standard Operation - Force Sensing Hub Handle: Handlebars (Gorbel® optional kit 74630, or by others) are attached to a mounting plate which in turn is connected to a force sensing device so that when the user applies a vertical force up or down, this is interpreted as intent to move. Speed of the unit is proportional to the amount of force applied. Forces in lateral directions are not detected. **Note:** There is no traditional OPS. When the force applied to the handle exceeds a small threshold, the unit activates.

Emergency Stop Button: When depressed, the emergency stop (E-stop) button disables the actuator. The E-stop button is located on the face of the handle (**diagram B**, page 34). The Easy Arm® will operate only when the E-stop has been reset. The OLED will display E-STOP ENGAGED.

Float Mode: In this mode, the operator can simply maneuver the payload directly and cause the load to raise or lower by applying either an upward or downward force on the load. The greater the force applied, the faster the load will move. Note: There is a standard setting in the controls that safely limits the maximum speed of travel in Float Mode; this setting is not adjustable. If the limit is exceeded, the unit will return to standard operation and the OLED will display LIFT READY.

Float Mode is initiated by simply pressing the G-Force® logo button on the left side of the handle (**diagram B** or **C**, page 34). See Step 12, page 30, for complete details on Float Mode operation.

Program Mode: In this mode, the operator can control speed, acceleration, service features and other variable settings (**diagram B** or **C**, page 30). See the **Programming Mode** section, page 37, for complete programming functionality located at the handle.

LIFT FUNCTIONALITY (CONTINUED)

Float Mode LED (Blue): The “Float Mode” enabled LED will illuminate when the G-Force logo button is pressed on the hand controller and Float Mode has been correctly initiated. This LED is located just above the MENU button (diagram B or C).

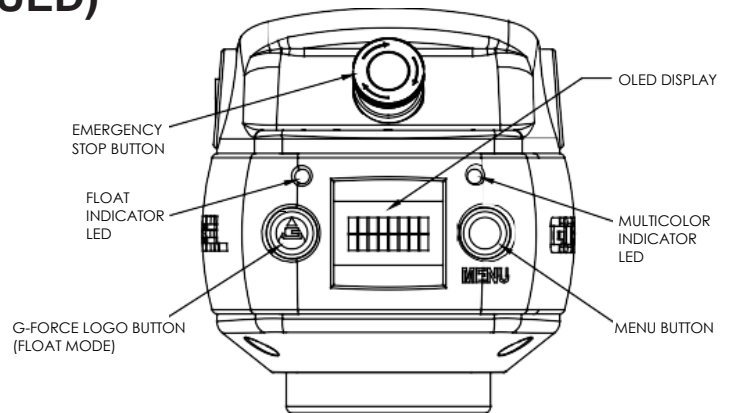


Diagram B. Slide Handle - G-Force® Logo (Float Mode), MENU and Emergency-Stop Buttons and LEDs.

System Fault LED (Red): The “System Fault” LED flashes when basic faults have been detected by the control system. If a fault has occurred, the system will be disabled. This LED is located just above the MENU button (**diagram B** or **C**).

Diagnostic Mode: The Diagnostic Mode is a special program within the Program Mode under the Service menu that will allow a technician to measure or monitor the state of select switches and other electronic components in the actuator and either the slide or pendant handle. It is intended to be used for troubleshooting purposes only. The user can choose a single or multiple components. The E-stop must be cycled off/on to exit this particular program.

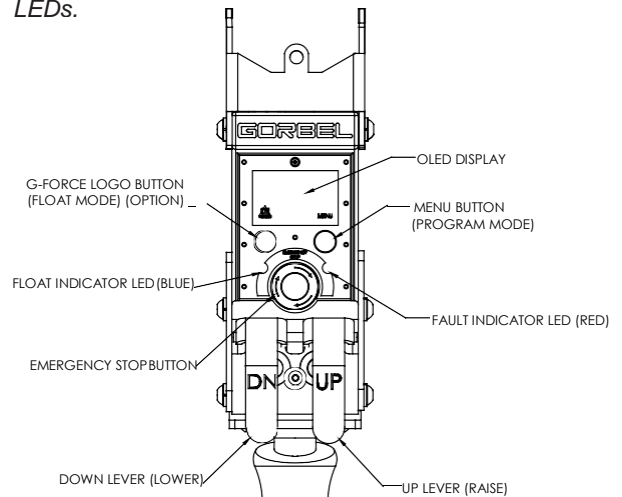


Diagram C. Pendant Handle - G-Force® Logo (Float Mode), MENU and Emergency-Stop Buttons and LEDs.

Overload: The servo controller will prevent the lift from moving upward if loaded beyond the maximum capacity of the Easy Arm®. The red LEDs will flash and LIFT OVERLOAD will be displayed on the OLED to indicate to the operator the unit is overloaded. The lift may be moved down to allow for the safe removal of the load.

WARNING

In Float Mode, the live load weight cannot be increased or decreased because this will cause unwanted motion. Float Mode must be reinitiated each time the weight of the live load is changed.

WARNING

Enabling the operator present sensor while in Float Mode will cause the unit to exit Float Mode.

Limit Switches: The Easy Arm® is equipped with both mechanical upper and lower limit switches, located in the actuator assembly. When the upper limit switch is triggered, the upward motion of the lift stops quickly at a controlled deceleration rate. The controlled deceleration rate guarantees the load cannot come off the hook. When the upper limit is triggered the lift will move down but not up. The lower limit is set so that a minimum of two full wraps of wire rope remain on the drum pulley at all times. When the lower limit switch is triggered, the downward motion of the lift stops quickly at a controlled deceleration rate. When the lower limit is triggered, the lift will only move up and not down.

LIFT FUNCTIONALITY (CONTINUED)

Slack Switch: The Easy Arm® is equipped with a slack switch that senses tension in the wire rope and trips when the wire rope develops slack. The switch is located inside the actuator assembly. When the slack switch senses slack in the wire rope, downward movement of the lift is stopped to minimize the amount of wire rope unwound from the drum pulley. When slack in the wire rope is sensed, the lift will only move up but not down.

Remote Mounted Handle (System Option): The lifting device is capable of operating with the handle displaced from the wire rope (not in-line with the wire rope). For example, if an end user has tooling that is too large for the operator to safely reach and operate the handle in the standard in-line position, remote mounting the handle is recommended. The tooling must be mounted (and balanced) on the end of the wire rope, while the handle can be remote mounted to the tooling.

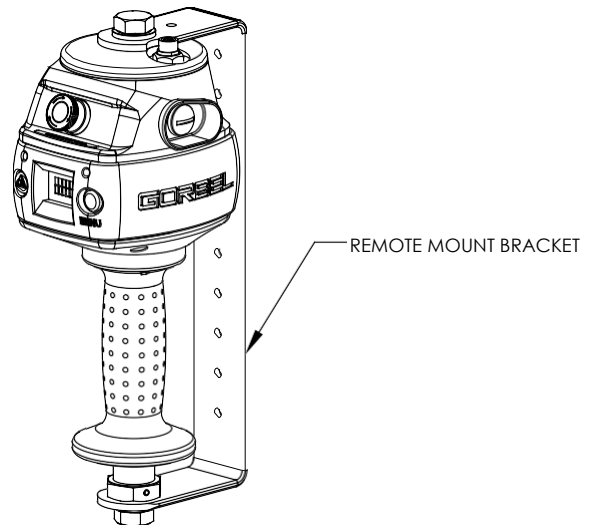


Diagram D. Remote Mounted Slide Handle with Gorbels® Bracket.

WARNING

The tooling **MUST** be attached to the end of the wire rope with the G360™ swivel assembly (supplied by Gorbels, Inc.). Failure to mount the tooling with a swivel assembly can result in premature failure of both the wire rope and the coil cord.

WARNING

All tooling must be retained to the G360™ assembly utilizing the M16 thread and locking pin provided.

The remote mounted handle is linked to the coil cord via an extension cable. The handle operates exactly the same as if it were mounted in-line. The end user must supply Gorbels with the required length of the extension cable such that it can be safely routed and clamped to the tooling.

CAUTION

Always include the distance for bends and turns when providing the extension length.

WARNING

Ensure that the slide handle is supported properly in remote mounted handle applications by restraining the slide handle at both the top and bottom mounting points (**diagram D**).

CONTROLS INTERFACE FEATURES

The jog switch push buttons and communications connector are protected by a cover (**diagram E**). To access the jog switch push buttons and communications connector, loosen the M4 nut and slide the shield back towards the wire rope. **Note:** Do not fully unthread the M4 nut. When finished, slide the shield back into place and re-tighten the M4 nut.

Jog Switch Push Buttons: The jog switch buttons allow qualified personnel to replace the wire rope on the unit. To effectively operate the jog switch buttons, all electrical cables must be connected and power on.

Depressing the “Up” jog switch button will enable the motor and cause the system to reel the wire rope into the actuator and onto the drum pulley. Depressing the “Down” jog switch button will enable the motor and cause the system to pay out the wire rope from the actuator and off of the main pulley. Jog switch push buttons override all motion control from a handle or tooling.

WARNING

The jog switch buttons are for system maintenance and load testing use only and should not be manipulated during normal operation of the Easy Arm. Operation of the jog switch buttons during normal operation increases the risk of personal injury to the operator.

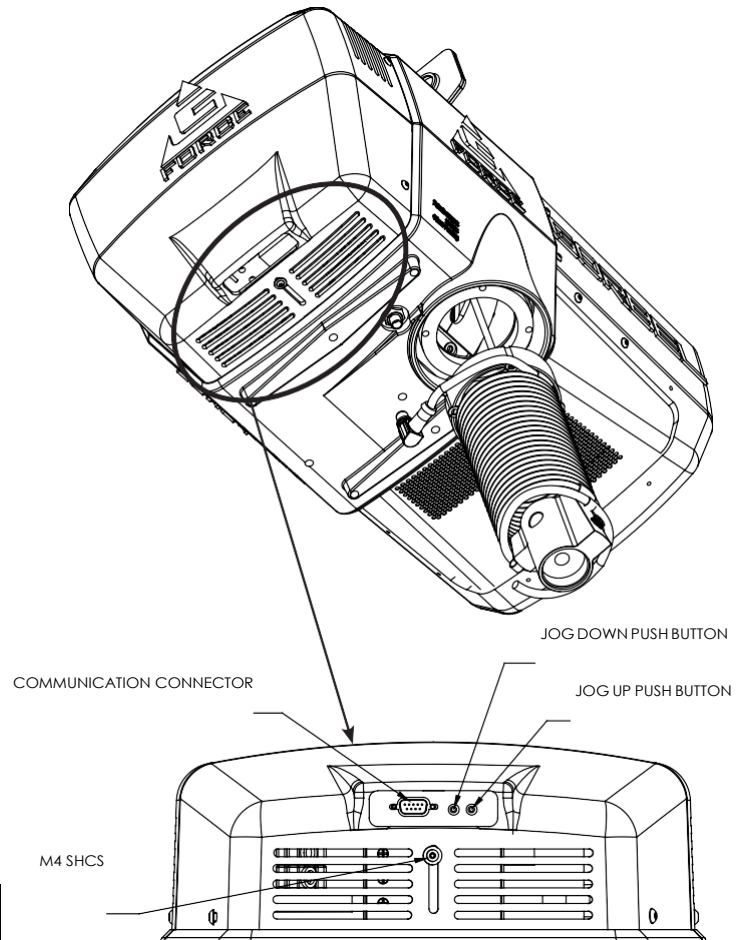


Diagram E. Actuator – Controls Interface Display
(as viewed from bottom of actuator)

Service Mode: This operation mode is similar to the “safe mode” of a PC. In this state all handle motion control and Q & iQ custom features are disabled, all digital outputs are turned off, and only basic jog up, jog down, OLED display and safety program mode are available. It allows a minimum safe operation on a unit with a damaged handle, broken I/O electronics or other damaged peripheral control components that would make it dangerous to run the unit if the component is used. The unit is still inoperative if actuator components such as the drive, motor, or jog switches are damaged. To activate service mode, with the handle E-stop pushbutton released and the OLED screen displaying LIFT READY, press and hold both jog pushbuttons on the actuator for ten seconds. Both the blue and red LEDs flash once per second and the OLED displays SERVICE MODE when the operation mode is ready.

Communications Connector: This connector is the communications port for the Easy Arm®. With a standard RJ45 Ethernet cable, users may connect to the Easy Arm® to upload software programs or use the Easy Arm® VNC Viewer. When not in use, ensure the Jumper is connected between the Communications Connector and the On-Board WiFi AP connector.

On Board WiFi AP Connector: This is the port that connects the CPU of the Easy Arm to the Access Point located on the actuator’s printed circuit board.

PROGRAM MODE

Overview (Software Version R2.0)

Program Mode is used to control and adjust all of the features on the Q2 and iQ2 series G-Force®. Before entering Program Mode, review the **Program Mode Menu outline, Chart D**, starting on page 39.

Note: An alternative to using Programming Mode via the Handle is the HMI Visualization which can be accessed via a PC with a VNC Viewer installed. See Appendix 2 for more info.

Using Program Mode

Program Mode is initiated by following the steps below. Reference **diagrams B** and **C** on page 26 for button locations.

Entering Program Mode (chart A, page 39):

1. **Press and Hold** the MENU button (right-hand side of handle) for two seconds to activate Program Mode.
2. After two seconds, release the MENU button. The LED will illuminate amber and “PROGRAM MODE” will be displayed for one second.
3. Press the MENU button to toggle between menus. The OLED will display the corresponding programmable menus:
 - V-LIMITS MENU - Virtual Limits menu
 - SPEED MENU - Lift Speed adjustment
 - RESPONSE MENU - Lift Response (acceleration) adjustment
 - SETTINGS MENU - Programmable Features on both the Q2 and iQ2 units
 - ADVANCED SETTINGS - Programmable Features on iQ2 units only
 - LANGUAGE SELECTION — Select regional language for OLED display.
4. Once you have reached the menu you would like to enter, press the G-Force® logo button.
5. The first programmable feature in that menu will be displayed. See **Chart D**, beginning on page 39 for the full list of menus and the programmable features under each menu.
6. To move to the second programmable feature, press the G-Force® MENU button again.
7. **Note:** If the MENU button is repetitively pressed in a submenu, then the selection is cleared and the last submenu option displays “RETURN BACK TO MAIN MENU” which can be selected to navigate to the program main menu.
8. Once the desired feature is selected the display shows “SELECTION CONFIRMED”.
9. After the command is executed, the system returns to standard operation, and the OLED displays “G-FORCE READY TO LIFT”.

PROGRAM MODE (CONTINUED)

Handle Operation



Avoid the OPS:

Make sure to keep fingers clear of the photo sensor area when in program mode. Breaking the photo sensor will drop the unit out of program mode and you will need to start over again.

Confirming a Selection:

When making changes in program mode, do not break the beam of the photo sensor until the new setting has been completed. The display must be allowed to flash “SELECTION CONFIRMED” before the handle is gripped.

Breaking the sensor beam before the display flashes “SELECTION CONFIRMED” will cancel the change, drop the unit out of Program Mode and you will have to start over.

G-Force® Logo Button:

Float Mode: Press and release this button to initiate Float Mode.

Program Mode: Use this button to select the desired item within the menu by pressing and releasing to advance to a submenu or confirm selection.



Menu Button:

Press and hold this button for approximately three seconds until the unit enters program mode. Once in program mode, this button is used to scroll to the desired menu. Press and release this button to advance to the next menu. If you happen to accidentally pass by a menu, it will come around again if you continue to press and release this button.

No Timeouts:

There is no Menu timeout when in Program Mode. The menus will be active long enough to confirm any selections and can be exited sooner by activating the OPS sensor.

PROGRAM MODE (CONTINUED)

The following table illustrates the different menus and corresponding selections available under each menu and sub-menu. Use the MENU button to scroll to the desired menu and the G-Force logo button to select the desired item within each menu.

Menu	Options	Sub-Menu	Sub-Menu Options	Next Sub-Menu Options			
Virtual Limits Menu	Upper Limit						
	Lower Limit						
	Lower Slow Down						
	Upper Slow Down						
	Upper Resume						
	Adjust Slow Down Speed						
	VL Menu Reset Settings						
	Return back to main menu						
Speed Menu	Current Speed						
	Select Speed 10%						
	Select Speed 20%						
	Select Speed 30%						
	Select Speed 40%						
	Select Speed 50%						
	Select Speed 60%						
	Select Speed 70%						
	Select Speed 80%						
	Select Speed 90%						
	Select Speed 100%						
	Return back to main menu						
Response Menu	Current Response						
	Response Low						
	Response Medium						
	Response High						
	Return back to main menu						
Settings Menu	Zero Weight Display						
	Weight Readout On						
	Display Units						
	Float Mode Setup Sub-Menu				Float Mode Setup Sub-Menu	Enable Float Mode	At over force To over speed Turn off SS check Max Force xx LBS (changeable)
						Float Mode Anti-Recoil	
			Unload Stop On				
			Float Mode Gains Sub-Menu				
			Return to previous menu				
			Return to main menu				
	User Overload Sub-Menu	User Overload Sub-Menu	Change Limit	At OVLD LBS xxx (weight) Tare OVLD Lmt Set Limits LBS 170			
			Change Operator Force	At Force LBS xxx (weight) To Force LBS 5 (Changeable)			
			Change Sensitivity	At Level 4 (Changeable) Return to previous menu Return to main menu			
			Default Settings				
			Return to previous menu				
			Return to main menu				
	Timer Sub-Menu	Timer Sub-Menu	Pause Timer				
			Handle Timer				
			Float Mode Timer				
			Custom Timer				
			Default Settings				
			Return to previous menu				
			Return to main menu				
	Force Sensing Handle Sub-Menu	Force Sensing Handle Sub-Menu	.—FSH-- Status				
	Settings –Reset!-						
Return back to main menu							

Chart A. Program Mode Process

PROGRAM MODE (CONTINUED)

Menu	Options	Sub-Menu	Sub-Menu Options	Next Sub-Menu
Advanced Settings	Settings Menu 2			
	Reset Menu 2 Settings			
	Return back to main menu			
Language Selection	English Language			
	Spanish Language			

Chart A. Program Mode Process

Lockout Feature (chart C)

To prevent tampering in Program Mode, a Lockout Feature is available.

To Lockout Program Mode from the handle:

1. Press both the G-Force® logo button and the MENU button simultaneously for five seconds.
2. The OLED will display “LOCKOUT CHECK” while both buttons are being depressed.
3. After five seconds, “PROGRAM LOCKED” will be displayed to confirm the Lockout was successful.

If Program Mode is requested after the Lockout has been enabled, the LED will illuminate amber to indicate Program Mode is not accessible and “PROGRAM LOCKED” will be displayed again.

To Unlock Program Mode:

1. Press both the G-Force® logo button and the MENU button simultaneously for five seconds.
2. The OLED will display “UNLOCK CHECK” while both buttons are being depressed.
3. After five seconds, “PROGRAM UNLOCKED” will be displayed to confirm the Lockout was successful.

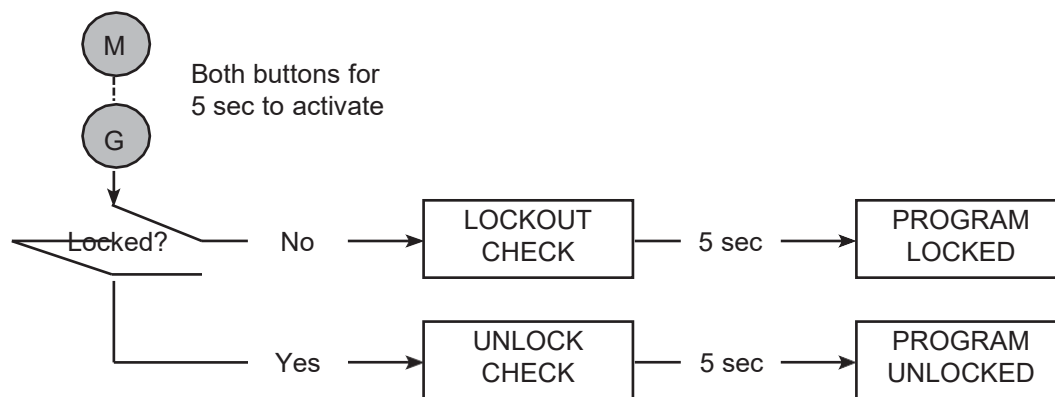


Chart C. Lockout Feature Process.

Disabling Handle Menu

For added system security the entire Program Mode Menu can be disabled from the password protected HMI Visualization. To do so only requires navigating to the **System Config** page and toggling the Handle Menu Enabled/Disabled button. **NOTE:** Once the Handle Menu is Disabled it requires Re-Enabling it via the HMI and Unlocking via the Handle pushbuttons to access Program Mode via the Handle.

If the G-Force® has detected a fault or is running in SERVICE MODE, only a limited set of menus are accessible. For example, if the G-Force® records a fault, when Program Mode is activated the OLED will display “LIMITED PRG MODE” rather than “PROGRAM MODE”. Safety Program Mode can be navigated just as Program Mode would be, however the only menus available are:

- V-LIMITS MENU - Virtual Limits menu
- SPEED MENU - Lift Speed adjustment
- RESPONSE MENU - Lift Responsiveness (Acceleration) adjustment
- SERVICE MENU - Customize and manage maintenance and service features

VIRTUAL LIMITS WARNINGS

WARNINGS

If the upward speed reduction point is being used to reduce the impact of engaging the load “on the fly” (i.e. catching the load with a hook while the G-Force® is already in motion in the upward direction), care must be taken to ensure the speed reduction takes place before the load is engaged. Please program the Upper Slow Down Reduction point at least half an inch below the exact point of pick-up.

PROGRAM MODE (CONTINUED)

Program Mode	Menu	OLED Text	Feature Description
Virtual Limits (VL) Menu (* **, ***)	V-LIMITS MENU[2] 2	UPPER LIMIT	Keep the load at the desired position and select to set the upper limit.
		LOWER LIMIT	Keep the load at the desired position and select to set the lower limit. Note: Setting the upper and lower virtual limits to the same position will cause the unit to not travel in either direction.
		LOWER SLOW DN	Keep the load at the desired position and select to set the lower slowdown limit. (The load slows down from max speed once crossing this limit).
		UPPER SLOW DN	Keep the load at the desired position and select to set the upper slowdown limit. (The load slows down from max speed once crossing this limit).
		UPPER RESUME	Keep the load at the desired position and select to set the upper resume limit. (The load's speed increases from the upper slowdown speed to the regular speed here).
		ADJUST SLOW DOWN SPEED	Allows one to set the speed of slowdown for both the upper and lower slow down limits. It first displays the current slowdown speed, and by toggling, one can select speeds from 5-50-% of max speed (Multiples of 5) as set in the SPEED MENU.
		VL MENU -RESET!-	Reset all programmed virtual limits in this menu.
		RETURN TO MAIN MENU	Return back to the main selection menu Reset all programmed virtual limits in this menu.
Lift Speed Setting	SPEED MENU	SPD MENU SPD 10% ~ SPD 100%	Maximum hoist speed selection, [10 – 100%] correspond to lowest and highest speed.
		RETURN TO MAIN MENU	Return back to the main selection menu
Lift Responsiveness (Acceleration) Setting	RESPONSE MENU	RESPONSE LOW	Set the lowest handle control response corresponding to about 75% of the highest responsiveness setting.
		RESPONSE MEDIUM	Set the medium handle control response corresponding to about 85% of the highest responsiveness setting.
		RESPONSE HIGH	Set the highest handle control responsiveness setting.
		RETURN TO MAIN MENU	Return back to the main selection menu
Force Sensing Handle Settings	FAST ZERO FSH	FAST ZERO FSH	This menu provides a short cut to tare the Force Sensing Handle. Clicking the Float Mode button will perform the tare process. This menu will not be displayed unless a Force Sensing Handle is connected.
Q2 & iQ2 Custom Features	SETTINGS MENU	ZERO WT DISP	Record and tare out the handle weight for weight readout calculation.
		WEIGHT READ ON READ OFF	Toggle between enabling and displaying the load weight. Once enabled, weight is displayed two seconds into standard operation (unit idling).
		DISPLAY METRIC	Toggle the unit of the weight readout display between pounds (English) and kilograms (Metric).
		FM SETUP SUB-MENU	Access Float Mode Configuration Setup Sub-Menu.
		USR OVLD SUB-MENU	User Programmable Overload Setup Sub-Menu.
		TIMER SUB-MENU	Excessive Pause Timer Setup Sub-Menu.
		FSH HNDL SUB-MENU	[Appears only when FSH is connected] Force Sensing Handle (FSH) Setup Sub-Menu.
		SETTINGS -RESET!-	Reset all custom features in the settings menu
		RETURN TO MAIN MENU	Return back to the main selection menu

Chart D. Program Mode Menu and Selection Settings.

PROGRAM MODE (CONTINUED)

Program Mode	Menu	OLED Text	Feature Description
[SUB-MENU] Float Mode (FM) Configuration Setup	FM SETUP SUB-MENU	FM Setup Menu	Startup prompt screen when this sub-menu is accessed.
		ENABLE DISABLE FLOAT MO ³	Enable or Disable running Float Mode related features, such as Standard Float Mode, Remote-Mount Float Mode Trigger, Dual Float Mode Weights, etc.
		FM ANTI-RECOIL	Float Mode Anti-Recoil Configuration Sub-Menu.
		UNLOAD STOP ON/ STOP OFF	Optional feature utilizing Anti-Recoil detection. When user sets a weight on a surface in Float Mode, it is terminated if Anti-Recoil detects an unloading. This can be useful for applications needing a quick Float Mode exit to an idle state to allow user to work on the part. Note: As a result of the extra detection, Float Mode is likely to terminate when the upper limit switch is hit while unit is running at a fast speed. This false detection can be avoided or reduced by running the unit at a low speed.
		FM GAINS SUB-MENU	Float Mode Gain Selection Sub-Menu (660 lb. capacity only)
		RETURN TO PREV. MENU	Clicking this takes the screen back to the Settings Menu page starting with Zero Wt Display
		RETURN TO MAIN MENU	Return back to the main selection menu
[SUB-MENU] Float Mode Anti-Recoil Configuration Setup	FM ANTI RECOIL	AT OVER FORCE / SPEED	Startup screen when this sub-menu is accessed. The current configured Anti-Recoil detection method is displayed (see next item for details on the detection methods).
		TO OVER FORCE/ SPEED	Toggle Anti-Recoil detection method between standard over-speed and over-force detections. Anti-Recoil protects against a dropped weight while running Float Mode causing the unit to speed upward until hitting an object or a push force equivalent to the dropped weight. Over-Speed Detection: Unit terminates Float Mode if speed exceeds maximum Float Mode speed at 90% of unit loaded speed. Over-Force Detection: Unit terminates Float Mode if user's operating force exceeds the maximum force limit or a dropped weight is detected by evaluating the force profile. Different from Over-Speed Detection, unit can run at the maximum Float Mode speed. a. Maximum force limit defaults at 35 lbs. b. A dropped weight profile assumes the operator has both hands off the weight (tooling) as the unit speeds upward. Detection ability may reduce if user attempts to stop the unit or if the tooling swings heavily. c. If the total lifted weight (e.g. tool and part) is less than the maximum force limit, Over-Speed Detection is applied.
		MX FORCE 15 ~ 45 LBS	Set Anti-Recoil Over-Force Detection maximum force limit between 15 and 45 lbs. at 5 lb. increments. Anti-Recoil Over-Force Detection limits increased for 660 lb. units. New limits are between 30 and 90 lbs. at 5 lb. increments.
		DEFAULT SETTINGS	Unit reset to the default setup according to the configured detection method. For example, unit configured with Over-Force Detection defaults to 35 lbs. maximum force limit, dropped weight profile checkup and conditional Over-Speed Detection. UNLOAD STOP option is turned off for both methods.
[SUB-MENU] Float Mode Gains Selection (660 lb. capacity ONLY)	FM GAINS SUB-MENU	DOES NOT APPLY	Will be displayed for non-660 lb. capacities.
		LOWEST	Lowest (least responsive / most stable) Float Mode gains.
		LOW	Second lowest Float Mode gains. (More responsive than LOWEST).
		DEFAULT (MEDIUM)	Default Float Mode gains as defined in database.
		HIGH	Highest (most responsive / least stable) Float Mode gains.

Program Mode	Menu	OLED Text	Feature Description
[SUB-MENU] User Programmable Overload Setup	USR OVLD SUB-MENU	USER SUB-MENU	Startup prompt screen when this sub-menu is accessed. Please activate weight readout while setting an overload limit, to ensure that the load cell is properly calibrated and the desired overload limit is within the acceptable range. Please see WEIGHT READ ON under SETTINGS MENU for additional details.
		CHANGE LIMIT	1. Displays the current overload limit 2. Tare Overload Limit 3. Set a new overload limit See <i>Program an Overload Limit</i> below for more details.
		CHANGE OPERATOR FORCE	1. Displays the current operator force 2. Set a new operator force value (Starting at 5 lbs.)
		CHANGE SENSITIVITY	Allows one to see the current sensitivity level and change it as well (Max value 5)
		DEFAULT SETTINGS	Apply factory default overload settings. Overload limit is set as the maximum limit either at the rated capacity plus 5 lbs. for G-Force® 165# and Easy Arm® 165# models, or 101% of the rated capacity plus 5 lbs. for all other models. The operating force limit is set at 15 lbs. and detection sensitivity is set to 5 (high).
		RETURN TO PREV. MENU	Clicking this takes the screen back to the Settings Menu page starting with Zero Wt Display
		RETURN TO MAIN MENU	Return back to the main selection menu
User Programmable Overload Limit. Program an Overload Limit	CHANGE OLVD LMT	AT OVLD LBS XXX	Startup prompt screen displaying the programmed overload limit. (Remember, the user Overload feature adjusts the detection sensitivity and limit parameters.) The G-Force is overloaded approximately when the load exceeds the Overload Limit + the OP FORCE (Operator Force Limit). Note: this limit is superseded by the G-Force® capacity limit.
		TARE OVLD LMT	Tare the total lifted weight as Overload Limit. When selected, unit tares the total lifted weight supported by the wire rope as the Overload Limit. (Monitored on the "WT READ ON" in the settings Menu). Maximum limit = Rated capacity plus 5 lbs. for G-Force® 165# and Easy Arm 165# models, or 101% of the rated capacity plus 5 lbs. for all other models. Minimum limit = 25% of the rated capacity. (A warning is triggered if the tare weight is outside this range)
		SET LIMIT LBS	Set Overload Limit to the selected limit. TARE OVLD LMT section lists the maximum and minimum limits for Overload Limit. Clicking the pushbutton decrements the limit from the maximum, one lb. at a time. Press the G-Force® button to confirm selection. The overload limit is now set at ##### lbs.
		RETURN MENUS	1. Clicking Return to Prev. Menu takes the screen back to the Settings Menu 2. Clicking Return to Main Menu takes it back to the main selection menu.
Configure Operating Force Limit for Moving a Load in Air	CHANGE OPERATOR FORCE	AT FORCE LBS XX AT FORCE LBS	Startup prompt screen displaying the programmed Operating Force Limit. Note: An Operator's push and pull force is an extra loading to the system, especially when handle is mounted on the tooling. This sub-menu allows one to set a Force Limit to account for different user's operating force thus reducing chance of false overload detection. The limit should not be set larger than necessary as it reduces detection capability. By default, the limit is set at 15 lbs.
		TO FORCE LBS	Set Operating Force Limit to between 5 and 25 lbs. in 1 lb. increments.
		RETURN MENUS	1. Clicking Return to Prev. Menu takes the screen back to the Settings Menu 2. Clicking Return to Main Menu takes it back to the main selection menu.
Configure the sensitivity. Config. Overload Detection Sensitivity	CHANGE SENSITIVITY	AT LEVEL X -	Startup prompt screen displaying the programmed Detection Sensitivity. The sensitivity parameter can be reduced to prevent false detection when operating a load at no greater than the Overload Limit. However, do not reduce the sensitivity unless it is necessary due to actual usage. A reduced sensitivity increases the time to detect a legitimate overload condition that may result in damages or failure to the unit. By default, Detection Sensitivity is set at 5 (HIGH).
		TO LEVEL 1 - 5	Set Detection Sensitivity to between 5 (HIGH) and 1 (LOW) one level decrements at a time.
		RETURN MENUS	1. Clicking Return to Prev. Menu takes the screen back to the Settings Menu 2. Clicking Return to Main Menu takes it back to the main selection menu.

Chart D. (continued) Program Mode Menu and Selection Settings.

PROGRAM MODE (CONTINUED)

Program Mode	Menu	LCD OLED Text	Feature Description
[SUB-MENU] Excessive Pause Timer Setup Sub- Menu	TIMER SUB-MENU ³	PAUSE TIMER	Startup prompt screen when this sub-menu is accessed.
		HANDLE TIMER	Change timer setting for the slide and pendant handle run modes.
		FLOAT MODE TIMER	Change timer setting for Float Mode.
		CUSTOM TIMER	Change timer setting for custom motion such as Auto Home or other motion profile.
		DEFAULT SETTINGS	Apply default excessive pause timer settings: slide and pendant handles (45 seconds), Float Mode (60 seconds) and custom motion (20 seconds).
		RETURN MENUS	1. Clicking Return to Prev. Menu takes the screen back to the Settings Menu 2. Clicking Return to Main Menu takes it back to the main selection menu.
Change Time Setting for the Selected Run Mode	CUSTOM TIMER	AT LIMIT SEC ## MIN	Startup prompt screen displaying the current timer limit between 1 ~ 59 seconds or 1 ~ 5, 10 or 15 minutes.
		SET LIMIT SEC ## MIN M	Set a custom pause timer limit. Clicking the MENU pushbutton increments the setting from 1 to 59 seconds, followed by 1-15 minutes. Press-and-hold the pushbutton does a quick scroll-thru on these limits. Once the desired time is reached, press the GForce button to confirm the selection.
[SUB-MENU] Force Sensing Handle Setup Sub-Menu	FSH HNDL SUB-MENU	FSH HNDL SUB-MENU	Startup prompt screen when this sub-menu is accessed.
		ZERO FSH WEIGHT	Tare the FSH handle bar weight to zero the load cell signal.
		CHANGE 2 INLINE (REMOTE)	Change FSH style to remote if current style is inline (or inline if current style setting is remote).
		SET FRCE 2 LARGE	Change FSH Start up force to large if current setting is small (or vice versa).
		RESET FSH TARE	Reset FSH tare value to zero to un-zero the load cell signal.
		DEADBAND CENTER	FSH deadband averaging to improve sensitivity of FSH signal by centering it.
		DEFAULT SETTINGS	Apply default setting of FSH.
Advanced Features	ADVANCED SETTINGS	DUAL FM TOOL WT	(Float Mode feature enabled) Record tooling weight for the Dual Float Mode weights feature.
		DUAL FM LOAD WT	(Float Mode feature enabled) Record tooling and load weights for the Dual Float Mode weights feature.
		ANTIDROP TOOL WT	Tare tooling weight for anti-drop feature. The minimum difference between unloaded and loaded tool weight is 20 lbs. for G-Force® and 25 lbs. for Easy Arm®.
		MENU 2 SET HOME	Program the auto home tracking position (load must be at desired position for the limit).
		MENU 2 -RESET!-	Reset above custom features including the dual Float Mode, anti-drop, and auto home features.

Chart D. (continued) Program Mode Menu and Selection Settings.

* Indicates this feature is only available on iQ2 units.

** Additional details are available in the Input/Output Functionality section.

¹ Four (4) virtual limit sets are available with a standard Q2 or iQ2 unit. The Limits Sets 1 and 2 are programmable via the Handle Program Menu (set programmed is toggled with Digital Input). More virtual limit sets are possible to configure via the visualization or with custom programming.

² Gorbel® recommends the minimum distance between any two virtual limits to be no less than 2 inches for best performance and user experience. Please note this distance is greatly dependent on Unit Speed, Responsiveness, Capacity, and Load, individual results may vary.

Note: Gorbel® G-Force® & EasyArm® products are capable of achieving consistent positioning to 0.5 inches. Please note this distance is greatly dependent on Unit Speed, Responsiveness, Capacity, and Load, individual results may vary.

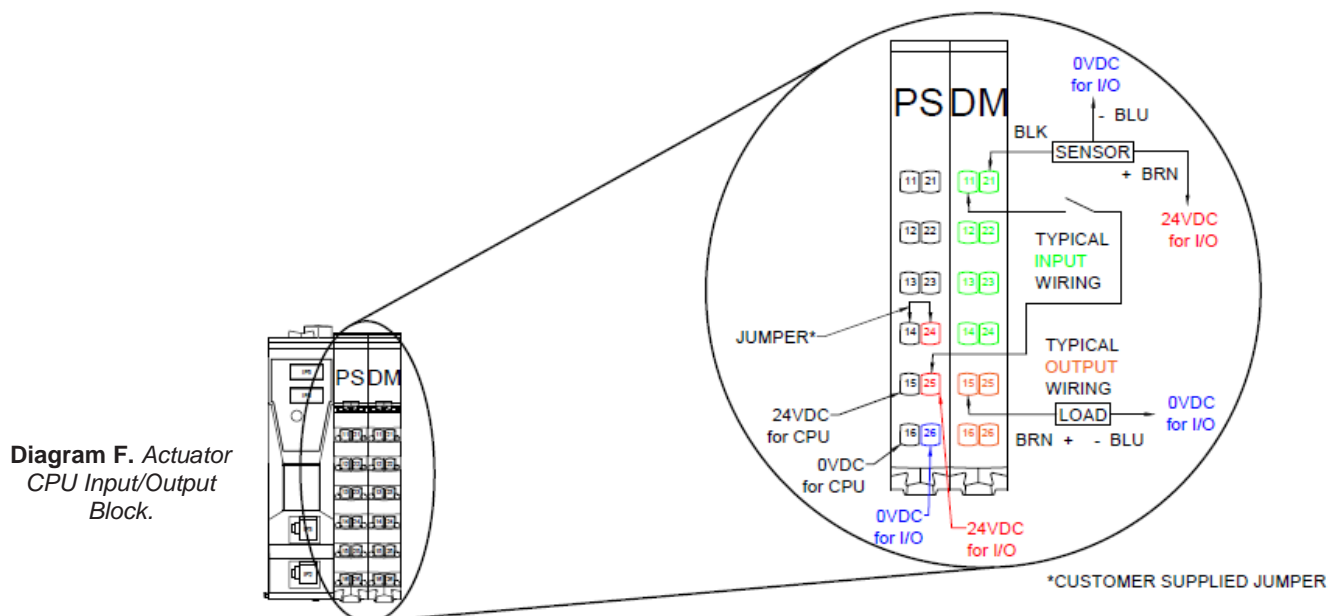
³ This entire section or item selection requires cycling the main 220 VAC power for the setting(s) to take effect.

PROGRAM MODE (CONTINUED)

iQ2 Actuator Programmable Input/Output Module Functionality

I/O Point	Assigned Function	Description
1	Input - Dual virtual limit sets	When this input option is turned on, the G-Force® switches to a second independent set of virtual limits. The second set of virtual limits is programmed the same as the standard set but with this input turned on. See chart DC for instructions on setting each of these limit sets.
2...	Input – Inhibit Motion	Example user defined inputs.
	Input – Remote Float	
3...	Input – Toggle Speed	
	Input – Slowdown	
	Input – Jog Down	
...4	Input – Float Bias Up	
5	Output - External Control Output 1	This output option is controlled by the input on the optional expansion 8-point input/output block set to EXTERNAL CONTROL INPUT 1. In this example, when that input is on, output 1 on the iQ2 actuator input/ output module is on and vice versa.
6	Output - External Control Output 2	This output option is controlled by the input on the optional expansion 8-point input/output block set to EXTERNAL CONTROL INPUT 2. In this example, when that input is on, output 2 on the iQ2 actuator input/ output module is on and vice versa.
7	Output – Service Indicator	This output option turns on when service is required (based on hours of use and set at the factory) and may be used to turn on an external service indicator (supplied by others). The reset function for this output is in the Handle Settings Menu option: CLEAR RUN TIME or disable the Warning in the Service Menu of the HMI.
8	Output - Fault indicator	This output option turns on when a command fault or drive fault occurs. It does not turn on due to a command warning.

Chart E. iQ2 Actuator Input/Output Module Example Functionality



PROGRAM MODE (CONTINUED)

➔ **Tip:** I/O Functionality may be assigned via HMI Visualization programming to meet application requirements. Review the HMI Visualization Programming Appendix for more options and details.

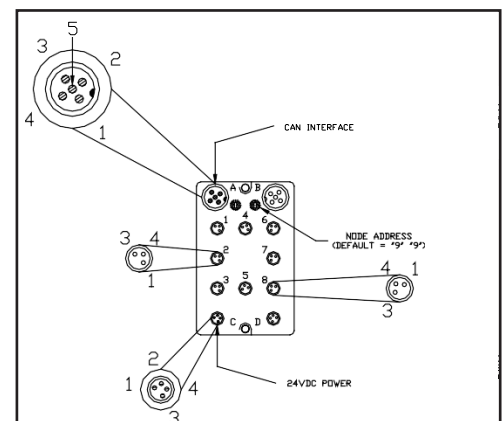
iQ2 Expansion Programmable 8-Point Input/Output Block Functionality

I/O Point	Assigned Function	Description	Settings (see chart A for instructions on navigating and setting menu functions)
1	Input - Dual load weight Float Mode*	When the G-Force® is in Float Mode, this input option allows switching from one pre-programmed load weight to another. These two weights must remain fixed; otherwise, some drifting can occur if the weight is different than the programmed value.	The two Float Mode load weights programmed are located in ADVANCED SETTINGS MENU - DUAL TOOL WT and DUAL FM LOAD WT. The desired load weight must be suspended from the G-Force® when performing each setting. I/O Functionality may be assigned via visualization programming to meet application requirements.
2	Input - Anti-drop feature (Clamp request)	This input option is typically wired to a clamp request pushbutton. When the input is on, Output #7 (see I/O Point 7) turns on and Output #8 turns off regardless of the tooling loading state.	Programming the tare weight is located at ADVANCED SETTINGS MENU - ANTIDROP TOOL WT. The empty tooling (including handle controller and other accessories) without a pickup part must be suspended solely by the wire rope when tarring. The minimum difference between unloaded and loaded tool weight is 20 lbs. for G-Force®, and 25 lbs. for Easy Arm®. I/O Functionality may be assigned via visualization programming to meet application requirements.
3	Input - Anti-drop feature (Unclamp request)	This input option is typically wired to an unclamp request push-button. When the input is on, Output #8 (see I/O Point 8) turns on only if Anti-Drop algorithm determines the suspended load is at or below the set weight (ANTIDROP TOOL WT). If Output #8 turns on, Output #7 is turned off.	
4	Input - Auto Home	When this input option is toggled (momentarily turned on then off again), the G-Force® automatically travels to the set home position in the vertical travel. Tracking stops when obstruction is detected, i.e. Q2/iQ2 G-Force® stops at 10-25 lbs. depending on unit capacity.	The Auto Home position programming is located at ADVANCED SETTINGS MENU 2 - MENU SET HOME. Move the G-Force® to the desired position in the vertical travel before selecting the position setting in this menu. I/O Functionality may be assigned via visualization programming to meet application requirements.
5	Input - External control input 1	This input option controls the output on the actuator input/output module set to EXTERNAL CONTROL OUTPUT 1. In this example, when this input is on, output 1 on the iQ2 actuator input/output module is on and vice versa.	I/O Functionality may be assigned via visualization programming to meet application requirements.
6	Input - External Control input 2	This input option controls the output on the actuator input/output module set to EXTERNAL CONTROL OUTPUT 2. In this example, when this input is on, output 2 on the iQ2 actuator input/output module is on and vice versa.	
7	Output - Anti-drop feature (Clamp Control)	This output option is typically wired to actuate the clamping mechanism of an end effector tooling. It turns on when Input #2 (see I/O Point 2) is on and remains latched on when the input is released. It can be turned off by Input #3 (see I/O Point 3).	See I/O Point 2&3 Settings description.
8	Output - Anti-drop feature (Unclamp Control)	This output option is typically wired to actuate the unclamping mechanism of an end effector tooling. It turns on when Input #3 (see I/O Point 3) is on and the Anti-Drop algorithm determines the suspended load is at or below the set weight (ANTIDROP TOOL WT). If it is not turned on, the input can be held momentarily (do not hold on indefinitely) until the tooling is unloaded then the output is turned on. Once the output turns on, it remains latched on when the input is released. It is always turned off with Input #2 (see I/O Point 2).	

Chart F. Expansion 8-Point Input/Output Block.

* G-Force® must have Float Mode feature enabled for this feature to work.

Diagram G.
Handle
Input/Output Block.



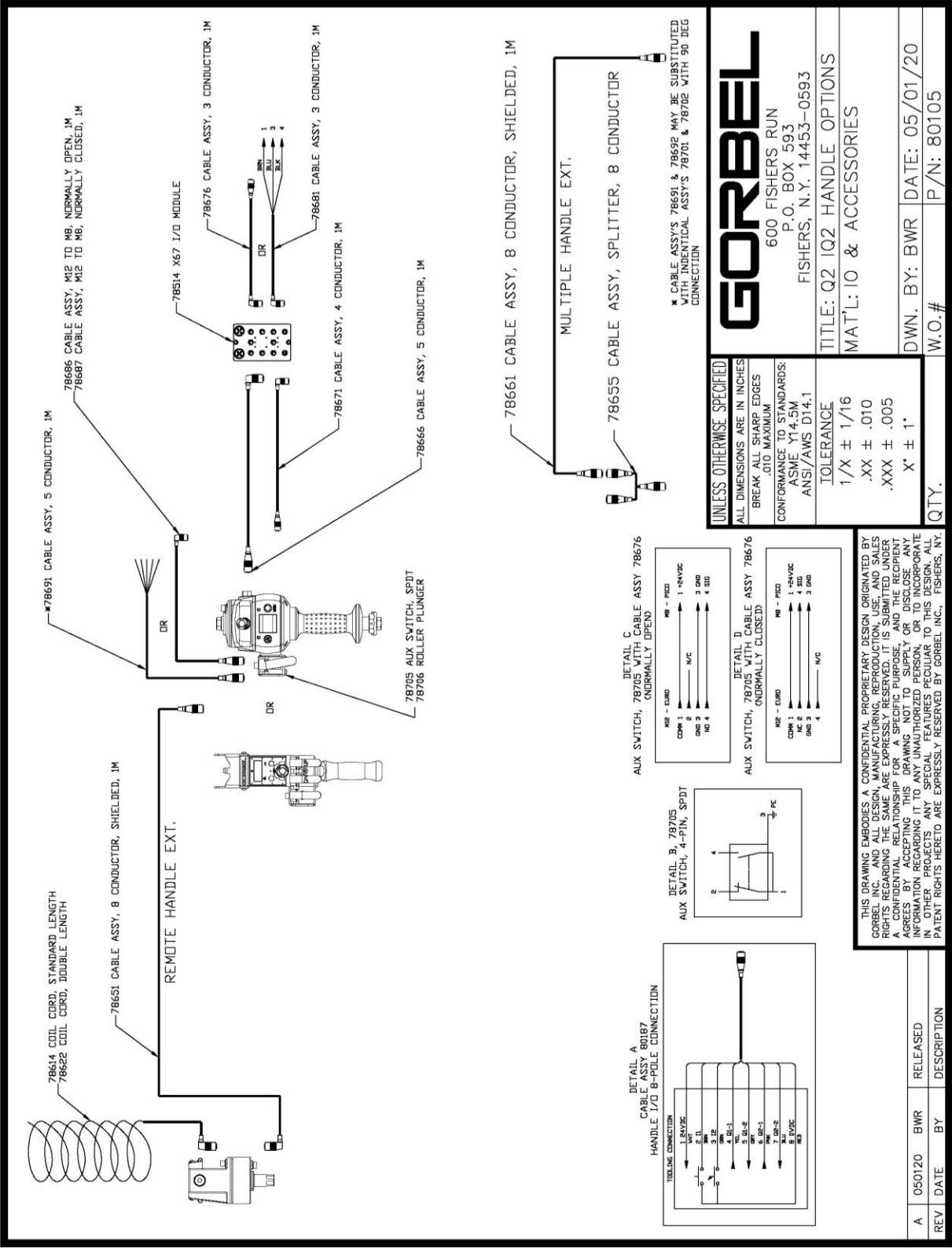


Diagram H. Q2-iQ2 Handle Configurations.

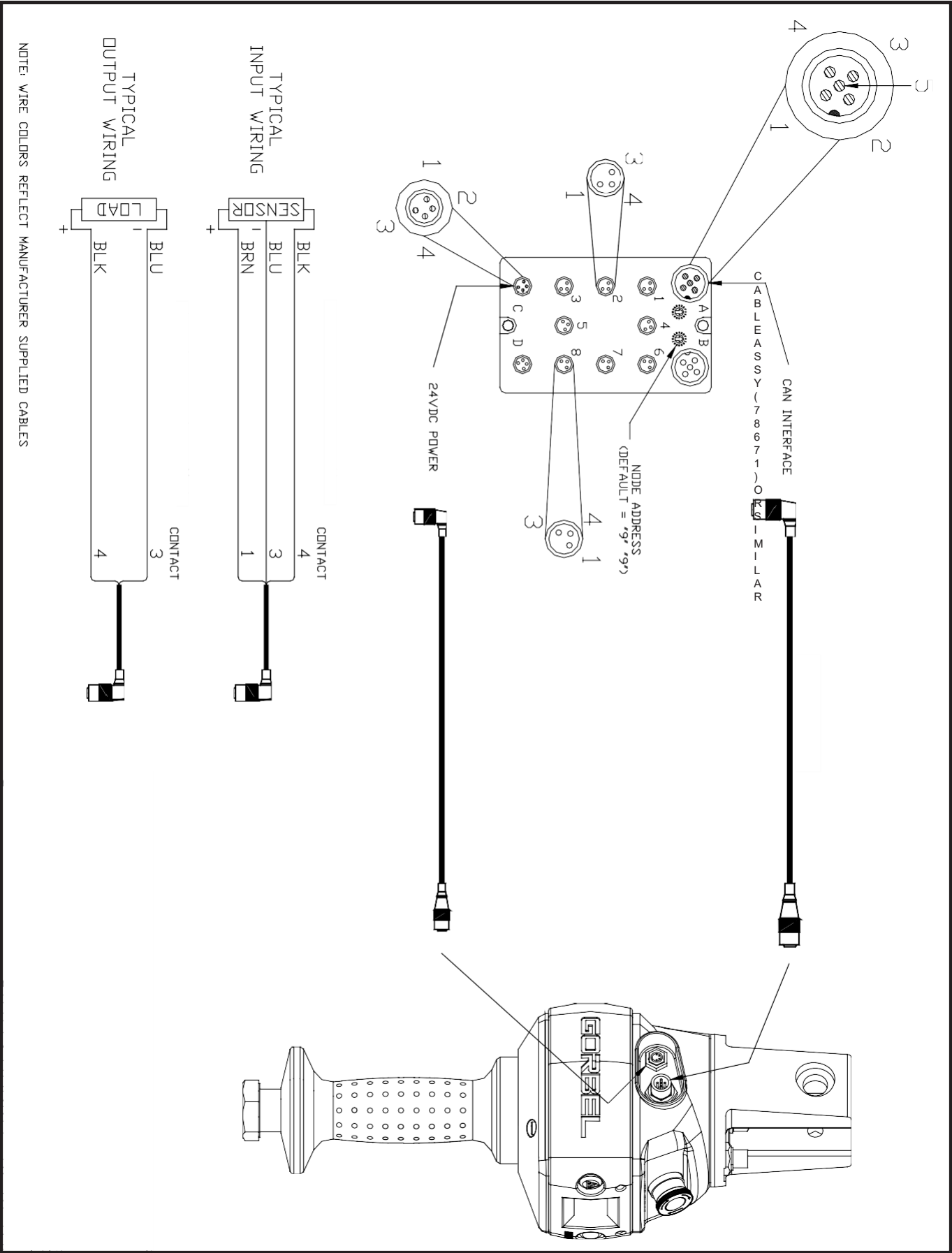
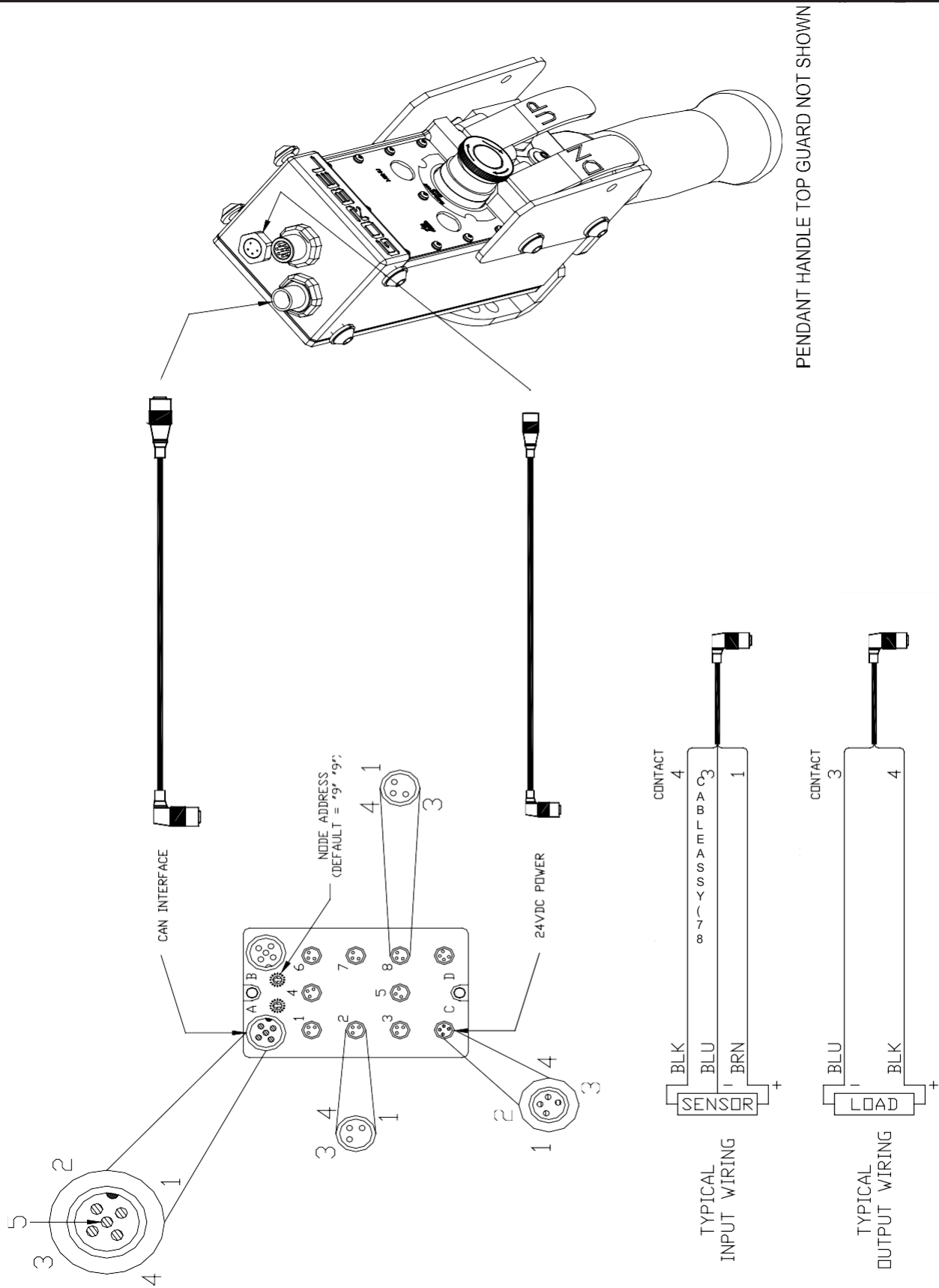


Diagram K. Handle IO Detail, Pendant Model.



Basic Troubleshooting

Failure	Possible Solution
There is no display on the OLED screen on the handle.	<ul style="list-style-type: none"> • Verify the correct AC power to the actuator. • Check the coil cord connections at both the handle and actuator. • Check the overall condition of the coil cord. Look for broken or exposed wiring. • Verify connections to Actuator PCB are all securely connected.
There is a fault or warning message displayed on the OLED screen on the handle.	<ul style="list-style-type: none"> • Clear the fault condition per the instructions on the OLED. • Reset the E-stop on the handle. • Cycle the AC power. Note: AC power must be disconnected from the actuator by unplugging the actuator from the AC power source or disconnecting power by using a circuit breaker or similar method.
LED on the control handle is on steady or flashing.	Refer to LED chart on page 44.
The unit will not raise or lower the load.	<ul style="list-style-type: none"> • Make sure you are in the RUN MODE. • Check the virtual limits settings if equipped with that option. • Check that you are not in an overloaded condition. • If you are wearing dark gloves, remove them and try the sliding handle again. • Check the coil cord for secure connections at both the handle and the actuator. • Check that the sliding handle grip or pendant handle levers move smoothly. • Check for any interference between the handle and any foreign objects, work surfaces, etc.
The unit is too slow or too fast.	<ul style="list-style-type: none"> • Adjust the speed in PROGRAM MODE. Check for speed reduction setting in virtual limits program if that option is selected.
The unit does not accelerate at the desired rate.	<ul style="list-style-type: none"> • Adjust the response in PROGRAM MODE. • Make sure you are not attempting to “snatch” the load. • Check the weight of the load. If you are close to the overload limit, try lifting at a reduced speed.
Unit will not raise or lower the load to the desired height.	<ul style="list-style-type: none"> • Check the virtual limits settings in PROGRAM MODE. • Check for wire rope damage. • Check whether or not you have an extended wire rope with a standard length coil cord. • Check to see if the wire rope has been modified (shortened) for any reason). • Check for any interference with foreign objects, tooling, work surfaces, etc.
The actuator is extremely noisy.	<ul style="list-style-type: none"> • Check the condition of the wire rope. • Check for any external damage to the actuator covers.
Float Mode does not function correctly.	Note: Refer to Technical Specifications, page 43, for maximum speed of G-Force® Float Mode. <ul style="list-style-type: none"> • Check that the blue LED on the handle is illuminated. • Check to see if the OLED screen indicates you are in Float Mode. • Check that Float Mode has not timed out because the system has not been used for 60seconds (default). • Ensure the unit is stable when Float Mode is initiated. • Check that the load data is reading accurately on the OLED screen. • Verify the bridge capacity. Check for excessive deflection in the bridge. • Check for obvious interference with the coil cord or handle.
Unit only goes in the up direction.	<ul style="list-style-type: none"> • Check the virtual limits settings if that option is active. • Check that the wire rope is not in a slack condition. • Check that no inhibit down motion inputs have been enabled. • Check for any obvious interference with the load or the handle. • Check that you are not at the lower limit of the system. • Check the coil cord connections at both the handle and actuator. • Check the overall condition of the coil cord. Look for broken or exposed wiring.
Unit only goes in the down direction.	<ul style="list-style-type: none"> • Check the virtual limits settings if that option is active. • Check that you are not at the upper limit of the system. • Check that no inhibit up motion inputs have been enabled. • Check that you are not in an overload condition. • Check for any obvious interference with the load or the handle. • Check the coil cord connections at both the handle and actuator. • Check the overall condition of the coil cord. Look for broken or exposed wiring.
E7219 / E4005 codes.	<ul style="list-style-type: none"> • The AC power is too low. If it approaches ~ 200VAC the system will not operate properly.
E501 / E11000 codes.	<ul style="list-style-type: none"> • Limit switch fault: <ol style="list-style-type: none"> a. Check for any mechanical binding that could engage both the upper and lower limit switches. b. Check and correct if the limit switch cable is connected to the interface board. • Check for bad electrical connection or shorted wires from the switches.

TROUBLESHOOTING (CONTINUED)

A system fault or warning message may appear on the OLED screen on the G-Force® handle along with flashing LEDs. The system fault or warning message can be one of the following:

1. **Command fault** - CPU detected condition while executing a command that results in a system shutdown. A message will displayed on the OLED screen with the Fault code.
2. **Command warning** — CPU detected condition that will allow the system to continue to operate. A message will display on the OLED screen until the condition message is cleared in Program Mode.
Note: The warning is cleared through Program Mode or cycling the power or E-stop if the warning condition has been resolved.
3. **ACOPOS Drive fault** — Drive detected condition that results in a shutdown. A drive fault message will display on the OLED screen with the Drive Fault code.

The recovery from these may require the cycling off/on of the E-stop switch or AC power source.

Note: The latter must be done by disconnecting the AC power cord, using an electrical disconnect device or a circuit breaker.

It is also possible that the fault clearance may require a more specific corrective action, such as replacing the wire rope, checking certain external input/ output modules or some other service-related task. If necessary, check with your Gorbel® distributor or contact Gorbel® After the Sales Service (ATSS) at 800-821-0086 for assistance.

For specific corrective action not listed above, refer to the optional Service Manual available from Gorbel.

TROUBLESHOOTING (CONTINUED)

LED Chart: The chart below shows the status of LED lights in different states.

Machine State	Sub-State (if applicable)	Color	OLED TEXT
E-Stop Engaged	--	No Light	E-STOP ENGAGED
Programming Mode		Amber	PROGRAMMING MODE
PLC (Command) Fault		Flashing Red	COMMAND FAULT ERROR NUMBER: ####
Drive Fault		Flashing Red	DRIVE FAULT ERROR NUMBER: #####
Warning		Amber	WARNING ####
Service Warning		Amber	SRV WARN <###> HRS
Service Mode		Amber	SERVICE MODE
Run Mode	Overload	Red	WARNING LIFT OVERLOAD
	Overspeed	No Light	FLOAT MODE OVERSPEED
	Handle Idle Timeout	Amber	IDLE TIME EXCEEDED
	Handle Mode	Green	RUN MODE HANDLE
	Float Mode	Blue	RUN MODE FLOAT
Ready Mode	--	No Light	G-FORCE READY TO LIFT
Startup Sequence	Before Ready Mode	No Light	SYSTEM BOOTING COMMUNICATION INITIALIZING POWERED ON
G-Force Initializing	--	No Light	G-FORCE INITIALIZING
User is connected to the unit with user interface*		Flashing Amber	HMI USER INTERFACE IS ACTIVE

*Service level 2 or OEM level 3 user is logged in.

TECHNICAL SPECIFICATIONS

Easy Arm® Q2 & iQ2 Actuator

Max Capacity	lb. [kg]	165 lb [75kg]	330 lb [150kg]	660 lb [300kg]	
Standard Crane Spans	ft [m]	6 [1.83], 8 [2.44], 10 [3.05], 12 [3.66], and 14 [4.28]			8 [2.44], 10 [3.05], 12 [3.66], and 14 [4.28]
Standard Crane Height Under Hook (HUH)	ft [m]	6 [1.83], 8 [2.44], 10 [3.05], and 11 [3.35]			
Degree of Arm Rotation		Primary Arm: 335° Secondary Arm: 325°	Primary Arm: 345° Secondary Arm: 325°	Primary Arm: 340° Secondary Arm: 310°	
Arm Rotation Friction Brakes		Yes			
Max Lift Speed Unloaded	ft/min [m/min]	195 fpm [59 mpm]	95 fpm [29 mpm]	45 fpm [14 mpm]	
Max Lift Speed Fully Loaded	ft/min [m/min]	120 fpm [37 mpm]	60 fpm [18 mpm]	40 fpm [12 mpm]	
Max Float Mode Lift Speed	ft/min [m/min]	110 fpm [34 mpm]	55 fpm [17 mpm]	40 fpm [12 mpm]	
Max Lift Range	ft [m]	11 [3.4]			
Max Lift Stroke	ft [m]	8 [2.4]			
Primary Voltage	VAC	220 +/- 10%			
Maximum Current	Amps	6			
Duty Cycle		H5	H5	H4	H3
Available Tooling Power		24VDC @ 0.5A			
Lifting Media		3/16" dia. 19x7 Preformed Stainless Steel Wire Rope			1/4" dia. 19x7 Preformed Stainless Steel Wire Rope
Operating Temperature Range	°F [°C]	41 – 122 [5 – 50]			
Operating Humidity Range (Non-Condensing)		35 - 90%			
Environmental Rating		NEMA 5			
Weight Display Accuracy		+/- 1% Rated Capacity			
UL/CSA Certified		Yes			
CE Certified		Yes			
Actuator I/O (iQ2 Model)					
Inputs, Type		8, Sinking			
Input Current @ 24 VDC		6ma			
Outputs, Type		4, FET			
Continuous Current/ Channel	Amps	0.5			
Module Max Current	Amps	0.5			
Handle with X67 I/O Module (iQ2 Model)					
Inputs, Type		8, Sinking			
Input Current @ 24 VDC		4mA			
Outputs, Type		8, FET			
Continuous Current/ Channel	Amps	0.5			
Max Current	Amps	0.5			
Handle with Standard I/O (Q2 Model)					
Inputs, Type		2, Sourcing			
Input Current @ 24 VDC		60mA			
Outputs, Type		2, Relay			
Max Switch Current	Amps	0.5			
Max Available Current	Amps	0.5			

WIRE ROPE INSPECTION

1. Frequent Inspection

The operator or other designated person should visually inspect all ropes at the start of each shift. These visual observations should be concerned with discovering gross damage, such as listed below, which may be an immediate hazard:

- distortion of the rope such as kinking, crushing, unstranding, birdcaging, main strand displacement, or core protrusion;
- general corrosion;
- broken or cut strands;
- number, distribution, and type of visible broken wires (see next section on rope replacement).

When such damage is discovered, the rope shall either be removed from service or given an inspection as detailed in the next section.

2. Periodic Inspection

The inspection frequency shall be determined by a qualified person and shall be based on such factors as expected rope life as determined by experience on the particular installation or similar installations; severity of environment; percentage of capacity lifts; frequency rates of operation; and exposure to shock loads. Inspections need not be at equal calendar intervals and should be more frequent as the rope approaches the end of its useful life.

A designated person shall perform periodic inspections. This inspection shall cover the entire length of rope. The individual outer wires in the strands of the rope shall be visible to this person during the inspection. Any deterioration resulting in appreciable loss of original strength, such as described below, shall be noted, and determination shall be made as to whether further use of the rope would constitute a hazard:

- points listed in previous section on Frequent Inspection;
- reduction of rope diameter below nominal diameter due to loss of core support, internal or external corrosion, or wear of outside wires.
- severely corroded or broken wires at end connections;
- severely corroded, cracked, bent, worn, or improperly applied end connections.

Special care should be taken when inspecting sections of rapid deterioration, such as the following:

- sections in contact with saddles, equalizer sheaves, or other sheaves where rope travel is limited;
- sections of rope at or near terminal ends where corroded or broken wires may protrude;
- sections subject to reverse bends;
- sections of ropes that are normally hidden during visual inspection, such as parts passing over sheaves.

WIRE ROPE MAINTENANCE

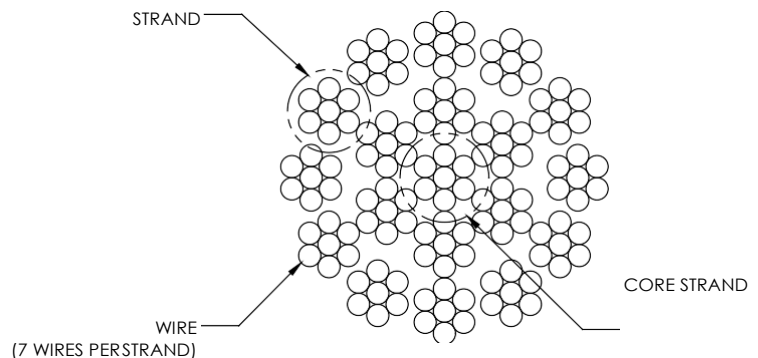
1. Rope should be stored to prevent damage, contamination, and deterioration.
2. Rope shall be unreeled or uncoiled in a manner to avoid kinking of or inducing a twist in the rope.
3. Before cutting rope, means shall be used to prevent unlaying of the strands.
4. During installation, care should be observed to avoid dragging of the rope in dirt or around objects that will scrape, nick, crush, or induce sharp bends.

CAUTION

Rope should be maintained in a well-lubricated condition. Gorbelt recommends using chain and cable penetrating oil for lubrication. Lubricant applied as part of a maintenance program shall be compatible with the original lubricant (PreLube 6). Lubricant applied shall be of the type that does not hinder visual inspection. Immediately after inspection, lubricant shall be applied before rope is returned to service. Those sections of rope that are located over sheaves or otherwise hidden during inspection and maintenance procedures require special attention when lubricating ropes. The object of rope lubrication is to reduce internal friction and to prevent corrosion.

WIRE ROPE REPLACEMENT CRITERIA

1. No precise rules can be given for determination of the exact time for rope replacement since many factors are involved. Once a rope reaches any one of the specified removal criteria, it may be allowed to operate to the end of the work shift, based on the judgment of a qualified person. The rope shall be replaced after that work shift, at the end of the day, or at the latest time prior to the equipment being used by the next work shift.
2. Removal criteria for the rope replacement shall be as follows:
 - in running ropes, 12 randomly distributed broken wires in one lay or four broken wires in one strand in one lay (**diagram L**);
 - one outer wire broken at the contact point with the core of the rope, which has worked its way out of the rope structure and protrudes or loops out from the rope structure;
 - wear of one-third the original diameter of outside individual wires;
 - kinking, crushing, birdcaging, or any other damage resulting in distortion of the rope structure;
 - evidence of heat damage from any cause;
 - reductions from nominal diameter greater than 1/64" (.4 mm) for 1/4" (6.35 mm) diameter rope or 3/16" (4.76 mm) diameter rope.
3. Broken wire removal criteria applies to wire rope operating on steel sheaves and drums. However, results of internal testing have shown that rope replacement follows the same criteria regardless of sheave or drum material.
4. Attention shall be given to end connections. Upon development of two broken wires adjacent to a socketed end connection, the rope should be resocketed or replaced. Resocketing shall not be attempted if the resulting rope length will be insufficient for proper operation.
5. Replacement rope and connections shall have strength rating at least as great as the original rope and connection furnished by the hoist manufacturer. A rope manufacturer, the hoist manufacturer, or a qualified person shall specify any deviation from the original size, grade, or construction.



WIRE ROPE REPLACEMENT INSTRUCTIONS

WARNING

Wire rope replacement is to be performed by qualified maintenance personnel only.

Removal of Existing Wire Rope:

Make sure the replacement rope is the same length and diameter (3/16" or 1/4")

1. A. Ensure there is no load on handle, weighted load hook (pendant) or end effector.
- B. If using slow down setting, clear (reset) on handle or pendant handle menu screen. If using virtual limits, clear (reset) on handle or the pendant handle's menu screen.
- C. Remove end tool.
 - a. Slide handle/G360™ (**diagram M**): Using a 19mm

socket, remove the M12 jam nut from the handle's socket

head shoulder screw, then use an M8 hex wrench and remove (unthread) socket head 16mm shoulder bolt from handle. This will detach it from wire rope thimble. Set handle down on bench or table to support it and not stretch the coil cord.

- b. Pendant handle (**diagram N**): Remove the weighted

hook or end effector from rope by removing the cotter pin and clevis pin and set aside.

2. Using a 3mm hex wrench, completely remove the four button head screws on actuator front cover (shorter blue cover).
3. Remove front cover from actuator and set aside upward to use as a bowl to hold future parts. **Note:** Be careful not to contact circuit board.
4. Going in the down direction, unspool rope from drum using jog down button while keeping tension on wire rope with other hand wearing a glove. Continue until lower limit is engaged.
5. Face the unit with circuit board on your left and wire rope on the right.

Note: The next two steps must be done at the same time.

6. Using a long screwdriver or hex wrench, reach through front of actuator and locate upper socket head cap screw head facing you next to the lower limit switch. Fully push the screw in until it cannot move anymore (it is spring loaded). Keep pressure on it (**diagram O**). Simultaneously apply force to your right to take the unit out of slack. You will hear the limit switch click when it is pushed enough.

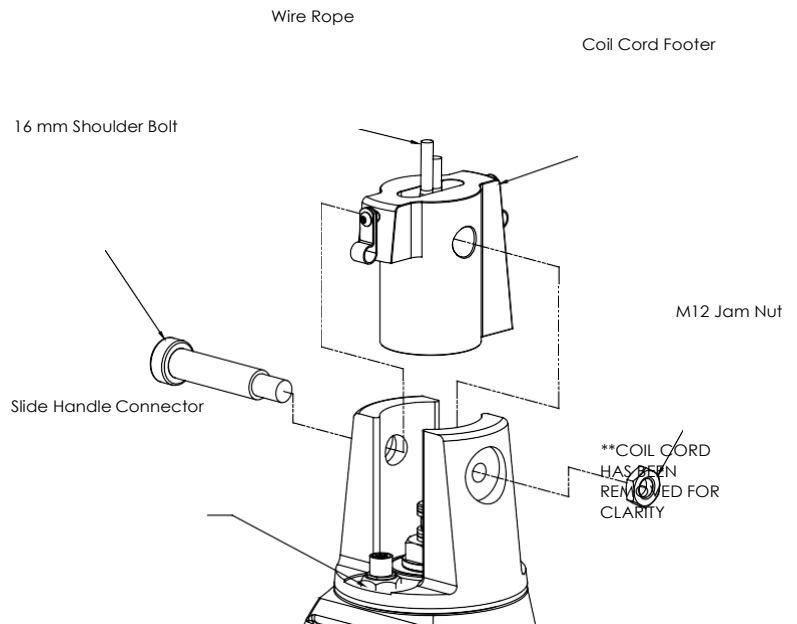


Diagram M. Removing wire rope from Slide Handle/G360™.

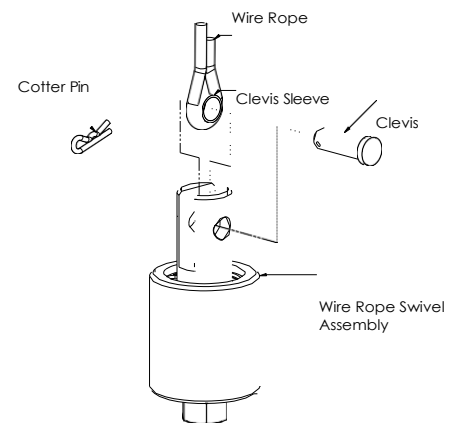


Diagram N. Removing wire rope from Pendant Handle.

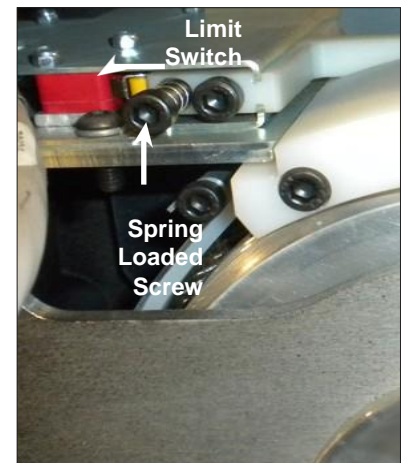


Diagram O. Locate socket head cap screw head and fully push it in until it can not move anymore.

WIRE ROPE REPLACEMENT INSTRUCTIONS (CONTINUED)

Removal of Existing Wire Rope (Continued):

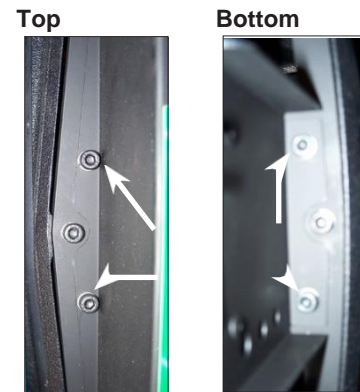
7. Using your right hand, press the jog down button while watching the drum rotate two full turns in the clockwise direction. The drum should stop automatically with the wire rope retainer visible at the 12 o'clock position on the drum.
8. From the limit switches is a gray colored lead that plugs into the circuit board. Its connected location is on the top side of the circuit board labeled "limits". Gently pull out the plug lead to disconnect plug from board (**diagram P**).
9. Using 13mm open-end wrench, loosen, not remove, the two flange nuts and remove reinforcement bracket (330# units only).
10. Using a 4mm hex wrench, remove four M5 socket head cap screws that fasten the swiveling circuit board bracket to the front support plate. Two screws are located on the left side and two are on the right side of bracket. Place screws in plastic front cover. Swing bracket downwards carefully (**diagrams Q and R**).
11. Using an M5 hex wrench, remove two M6 socket head cap screws from the drum gates. Slide the unthreaded gate out towards you. Place gate and hardware in front cover (**diagram S**).
12. Using an M3 hex wrench, remove the two M5 socket head cap screws from the rope retainer and slide retainer off of rope end

towards you. Place retainer and screws in front cover (**diagram T**).

13. Grasp wire rope with right hand where it exits actuator. Keep rope from bending while pushing rope to the left to unseat the stop sleeve from the anchor channel. If this does not work, use a medium screwdriver (flat) sliding it upward between rope and drum to progressively pry rope out of anchor channel while still pushing up on rope. Remove rope from actuator through opening at bottom once unseated.
14. Remove one M12 shoulder bolt from one of the knuckle pulleys (**diagram U**) and M6 and M12 shoulder bolts from pulley block (**diagram V**) at end of arm. With the pulley block removed, remove the three M4 screws holding the halves of the block together. The old wire rope can now be removed completely.



Diagram P. Gently pull out the grey limit switch wiring lead to disconnect plug from board.



Diagrams Q & R. Remove four M5 socket head cap screws (two on top, two on bottom) that fasten the swiveling circuit board bracket to the front support plate.

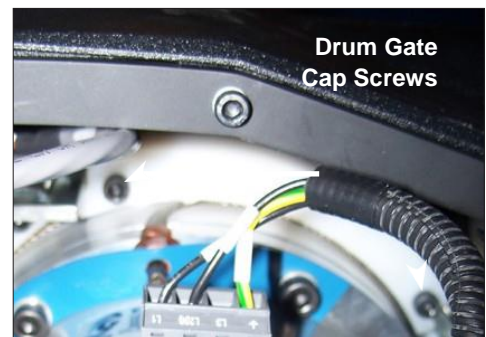


Diagram S. Remove two M6 socket head cap screws from the drum gates.

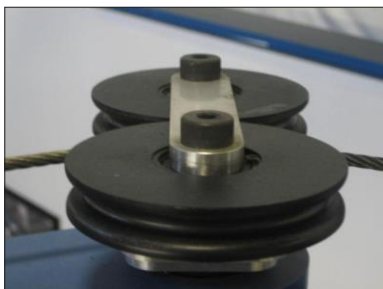


Diagram U. Knuckle pulley.



Diagram V. Pulley block at end of arm.



Diagram T. Remove the two M8 socket head cap screws and slide retainer off of rope end towards you. Configuration may vary depending on capacity.

WIRE ROPE REPLACEMENT INSTRUCTION (CONTINUED)

Installation of New Wire Rope:

1. Grasp anchor end of rope (not thimble) and make a crimp in gloved hand approximately three inches from the end (try to kink rope to make a bend radius).
2. Insert the rope into the actuator up through the wear ring using right hand while seating the end crimp into the locker with your left hand. This will involve seating the rope into the radius channel afterwards.
3. Pull down on the rope at the exit location of the actuator to seat the crimp into the locker fully.
4. Install the rope retainer plate over the rope end and install the two M5 socket head cap screws and lockwashers. Torque hardware to fully compress lockwashers.
5. Ensure that rope is seated in radius channel and install rope gate back in the unit making sure the rope guide (cutout) side is inserted first and the ends are sliding on guide rails freely. Fasten the rope gate assembly together using the previously removed hardware. Torque hardware to compress lockwashers.
6. Install (slide) the reinforcement bracket studs into channels and tighten the two 13mm flange nuts (330# units only). Next, swing circuit board bracket closed towards plate and fasten to plate using the four previously removed socket head cap screws and lockwashers. Torque hardware to compress lockwashers.
7. Plug limit switch lead into circuit board "limits" receptacle making sure retention tab on plug is facing you.
8. Using a clean cotton cloth wrapped around rope loosely near actuator entrance, pull down on rope and press jog up button allowing rope to pass through cloth cleaning it as it is being wrapped onto the drum. Continue loading rope onto drum using jog button until three drum revolutions are completed.
9. Install front cover onto actuator making sure all four screws are aligned with tabs before threading.
10. If using coil cord, make sure rope is inserted down through the middle of the coils.
11. Attach wire rope to handle, weighted hook, or end effector in reverse order of disassembly.
12. Reassemble pulley block with new wire rope fed through it and reinstall block at end of arm. Reinstall pulleys at arm knuckle with new wire rope fed between them.
13. Reset virtual limits and/or slow down settings.

WIRE ROPE REPLACEMENT INSTRUCTIONS (CONTINUED)

660 LB. EASY ARM UNITS ONLY:

Due to actuator orientation, it may be necessary to tilt the actuator to make accessing the internals of the unit easier. Refer to **diagram W** for details regarding procedure and locations.

1. Temporarily disconnect signal cable from actuator.
2. Loosen M8 nuts closest to wire rope opening.
3. Pull pin on actuator swivel and tilt down one notch only.
4. Remove top rollers and one knuckle pulley.
5. Remove end pulley bolt.
6. Reverse procedure once rope is changed.

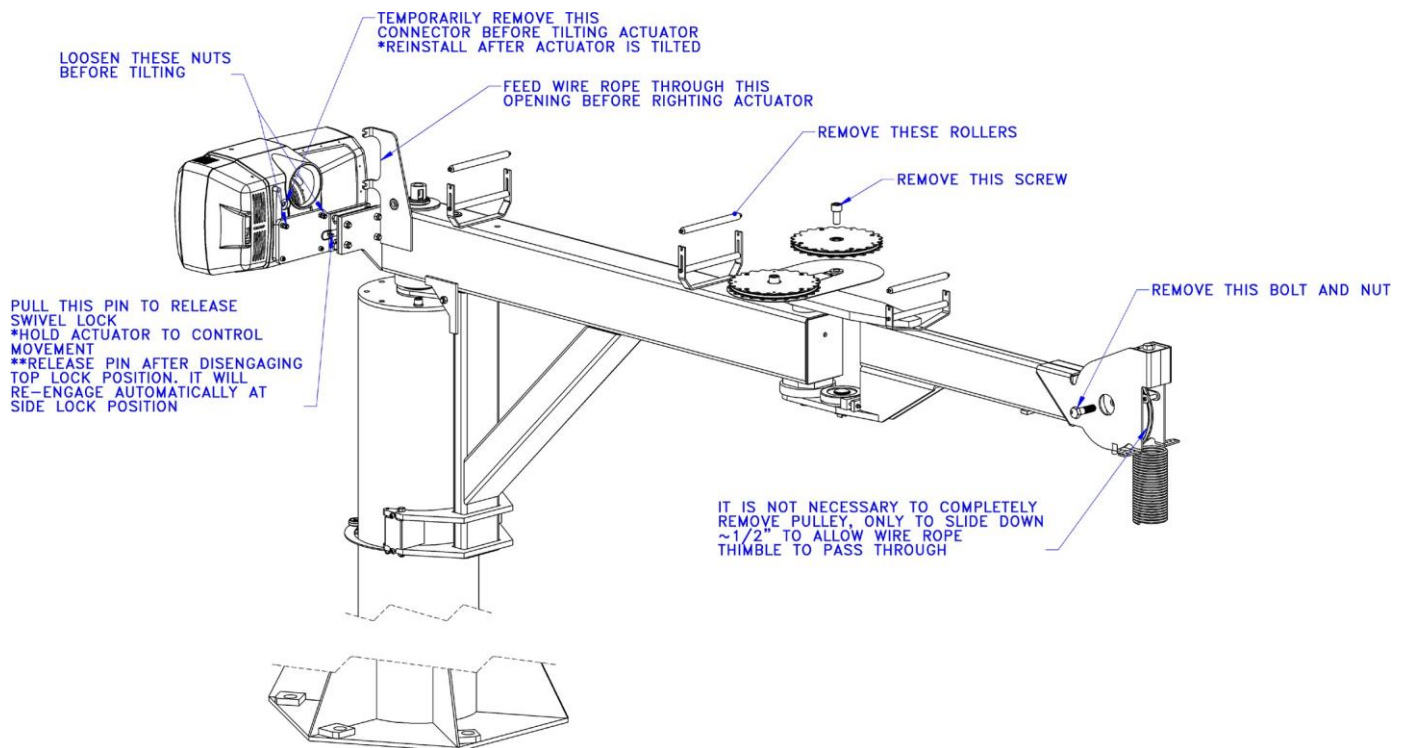


Diagram W. 660# Easy Arm wire rope replacement.

SLACK SPRING ADJUSTMENT

1. Turn off the power to unit by unplugging or locking out at power source. Remove the rear cover from the longer side of the Easy Arm® by using an M3 hex wrench to remove the M5 button head cap screws and lockwashers. Carefully slide the rear cover away from the actuator casting.
2. Locate the slack spring over the motor, next to the housing (**diagram X**). Slack spring is held in place by a bracket on one side and an eyebolt on the other. To adjust the slack spring, use an M10 (or 7/16") wrench to loosen the inside nut on the eyebolt and then tighten the outside nut while holding the eyebolt stationary to prevent it from spinning with the nut (**diagram Y**). It should only take a few turns to increase the spring force.

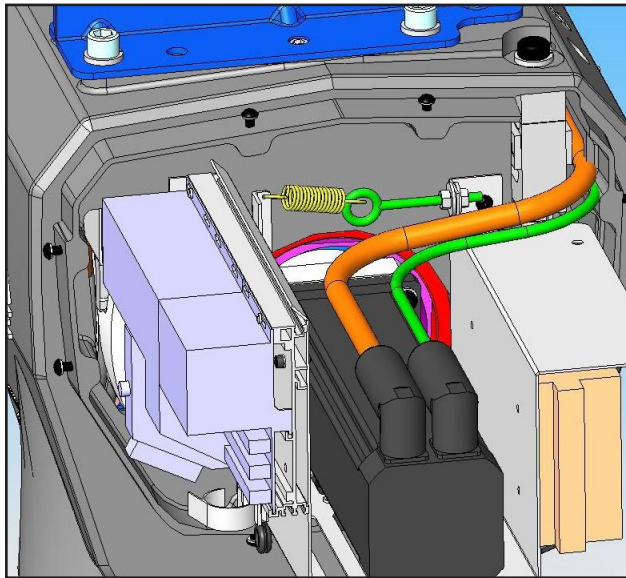


Diagram X.

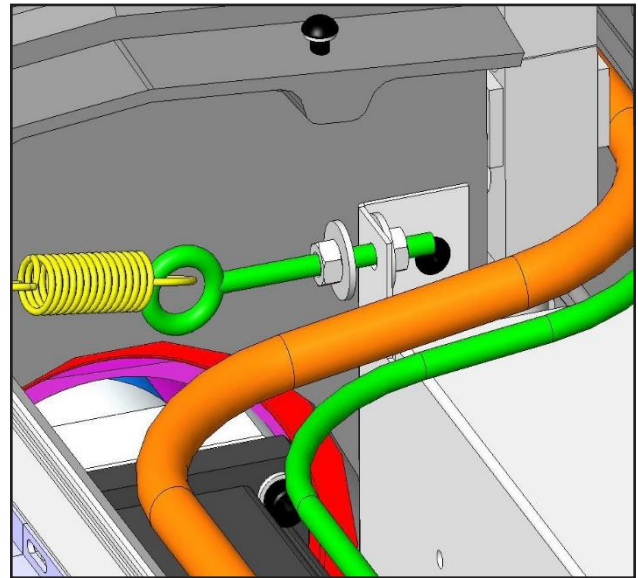


Diagram Y.

3. If the spring is too tight, you might experience some chatter when trying to move an unloaded G360™ down from the top of its stroke. If possible test this before putting the cover back on.
4. After adjusting the spring, remember to tighten the inside nut back down to ensure that the slack spring stays in place after it has been adjusted.
5. Replace the rear cover by carefully sliding the rear cover over the motor, CPU and power supply and aligning holes with brackets attached to the actuator casting. Install the M5 button head cap screws and lockwashers.

RECOMMENDED SPARE PARTS KITS

Here is a list of the Spare Parts Kits we recommend. We encourage you to have spare parts on hand to limit the potential downtime if your unit experiences issues. To order any of these kits, please consult your authorized Gorbel® distributor.

You will have to know your system specification such as Capacity, Trolley Saddle Height, Height Under Hook and Span (if applicable to your unit).

Level One Kit includes:

One Wire Rope Assembly
One Coil Cord Assembly

Level Two Kit includes:

One Wire Rope Assembly
One Coil Cord Assembly
One Hardware Kit

Level Three Kit includes:

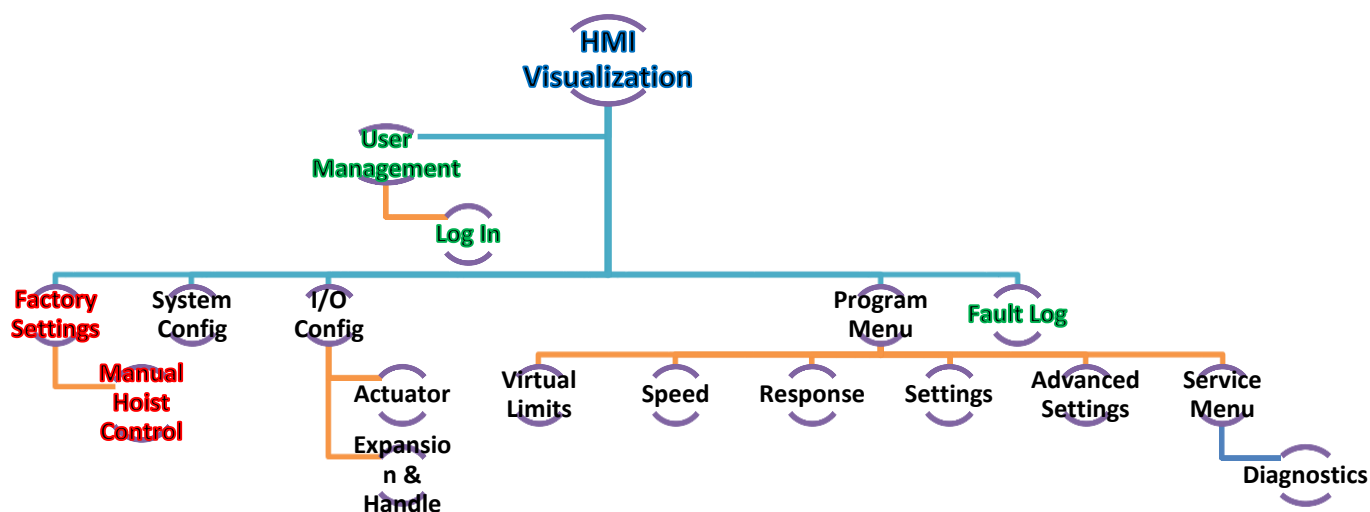
One Wire Rope Assembly
One Coil Cord Assembly
One Hardware Kit
One Swivel Kit*

* If your system is equipped with a Suspended Pendant Handle you can use the Level Two Kit because you will not need the Swivel Kit.

- All kits can be used on either G-Forces or Easy Arms regardless of their capacity.

APPENDIX A: HUMAN MACHINE INTERFACE (HMI) EXPLANATION

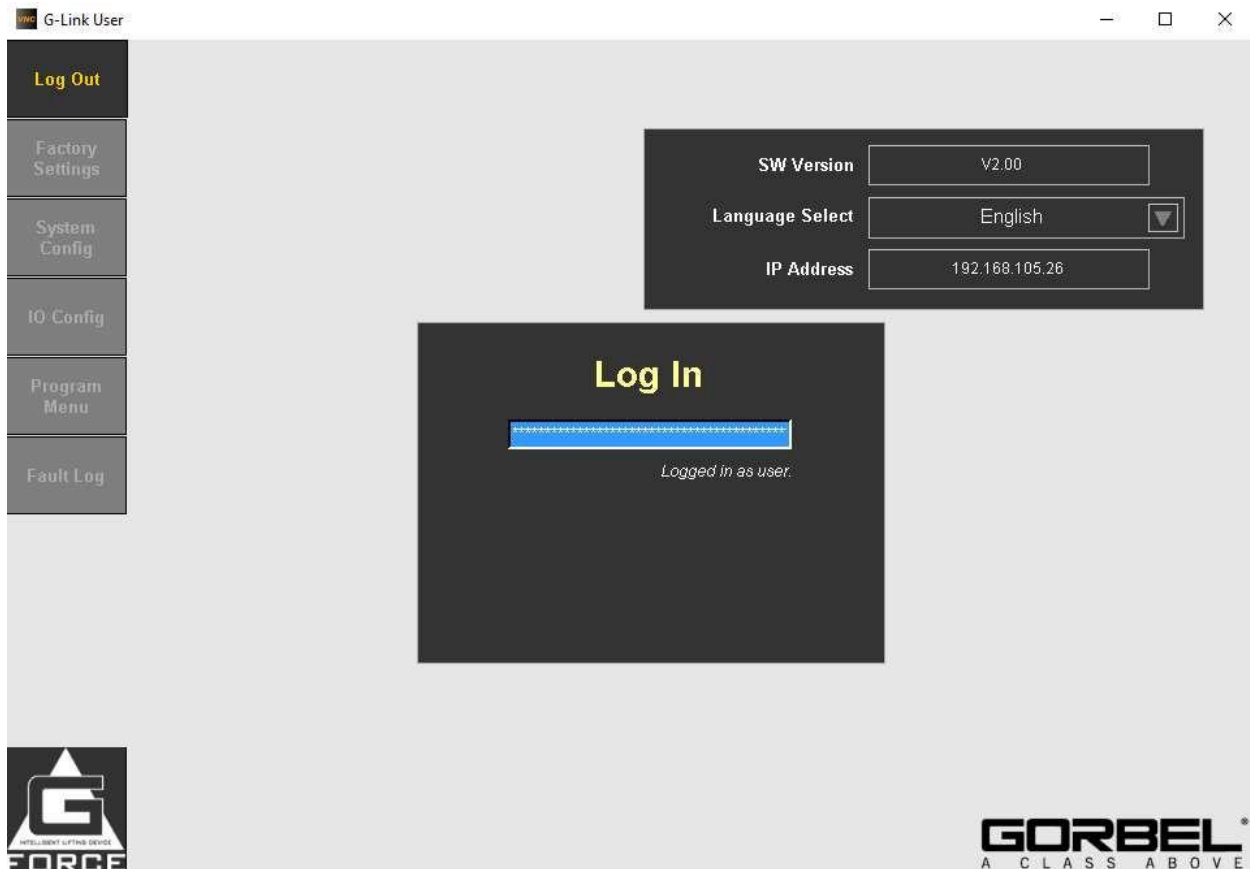
Gorbel's G-Force® Q2 and iQ2 Intelligent Lifting Devices were designed with G-Link™ Smart Connect technology. G-Link enables units to transmit data locally or anywhere with internet access. It also allows users to set parameters remotely from a desktop, laptop, or tablet. The following pages take you through the options available to you on each screen in this Human Machine Interface (HMI).



APPENDIX A: HMI EXPLANATION (continued)

Page	Sub Page	Content
User Management	--	Log In Page
Factory Settings	--	Calibrate Factory Test Manual Control Page
System Config	--	Manual Configuration Import/Export Config IP Address settings
I/O Config	Actuator	Set Actuator I/O, standard presets and clear all previous settings
	I/O & Handle	Set I/O and Handle settings, Presets and clear settings
Program Menu	Virtual Limits	Set Upper/Lower limit, Upper/Lower Slowdown, Upper Resume and Slowdown Speed
	Speed	Set Max Actuator Speed, Up/Down Toggle and Jog speed
	Response	Set Handle Response levels
	Settings	Weight Display, Idle Time out, Float Mode, Unload Stop, Anti-Recoil, Overload Limit, Operator Force, Sensitivity can be set
	Advanced Settings	Multiple FM tool and load weight, anti-drop tool weight and Auto home position
	Service Menu	Set Service warning, view system information and set operating cycles
Fault Log	--	Refresh all faults and warnings
Manual Hoist Control	--	Redirected from Factory Settings Page Manual control of the hoist

APPENDIX A: HMI EXPLANATION (continued)



Feature	Description
Log in	If you tap on the blue box, the user is prompted to enter a password to change the access level of the HMI. By default, passcode level “1” allows access to the fault log, passcode level “2” allows access to everything except Factory settings.
SW Version	This will show the Software Version number of the PLC/Actuator software.
Language Select	This is a pulldown menu that allows the user to select the language of the HMI.
IP Address	This read-only field will show the IP Address of the PLC/Actuator.

APPENDIX A: HMI EXPLANATION (continued)

The screenshot displays the G-Link User HMI interface. On the left is a vertical menu with options: User Management, Factory Settings, System Config, IO Config, Program Menu, Fault Log, and Manual Hoist Control (highlighted in yellow). The main area is divided into two panels. The 'Unidirectional' panel on the left has input fields for Speed (10000) and Acceleration (20), two large buttons labeled 'UP' and 'DOWN', a 'Cyclic Mode Preset' dropdown menu set to 'Select...', and an 'Apply' button. The 'Cyclic Operation' panel on the right has input fields for Speed (0), Stroke 1 (in) (0), Stroke 2 (in) (0), Period (0), Pause Time (0), and Duration (0). It also features 'Start' and 'Stop' buttons, a 'Counts' display showing 0, and a 'Reset' button. At the bottom left is the 'G FORCE' logo, and at the bottom right is the 'GORBEL A CLASS ABOVE' logo.

Feature	Description
Unidirectional	
Speed	This allows you to select the speed at which you'd like the unit to move in.
Acceleration	This allows you to select the acceleration at which you'd like the unit to move in.
Up	This button jogs the unit upwards.
Down	This button jogs the unit downwards.
Cyclic Mode Preset	This option allows you to select a pre-defined cyclic mode operation.
Apply	After choosing a cyclic mode preset, "Apply" updates the options in the "Cyclic Operation" section.
Cyclic Operation	
Start	After choosing a cyclic mode preset, this will initiate the cyclic operation.
Stop	This will stop the cyclic operation.
Count	This will increment by 1 every time a cycle is complete.
Reset	This will reset the Count to zero.

APPENDIX A: HMI EXPLANATION (continued)

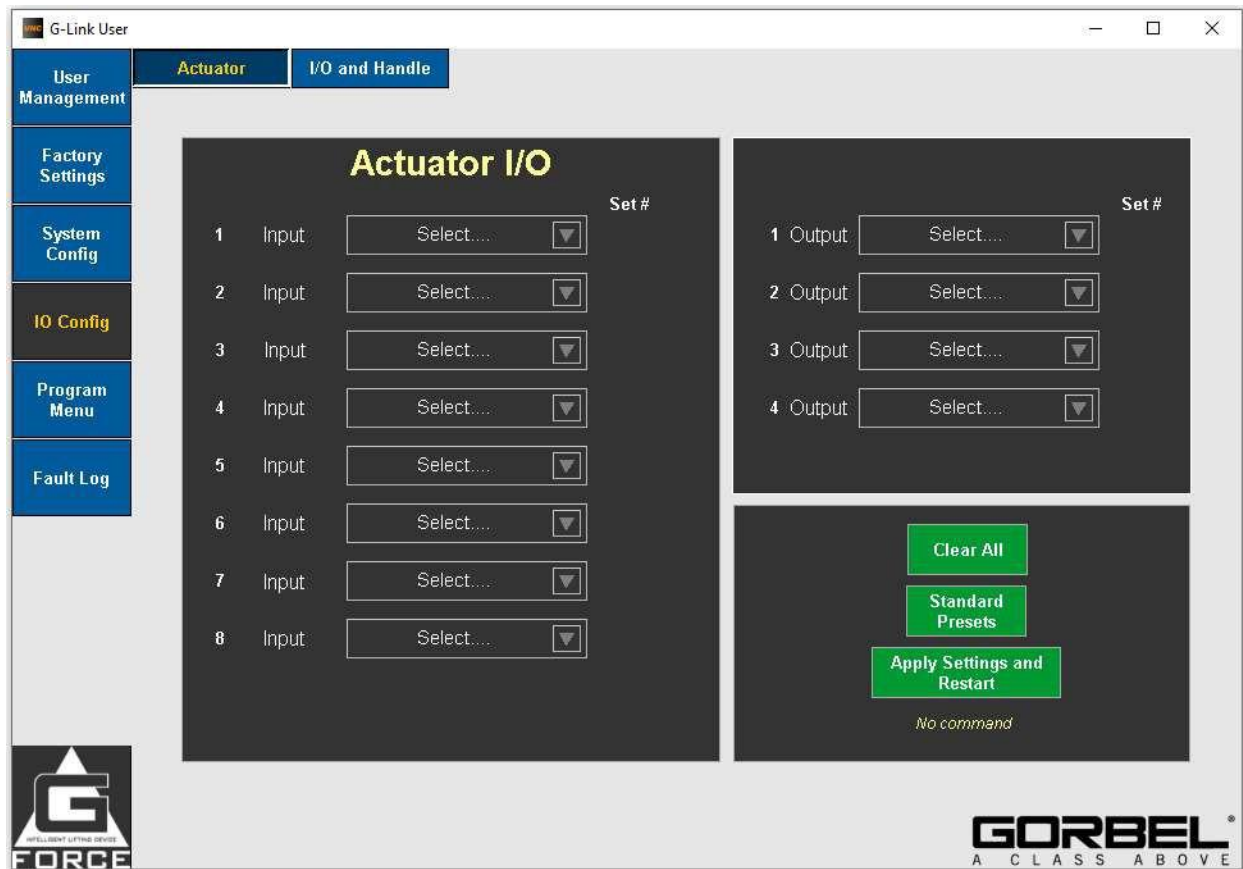
The screenshot displays the G-Link User HMI interface. On the left is a vertical menu with options: User Management, Factory Settings, System Config (highlighted), IO Config, Program Menu, and Fault Log. The main area is divided into two panels. The left panel, titled 'Manual Configuration', contains input fields for Serial Number (000000-1-A-PiQ), I/O Type (PLC), Type (Select...), Span (Select...), and Capacity (Select...). Below these are buttons for 'Factory Default', 'Apply Settings and Restart', and a 'New IP Addr.' field with a 'Confirm' button. A message states 'Changes will be applied on next restart!!!'. At the bottom is a 'Handle Menu Enabled' button. The right panel, titled 'Import/Export Configuration', shows a list of files with 'factory_600305-1-A.xml' selected, displaying a date of 2000-05-30 13:50:11. It includes buttons for 'Import From Selected', 'Export To Selected', 'Delete Selected', 'Create New', and 'USB'. Below this is a 'Unit Select' section with a dropdown menu currently set to 'Imperial'. The bottom of the screen features the GORBEL logo with the tagline 'A CLASS ABOVE'.

Feature	Description
Manual Configuration	
Serial Number	Manually enter the serial number of the unit
I/O Type	This automatically detects the I/O type of the unit
Type	G-Force® or Easy Arm®.
Span	If Easy Arm®, you select the span of it.
Capacity	Capacity of the unit.
Factory Default	This will reset the configuration to the factory default.
Apply Settings and Restart	This should be pressed when the configuration has been selected to ensure it was saved on the PLC.
New IP Addr.	Enter the new IP address of the G-Force®. (E.g. Factory IP Address: 192.168.105.26) Click Confirm to assign the IP address. NOTE: After clicking confirm, the VNC will disconnect, and one will need to reconnect using the newly set IP address.
Handle Menu Enabled/Disabled	Toggle to allow access to the G-Force® Handle Menus.

APPENDIX A: HMI EXPLANATION (continued)

Import/Export Configuration	
Create new	Once a manual configuration has been entered, you can select the input box (next to Create New) to type in the name of the .xml file, and then press on Create New to save a new .xml file with the configuration.
Import from Selected	Once multiple .xml files are made, scroll using the arrow buttons to choose one to import back to the PLC.
Export to Selected	To change the configuration of a .xml file, set the configuration desired from the Manual Configuration section, scroll using the arrow buttons to choose the .xml file to overwrite, and then press Export to Selected.
Delete Selected	To delete any .xml file (except factory as it cannot be deleted), scroll using the arrow buttons to choose the .xml file then press on Delete Selected.
USB/USER	This toggles the active .xml file configuration storage location. If a USB is connected to the PLC, with a pre-set configuration, pressing on USB would redirect to that configuration storage on the USB. The active storage location is indicated by the button with Dark Text .
Unit Select	
Unit Select	Choose the units of the HMI (between imperial and metric)

APPENDIX A: HMI EXPLANATION (continued)

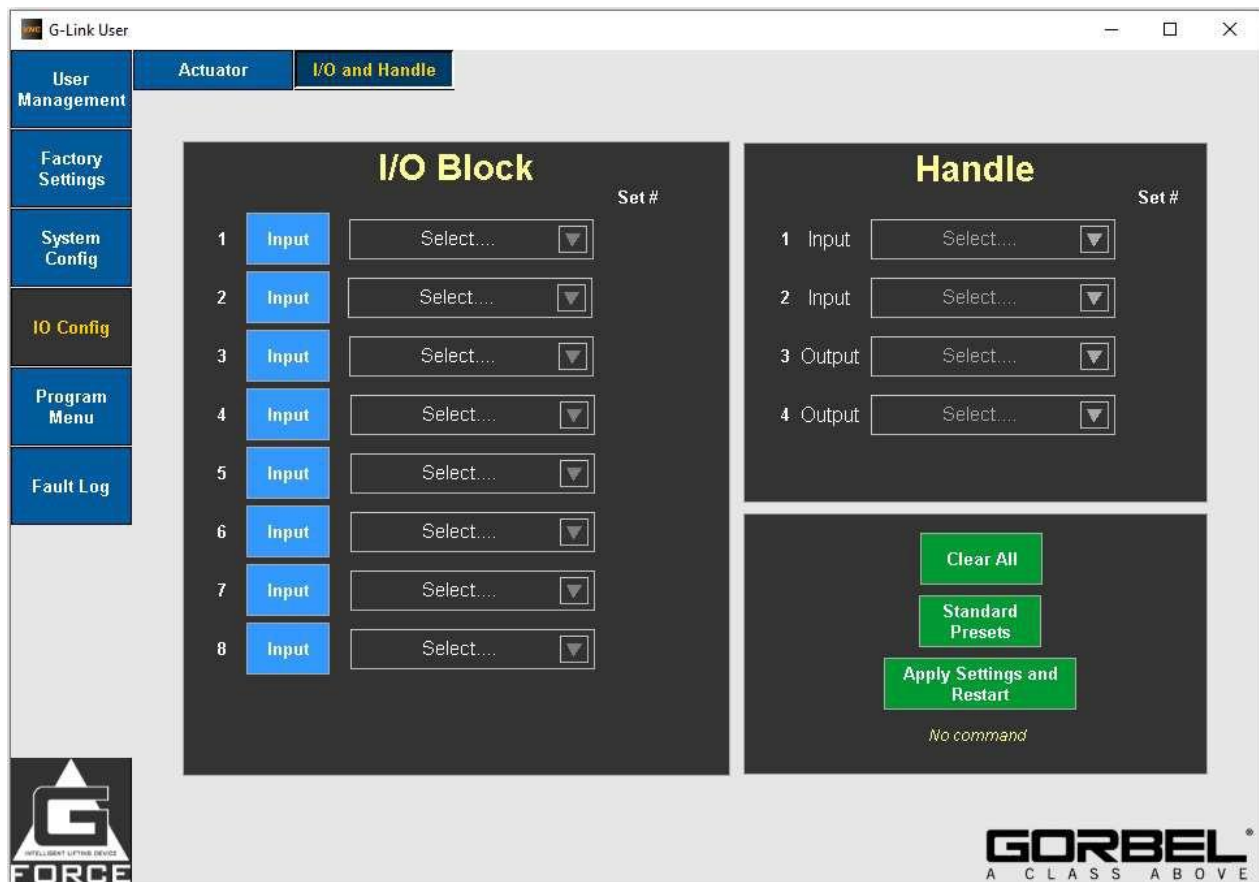


Feature	Description
Actuator I/O	
The Actuator I/O will come with 8 inputs and 4 outputs. iQ2 units will have Actuator I/O and/or an I/O Block. Q2 units will have Handle I/O to configure.	
Inputs	
AD Clamp	Anti-Drop Clamp input signal. This input is typically wired to a clamp request pushbutton.
AD Unclamp	This input is typically wired to an unclamp request pushbutton. When the input is on, an Output (set by user) turns on only if Anti-Drop algorithm determines the suspended load is at or below the set weight (ANTIDROP TOOL WT).
Auto-Home	When this input is toggled (momentarily turned on then off again), the G-Force® automatically travels to the set home position in the vertical travel.
Dual Float	When the G-Force® is in float mode, this input allows switching from one pre-programmed load weight to another.
IO Config Settings	
Clear All	Clears all the inputs and outputs.
Standard Presets	Resets the I/O to factory default.
Apply Settings and Restart	This must be pressed anytime the configuration is changed for changes to take effect.

APPENDIX A: HMI EXPLANATION (continued)

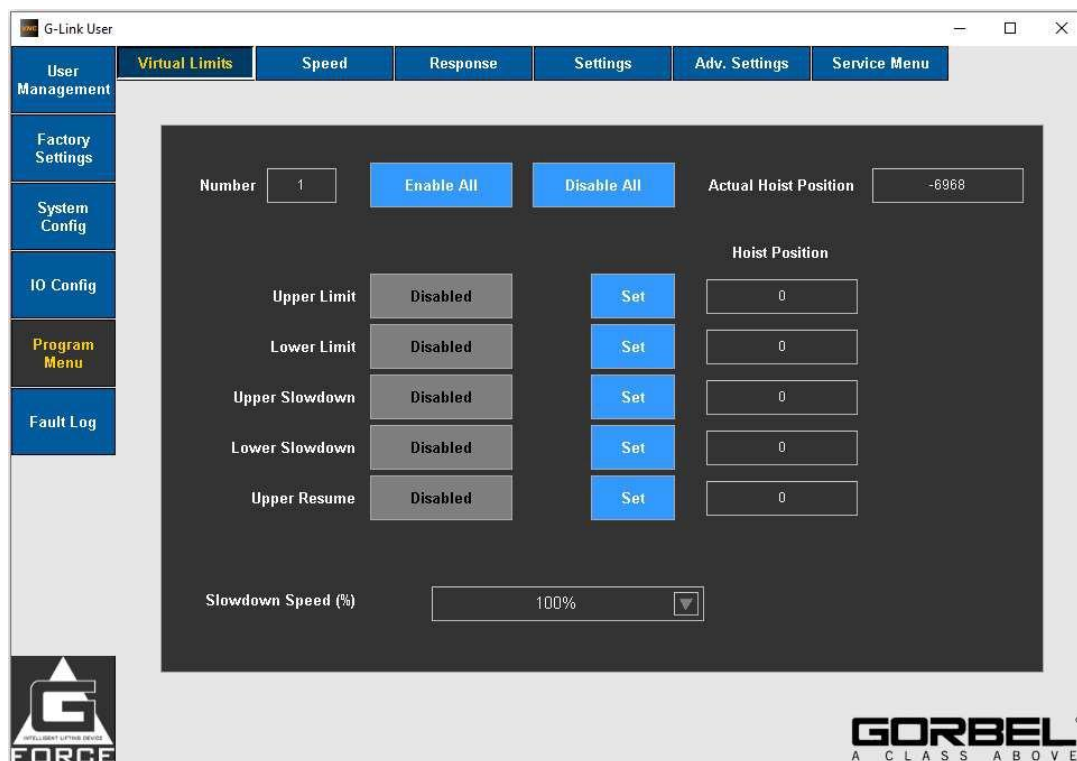
AD Clamp/Unclamp	When this input is off, it's a clamp signal, when it's on, it's an unclamp signal if the weight is below the set weight.
Multi-Zone VL	When this input is turned on, the G-Force® switches to a second independent set of virtual limits.
Inhibit Motion	If this input is on, it inhibits motion in both directions.
Remote Float	This is a momentary input to activate float mode.
Toggle Speed	This is a maintained input, and when it's ON it switches the speed to a pre-set one (from the program menu page)
Inhibit Motion Up	This is a maintained input, and it inhibits motion up if it's ON.
Inhibit Motion Down	This is a maintained input, and it inhibits motion down if it's ON.
Jog up	Maintained input. When this is on, the unit jogs upwards at a preset speed (from the program menu page)
Jog Down	Maintained input. When this is on, the unit jogs downwards at a preset speed (from the program menu page)
Float mode Quit	This is a momentary input to deactivate float mode.
External Control Input	When this input is on, a selected output on the PLC/Expansion block input/output module is on and vice versa.
Outputs	
Clamp Signal	This output is typically wired to actuate the clamping mechanism of an end effector tooling. It turns on when AD Clamp input is on and remains latched on when the input is released.
Unclamp signal	This output is typically wired to actuate the unclamping mechanism of an end effector tooling. It turns on when unclamp Input is on and the Anti-Drop algorithm determines the suspended load is at or below the set weight (ANTIDROP TOOL WT).
Slack Detection	If the unit experiences slack, this output turns on.
Run Mode	If the unit is in motion in any mode, this output is on.
Float Mode	If the unit is in float mode, this output turns on.
Upper Limit	If the unit reaches the upper limit, this output turns on.
Lower Limit	If the unit reaches the lower limit, this output turns on.
OPS Active	If the OPS is active, when the operator presence is detected, this output turns on.
E-stop Pressed	If E-stop is engaged, this output turns off, otherwise it is always on.
Fault Indicator	If there is a fault (error) in the unit, this output turns on.
Apply Settings and Restart	This must be pressed anytime the configuration is changed for changes to take effect.

APPENDIX A: HMI EXPLANATION (continued)



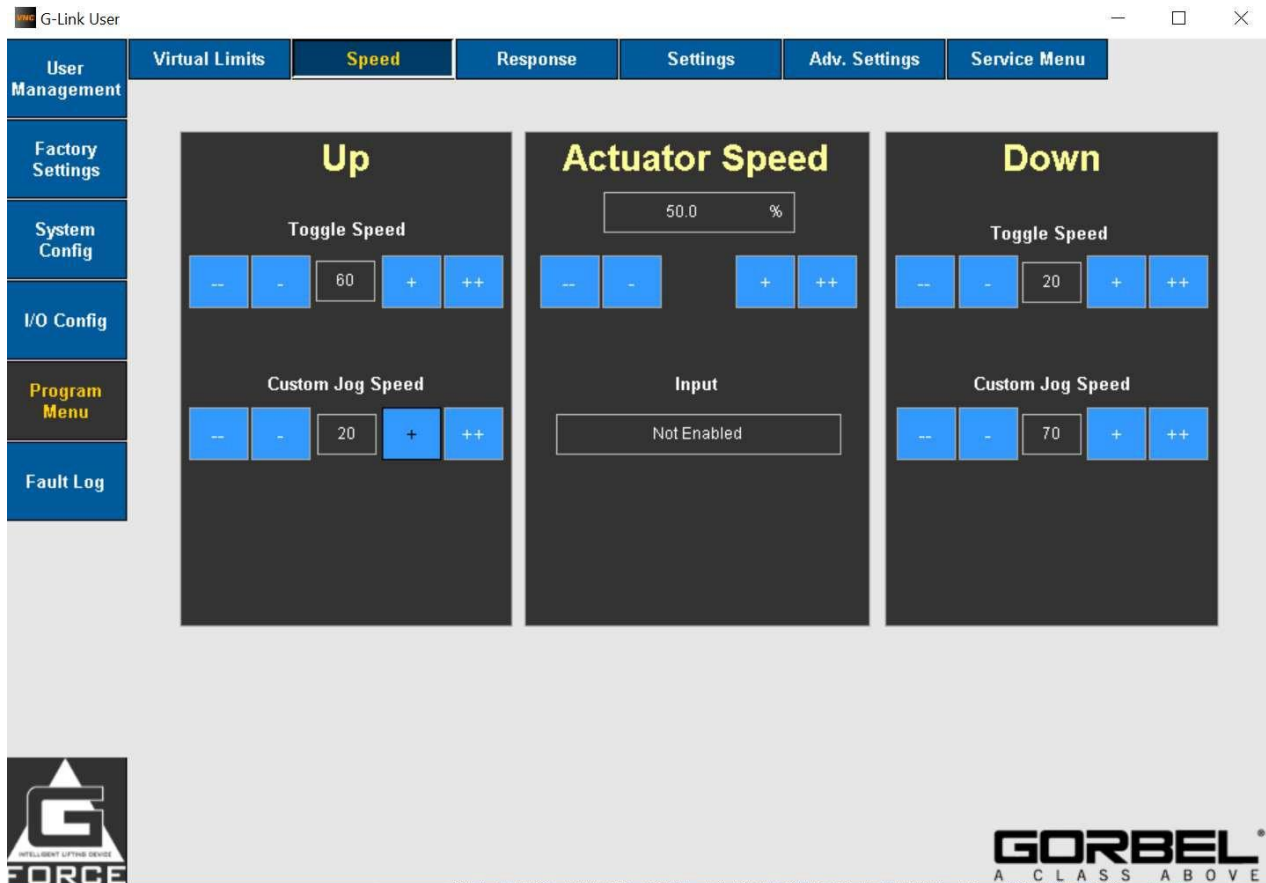
Feature	Description
Expansion Block I/O The Expansion Block I/O will come with 8 configurable I/O points (User can choose whether it's an input or an output). The set of input features will be identical to PLC I/O. iQ2 units will have Actuator I/O and/or an I/O Block.	
Handle I/O The Handle I/O will come with 2 inputs and 2 outputs. Identical features to PLC I/O. Q2 units will have Handle I/O to configure.	
Clear All	Resets the I/O to factory default.
Standard Presets	Clears all the inputs and outputs.
Apply Settings and Restart	This has to be pressed anytime the configuration is changed for changes to come into effect.

APPENDIX A: HMI EXPLANATION (continued)



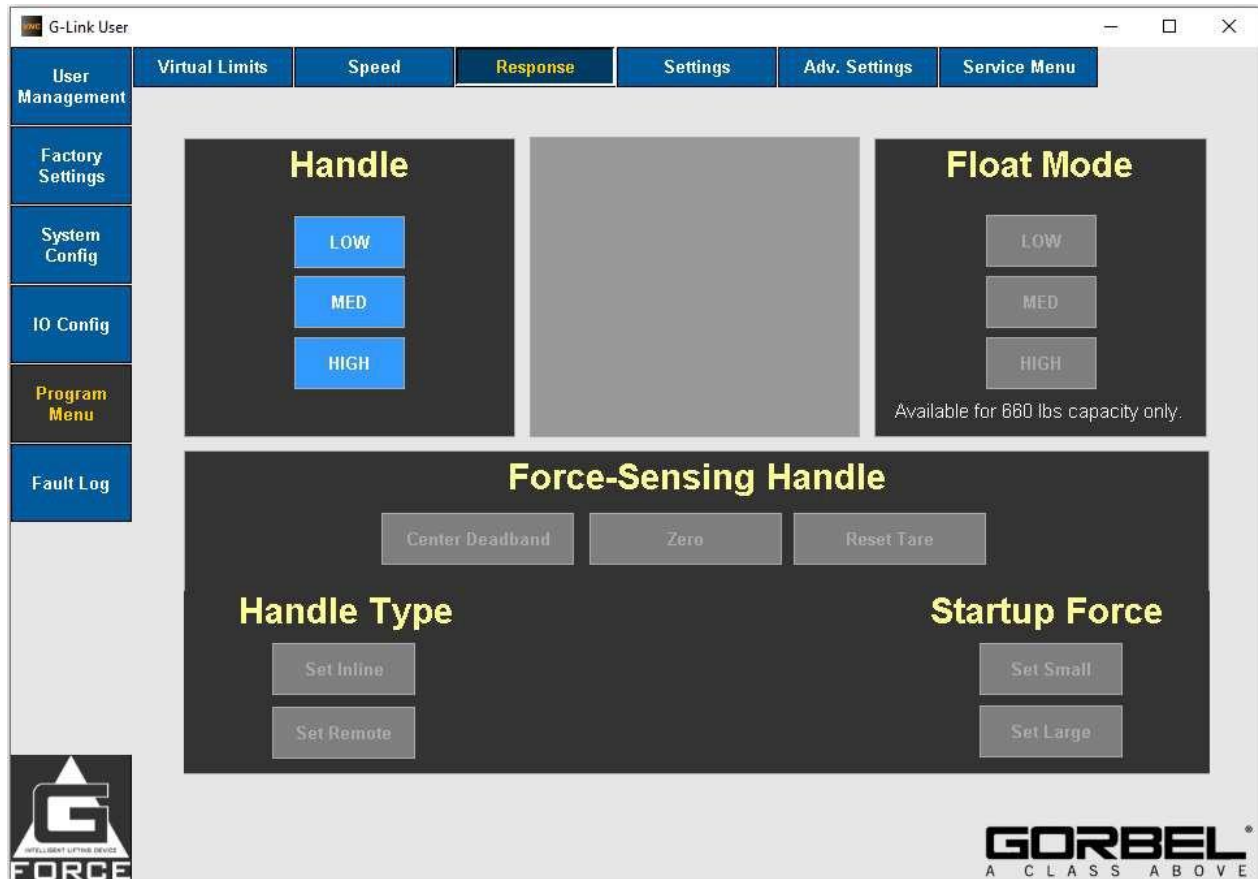
Feature	Description
Virtual Limits The difference between setting and enabling is that 'set' saves the hoist position, while 'enable' activates the virtual limit.	
Number	This number is for choosing the set of virtual limits you're trying to set (max is 4)
Upper Limit	Program the upper virtual limit (load must be at desired position for upper limit).
Lower Limit	Program the lower virtual limit (load must be at desired position for lower limit).
Upper Slowdown	Program the upper slow down reduction point (load must be at position where slow-down begins when raising load).
Lower Slowdown	Program the upper slow down reduction point (load must be at position where slow-down begins when raising load).
Upper resume	Program the upper speed resume point (load must be at position where system will resume normal speed when raising load).
Slowdown Speed	Choose the slowdown speed for both upper and lower slowdown. (from 5% to 50% in increments of 5%)
Enable All	This is where the user can enable all the Virtual Limit features.
Disable All	This is where the user can disable all the Virtual Limit features.
Actual Hoist Position	Displays the current position corresponding of the Hoist in a counts value

APPENDIX A: HMI EXPLANATION (continued)



Feature	Description
Up	
Toggle speed	This is regarding the Toggle Speed Input selection. If that input is on, the unit changes speeds to this set speed. If the input is off, it goes back to hoist speed selected.
Custom Jog Speed	This is regarding the Jog Input selection. If that input is on, the unit changes upward jog speed to this set value.
Actuator Speed	
Set Speed	If this is selected, the max speed of the motor is restricted.
Input	Displays the location of where the Toggle Speed was configured, either on the PLC, Expansion Block, or Handle I/O
Down	
Toggle speed	This is regarding the Toggle Input selection. If that input is on, the unit changes speeds to this set speed. If the input is off, it goes back to hoist speed selected.

APPENDIX A: HMI EXPLANATION (continued)

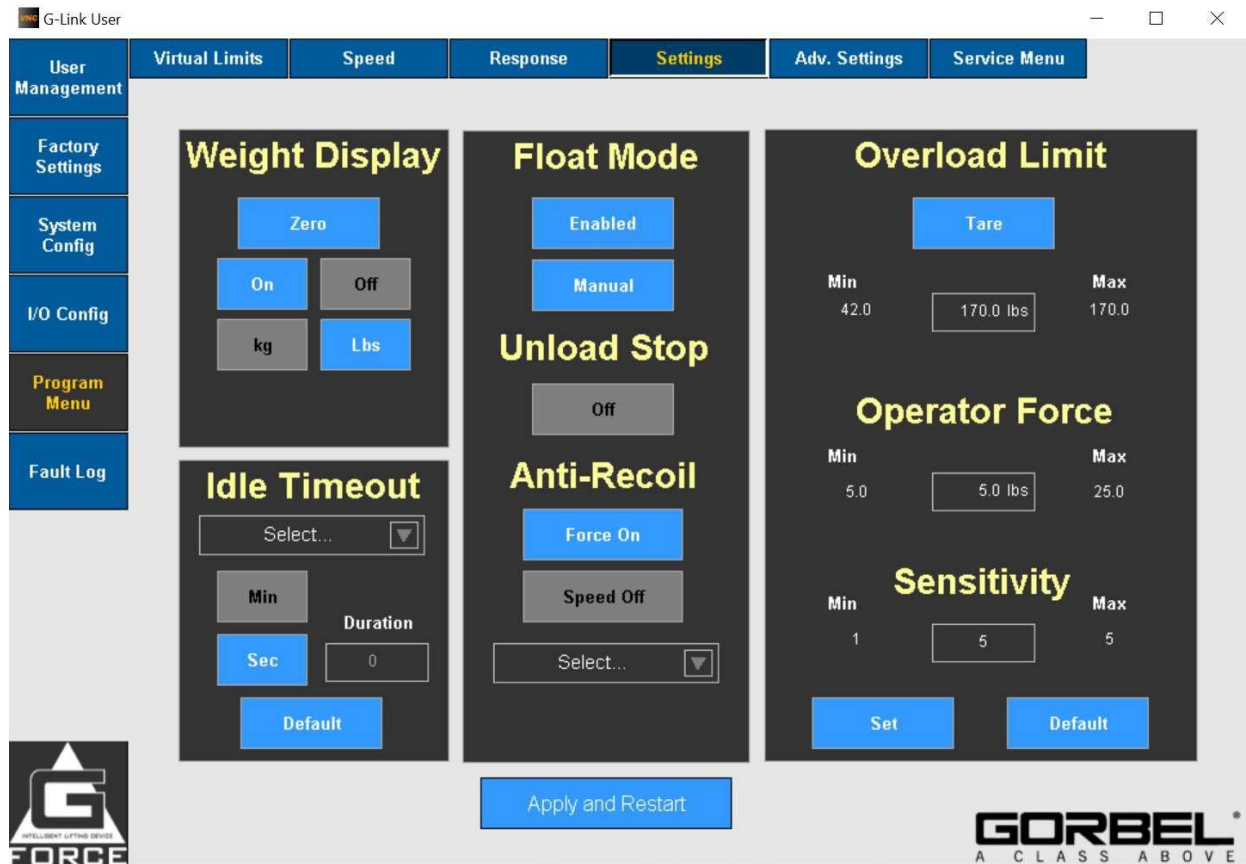


Feature	Description
Handle	
Low	Set the lowest handle control response corresponding to about 75% of the highest responsiveness setting.
Med	Set the medium handle control response corresponding to about 85% of the highest responsiveness setting.
High	Set the highest handle control responsiveness setting.
Float	
Low	Lowest (least responsive / most stable) Float Mode gains.
Med	Default Float Mode gains with normal responsiveness / stability.
High	Highest (more responsive / least stable) Float Mode gains.
Force Sensing Handle	
Center Deadband	FSH deadband averaging can be used to improve sensitivity of FSH signal by centering it.

APPENDIX A: HMI EXPLANATION (continued)

Feature	Description
Handle	
Zero	Tare the FSH handle bar weight to zero the load cell signal.
Reset Tare	Reset FSH tare value from zero to un-zero the load cell signal.
Set Inline	Change FSH style to inline if current style is remote.
Set Remote	Change FSH style to remote if current style is inline.
Set Small	Change FSH Start up force to small.
Set Large	Change FSH Start up force to large.

APPENDIX A: HMI EXPLANATION (continued)



Feature	Description
Weight Display	
Zero	Zero the weight display.
On/Off	Turns the weight display ON/OFF on the OLED.
kg/Lbs.	Sets the units of the weight display, separately from the Unit Select configuration.
Idle Timeout	
Select	Choose which idle time to configure. (multiple idle times can be set concurrently between jog, float, or custom)
Min/Sec	Select the mins or secs to configure the idle time.
Default	Apply default excessive pause timer settings: slide and pendant handles (45 seconds), Float Mode (60 seconds) and custom motion (20 seconds).
Float mode	
Enabled/Disabled	Button that indicates the current status of float mode. Click it to toggle the enable / disable.
Manual/Auto	Change between manual float mode and Auto Float mode. The way auto float works is if it detects a pre-set weight, it triggers float mode automatically.

APPENDIX A: HMI EXPLANATION (continued)

Unload Stop	
Optional feature utilizing Anti-Recoil detection. When user sets a weight onto a surface in Float Mode, it is terminated if Anti-Recoil detects an unloading. This can be useful for applications needing a quick Float Mode exit to an idle state to allow user to work on the part. Note: As a result of the extra detection, Float Mode is likely to terminate when the upper limit switch is hit while unit is running at a fast speed. This false detection can be avoided or reduced by running the unit at a low speed or maintaining a distance from the upper limit.	
Anti-Recoil	
Force On/Off	Over-Force Detection: Unit terminates Float Mode if user's operating force exceeds the maximum force limit or a dropped weight is detected by evaluating the force profile.
Speed On/Off	Over-Speed Detection: Unit terminates Float Mode if speed exceeds maximum Float Mode speed at 90% of unit loaded speed.
Select	This is to choose Force ON detection force. (15 to 45 lbs. in increments of 5 lbs.)
Overload	
Tare	Set the overload limit to the current load weight.
Overload Limit	Program an overload limit.
Operator force	Configure operating force limit for moving a load in air. Refer to I&O Manual for details.
Sensitivity	Configure overload detection sensitivity.
Set	When you make changes to either overload limit, operator force, or sensitivity, the set button must be pressed.
Default	Sets overload settings to default

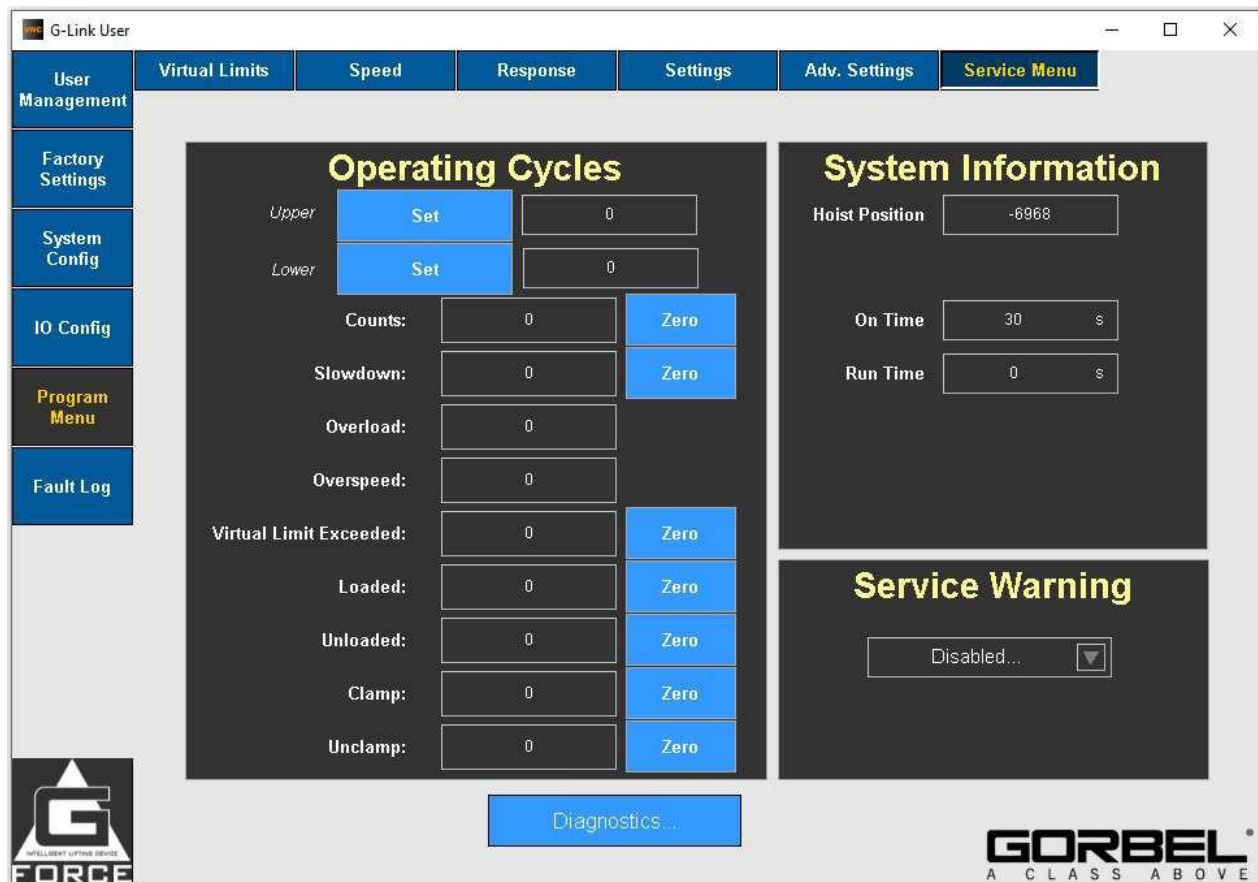
APPENDIX A: HMI EXPLANATION (continued)

The screenshot displays the G-Link User HMI interface. At the top, there is a navigation bar with tabs: User Management, Virtual Limits, Speed, Response, Settings, **Adv. Settings** (highlighted), and Service Menu. On the left side, a vertical menu lists: User Management, Factory Settings, System Config, IO Config, **Program Menu** (highlighted), and Fault Log. The main area is divided into three sections. On the left, under the heading 'Feature', there is a list of four items: Multiple FM Tool Weight, Multiple FM Load Weight, Anti-Drop Tool Weight, and Auto Home Position. In the center, there are four 'Set' buttons, each corresponding to one of the features listed on the left. On the right, under the heading 'Value', there are four input fields, each containing the number '0'. Above these input fields, there are two status displays: 'Calculated Weight' showing '0.0 lbs' and 'Hoist Position' showing '-6968'. At the bottom left is the 'FORCE' logo, and at the bottom right is the 'GORBEL' logo with the tagline 'A CLASS ABOVE'.

Feature	
Multiple FM Tool Weight	Program the feature by clicking Set at the desired value shown in the “Value” column
Multiple FM Load Weight	Program the feature by clicking Set at the desired value shown in the “Value” column
Anti-Drop Tool Weight	Program the feature by clicking Set at the desired value shown in the “Value” column
Auto Home Position	Program the feature by clicking Set at the desired value shown in the “Value” column

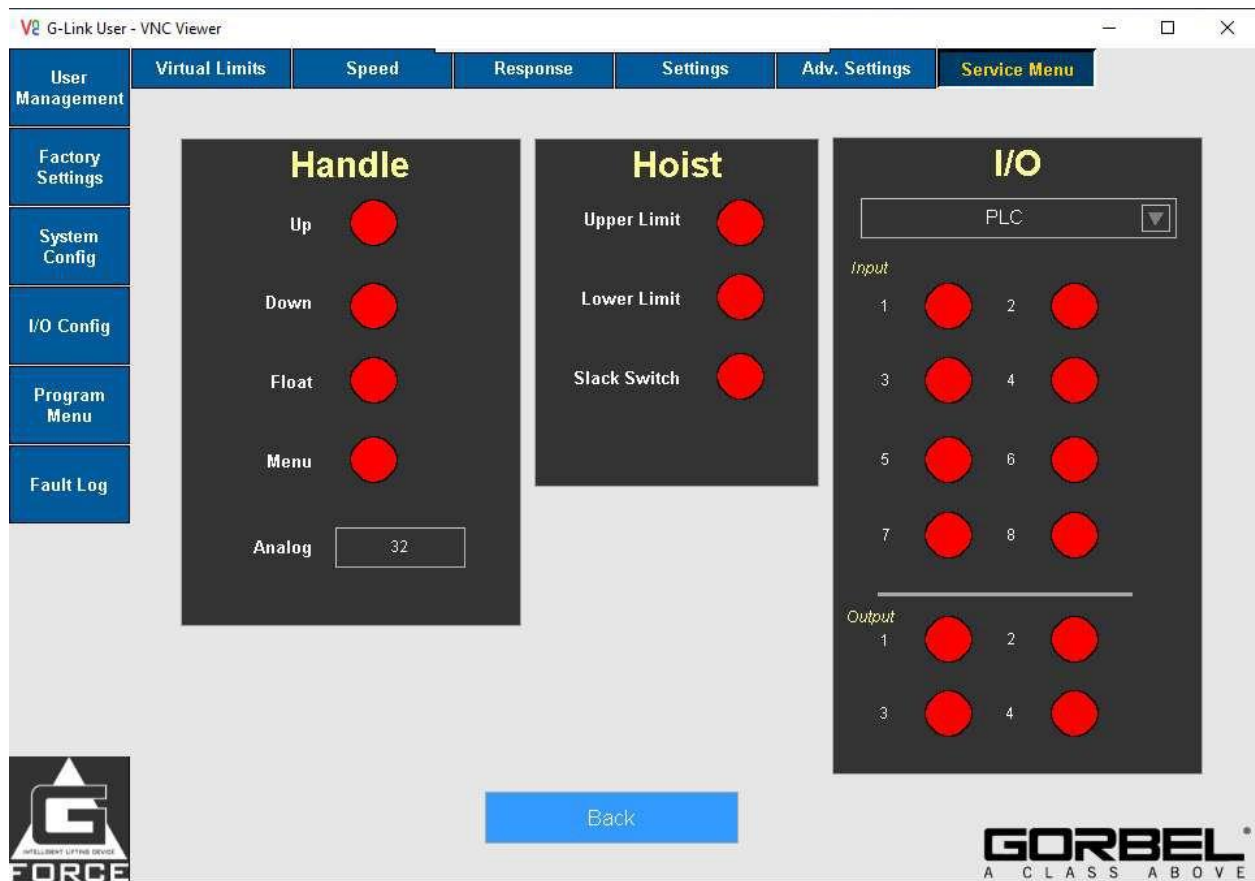
*Refer to I&O Manual for more feature info.

APPENDIX A: HMI EXPLANATION (continued)



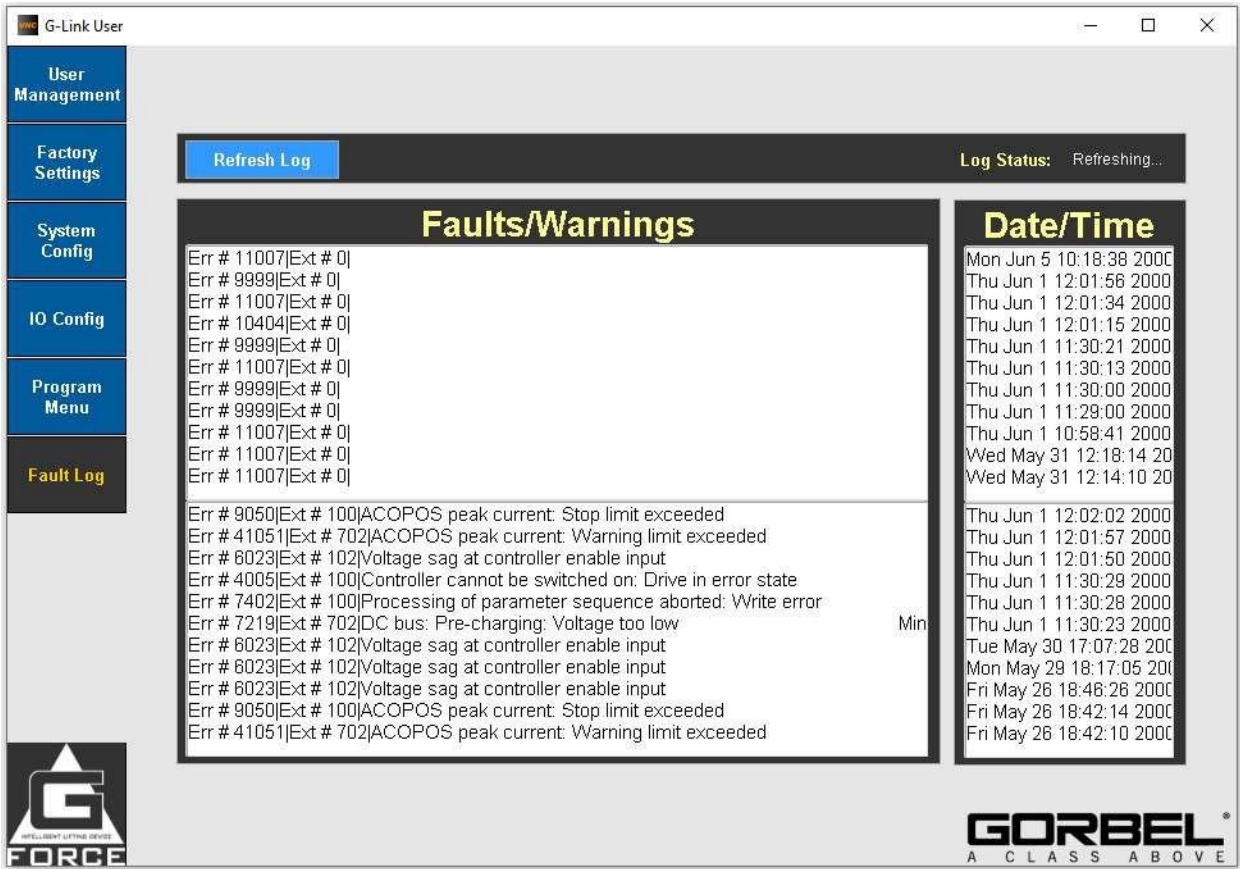
Feature	Description
Operating Cycle	
Upper (Set)	Set the upper hoist position for cycles.
Lower (Set)	Set the lower hoist position for cycles.
Zero	Zero the variable (for counts, slowdown, loaded, unloaded...etc)
System Information	
Hoist Position	Current hoist position of the unit.
On time	Total time the unit was on.
Run time	Total run time (in use)
Service Warning	
User can select a duration for a service warning to pop up. (between 500, 1000, and 1500 hours)	

APPENDIX A: HMI EXPLANATION (continued)



Feature	Description
Diagnostics Page	
Handle	Lights indicate when handle options are triggered, and Analog indicates the current value of the analog control signal in counts.
Hoist	Lights indicate if the Upper / Lower limit or Slack switches are triggered.
I/O	Toggle to choose between PLC / Handle / Expansion Block I/O and view the indication based on whether the input is triggered.

APPENDIX A: HMI EXPLANATION (continued)



Feature	Description
Command Faults & Warnings The upper pane shows the most recent 20 Command Faults & Warnings.	
Drive Faults The lower pane shows the most recent 20 Drive Faults.	
Refresh Log	Updates the log list with any new or active errors.

APPENDIX B: WiFi Access Point Set Up Instructions

Gorbel's Easy Arm® Q₂ and iQ₂ Intelligent Lifting Devices were designed with G-Link™ Smart Connect technology. G-Link enables units to transmit data locally or anywhere with internet access. It also allows users to set parameters remotely from a desktop, laptop, or tablet. The following pages walk you through how to connect to your Easy Arm unit.

Access Point Settings:

To change one of the following details:

- SSID Access Point Name
- Access Point Password
- Transmit Power Setting (contact Gorbel)
- Transmit Channel Setting
- Mode Change from Access Point or Station

Connect via WiFi, open a browser and connect to 192.168.105.1 and login using “**Order Number**” to change any of these fields. *Your order number is on the front cover of this manual.*

Change the SSID (AP Name) or Password Instructions:

Default Settings:

- AP SSID: G-Force AP Order Number
- AP Password: Order Number
- Station SSID: G-Force STA
- Station Password: mypassword

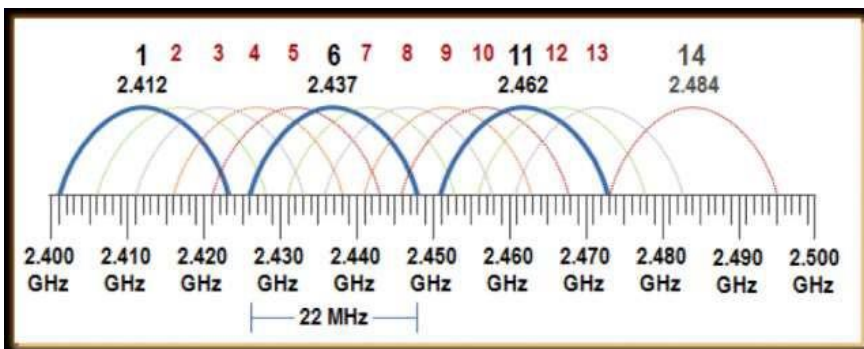
You can change the password.

The new password must be:

- Minimum of 8 characters in length
- Allowed SSID characters: !\$%&_-
- Allowed Password characters: !\$%&_-
-

Transmit Channel Instructions:

If there are multiple units with configured APs choose a transmit channel further away from the others. E.g.: When using 3 Easy Arms, use 3 channels, i.e. use 1, 6 and 11 for the channels to be spread across the bandwidth. Click done to apply settings and wait 10 seconds to reboot.



APPENDIX B: WiFi Access Point Set Up Instructions (continued)

NC Viewer Appendix

Download the suggested VNC viewer (recommended by Gorbel®)

You can download the latest version by copying and pasting this link into your browser:

<https://www.br-automation.com/en-us/downloads/software/hmi-software/vnc-viewer/vnc-viewer-winxp-win7-win81-win10/?noredirect=1>

Install:

- a) Unzip the downloaded VNC file
- b) Click on the BrVncViewer in the unzipped folder (Windows Installer File Type) (Fig: 12) and install the application on the local windows machine.

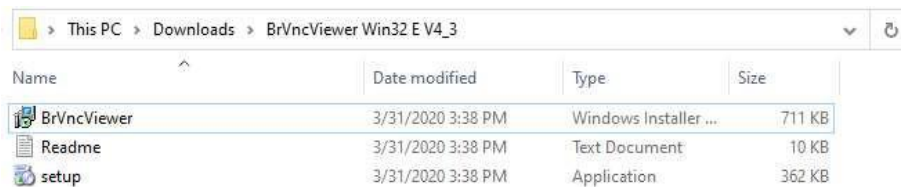


Figure 12: Unzipped/Extracted folder

- c) Once successfully installed, go to Start Menu and open the “VNC Viewer” by either typing in the search bar and clicking on it, or opening the B&R Automation folder and clicking the application (Fig 13)

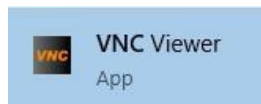
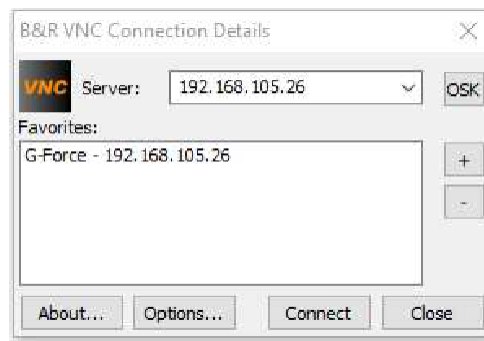


Figure 13: VNC Icon

Connect: Connect to the Easy Arm® AP (See Appendix 2 for instructions on the AP) at the G-Force® IP Address

192.168.105.26 on the VNC viewer and click **Connect**.



APPENDIX B: WiFi Access Point Set Up Instructions (continued)

Customer AP Quick Start Guide

Find out your Easy Arm® SSID: Select the Internet Network Icon in the taskbar and search for the WiFi Network with the Easy Arm® access point name. Connect and log in.

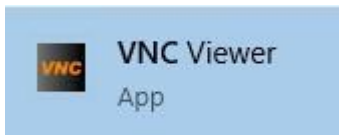
Factory Default SSID: Easy Arm ® AP 123456-1

(this represents your order number, which you can find on the front cover of this manual)

Factory Default Password: 123456-1

Open VNC Viewer Application:

Open a VNC viewer program on your PC. Need a VNC Viewer Program?
Gorbel® recommends the B&R VNC Viewer (See Appendix 2 for Instructions to set up).



Specify G-Force® IP Address:

The VNC Viewer needs the Easy Arm® IP Address to connect.
Enter the Easy Arm® IP address in the Server field and click Connect.

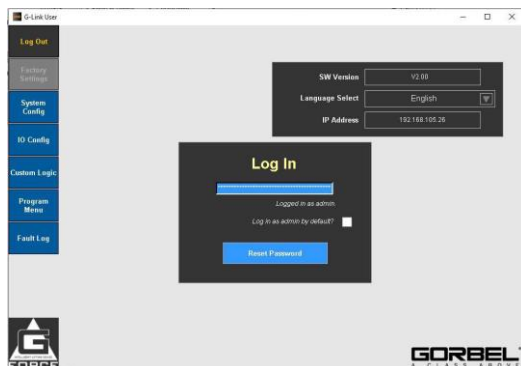
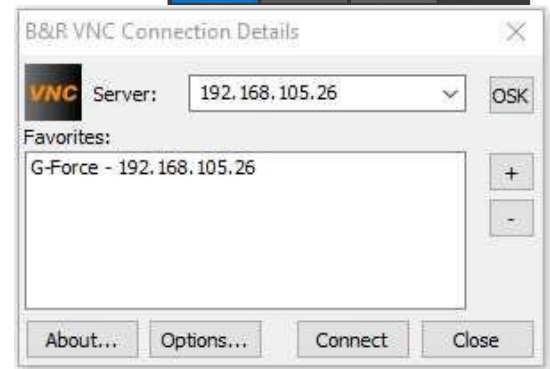
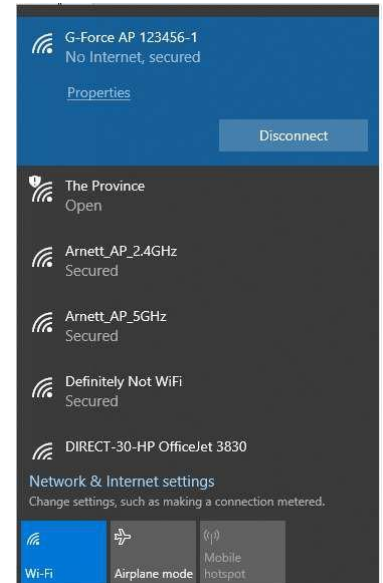
Factory Default IP Address: 192.168.105.26

Note:

The IP Addresses of your Easy Arm units can be added as favorites with custom names to make it easier when working in an environment with multiple Easy Arms.

Log into the Easy Arm®:

Click on the blue log in field and enter the passcode. Ensure that the VNC interface has loaded successfully by confirming the text “Logged in as admin” is present and Navigation Buttons along left side of screen are active.



APPENDIX C: I/O Default Configuration and Description

Safety precautions before proceeding

Activities described in this procedure can cause personal harm. The minimum personal protective equipment (PPE) that must be worn at all times include safety glasses with side shields and safety shoes. Additional PPE required for specific activities will be noted within the instructions.

Tools needed:

G-Force Q2 or iQ2 device

Laptop with VNC software (suggested – Tight VNC)

WiFi capability to remotely connect to the G-Force OR Ethernet cable connected from J7 (Black) port on the G-Force to the computer

5.1 Opening IO Page

- Open the VNC viewer (Refer to Appendix B for steps to install the VNC)
- Connect to the G-Force on the VNC using the IP address 192.168.105.26 (Ref: Fig 1)
- Log in by selecting the blue log in field and entering the password: “2” (or, followed by the enter key on the virtual keyboard (Ref: Fig 2)
- Click the IO Config tab on the left pane of the Visualization to open the Input/Output Configuration page

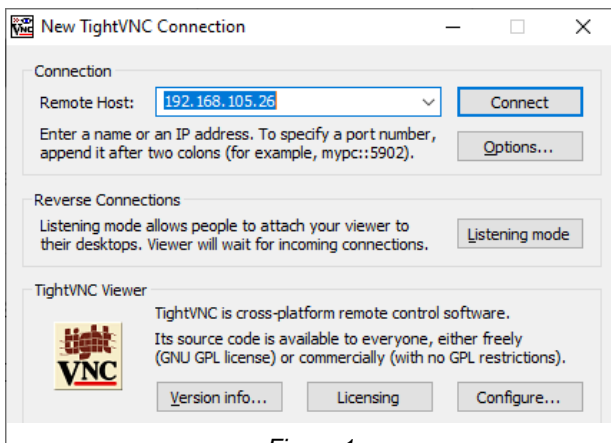


Figure 1

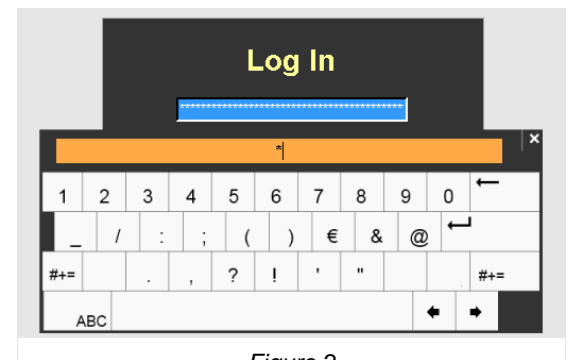


Figure 2

5.2 IO Types

iQ unit: Navigate to the Actuator tab on the top (If that tab is not already selected) – 8 actuator Inputs and 4 Outputs can be configured on this page (Ref: Fig 3)

If expansion block IO is also available, navigate to the IO and Handle tab on the top and then I/O Block can also be configured (Ref: Fig 4)

Note 1: The Expansion I/O Block can be configured as both Input and Output (Click on Input to toggle it to an output). This block contains 8 IO points, which can each be configured as an input or an output.

Note 2: If actuator IO is only present and more IO is desired, please contact Gorbels CSR.

APPENDIX C: I/O Default Configuration and Description (continued)

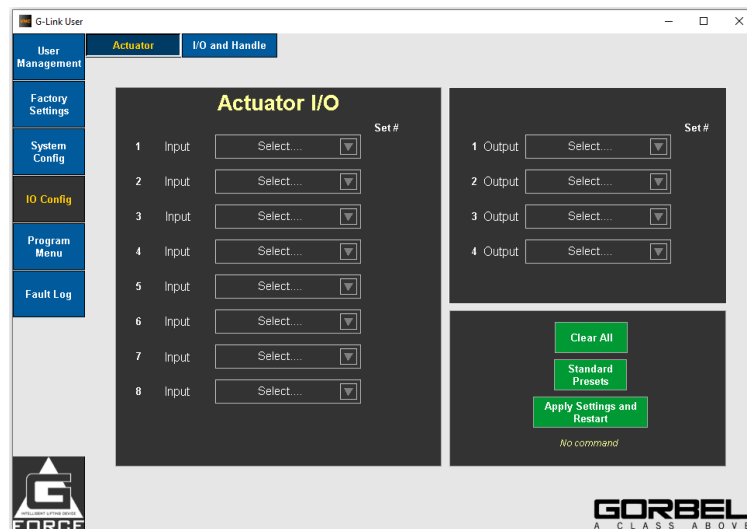


Figure 3

Q2 Unit: Navigate to the IO and handle tab on the top – Only Handle IO can be configured (Ref: Fig 4 – Handle) On this page, 2 inputs and 2 outputs can be configured.

NOTE: If more Inputs/Outputs are desired, please contact Gorbel CSR.

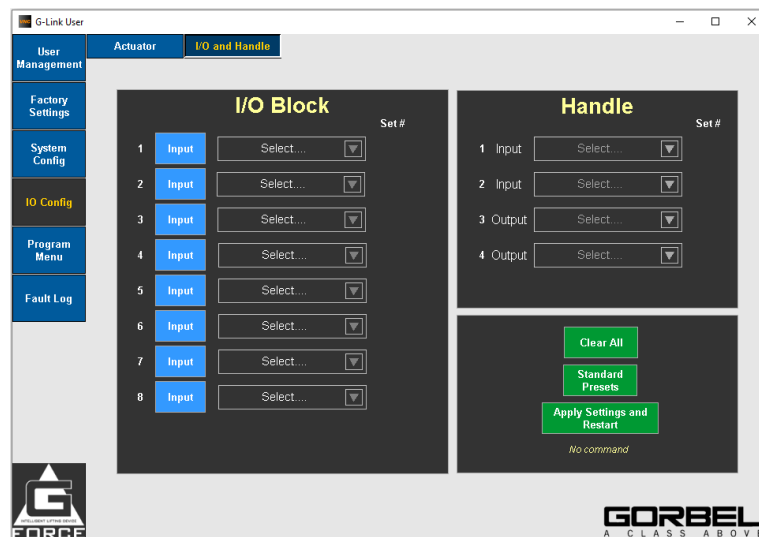


Figure 4

5.3 Understanding IO options and functionality

Any of these Inputs / Outputs can be set on the Actuator IO, Expansion IO Block or the Handle IO
NOTE: It is advised to not select the same Input / Output option at multiple points within the same IO slice or at other blocks.

APPENDIX C: I/O Default Configuration and Description (continued)

Feature	Description
INPUTS	
AD Clamp	Anti-Drop Clamp input signal. This input is typically wired to a clamp request pushbutton. Clicking this input would actuate any clamp that is linked to the output Clamp Signal . Ensure that an Anti-drop tool weight has to be set on the Advanced Settings tab on the Settings Page.
AD Unclamp	This input is typically wired to an unclamp request pushbutton. When the input is on, an Output (Unclamp Signal) turns on only if Anti-Drop algorithm determines if the suspended load is at or below the set weight (ANTIDROP TOOL WT). i.e If the user attempts to unclamp when lifting a weight using the tool, the G-Force / Easy Arm does not allow unclamp to be triggered, ensuring that the weight is not dropped.
AD Clamp/Unclamp	Toggle to input switch (Momentary input) to change status from Clamp to Unclamp. An output (AD Clamp/Unclamp) can be set to see the status. Unclamp signal Input does not trigger the unclamp output when lifting a weight, thereby protecting a weight from being dropped.
Setting Anti-Drop Tool weight: To use the Anti Drop Clamp and Unclamp inputs and outputs, navigate to the Advanced Settings Tab on the settings page, and click on set (When only the tool is being set). NOTE: If any I/O changes are made, the Anti-Drop Tool weight has to be set again to continue using the Clamp and Unclamp inputs/outputs.	
Auto-Home	When this input is toggled (momentarily turned on then off again), the G-Force® automatically travels to the set home position in the vertical travel.
Setting Auto-Home Position: To use the Auto-Home input, navigate to the Advanced Settings Tab on the settings page, and click on set Auto-Home position (When moved and set at the desired position). NOTE: If any I/O changes are made, the Auto-Home position has to be set again to continue using the Clamp and Unclamp inputs/outputs.	
Dual Float	When the G-Force® is in float mode, this input allows switching from one pre-programmed load weight to another. (Change from tool weight to tool + load weight)
Setting Dual Float Weight: To use the Dual Float input, navigate to the Advanced Settings Tab on the settings page, and click on set Multiple FM tool weight when just the tool weight – weight 1 is lifted. Then lift weight 2 (tool + load weight) and click on Set Multiple FM load weight . NOTE: If any I/O changes are made, ensure that the weights are set correctly.	
Inhibit Motion	This is a maintained input, and it inhibits motion both UP and DOWN if it's ON.
Inhibit Motion Up	This is a maintained input, and it inhibits motion UP if it's ON.
Inhibit Motion Down	This is a maintained input, and it inhibits motion DOWN if it's ON.
Setting Multiple Inhibit Motion Inputs: It is advised against assigning multiple Inputs to Inhibit Motions (Eg: Assigning Input 2 to Inhibit Motion and Input 3 to Inhibit Motion – In this case only the last set Input (Input 3) works). Therefore, always assign one of the three Inhibit Motion Inputs.	
Multi-Zone VL (Set 0 to 2)	When this input is turned on and a set number is selected on the I/O page, toggling the input for the corresponding set makes the G-Force® switch to that particular independent set of virtual limits. By default Virtual Limit Set 1 is active, Setting a Multi-Zone VL Set 0 as an input enables Virtual Limit Set 2. NOTE: The inputs are to be set from 0 onwards, and it is advised to not select a higher set before any previous VL sets are assigned on the I/O

APPENDIX C: I/O Default Configuration and Description (continued)

Understanding VL Limits			
Inputs on I/O Page			Virtual Limit Set on Settings – Virtual Limits
Multi VL Set 0	Multi VL Set 1	Multi VL Set 2	Active Multi-VL Set
OFF	OFF	OFF	1
ON	OFF	OFF	2
OFF	ON	OFF	3
OFF	OFF	ON	4
ON	ON	ON	Error (Only 1 VL input must be switched ON at one time)
Remote Float			This is a momentary input to activate float mode.
Toggle Speed			This is a maintained input, and when it's ON it switches the speed to a pre-set one (from the program menu page).
Setting Toggle Speed: To set toggle speed, navigate to the Speed Menu Tab on the Settings page, and click on + (to add 5%) or ++ (to add 10%) (Vice Versa for – and --) on the Toggle Up Speed and Toggle Down Speed to set the desired speed.			
Jog Up			This is a maintained input, and when it's ON it jogs up based on the set Custom Up Jog speed
Jog Down			This is a maintained input, and when it's ON it jogs down based on the set Custom Down Jog speed
Setting Custom Jog Speed: To set jog speed, navigate to the Speed Menu Tab on the Settings page, and click on + (to add 5%) or ++ (to add 10%) (Vice Versa for – and --) on the Custom Jog Up Speed and Custom Jog Down Speed to set the desired speed. If this speed is 0, turning the Jog Inputs ON would not move the hoist up/down.			
External Control Input [Set] (There are two External Control Inputs that can be set – Set 0 and Set 1) NOTE: Set 0 has to be set before Set 1			When this input is on, a selected output on the PLC/Expansion block input/output module is on and vice versa.
Float mode Quit			This is a momentary input to deactivate float mode.
OUTPUTS			
Clamp Signal			This output is typically wired to actuate the clamping mechanism of an end effector tooling. It turns on when AD Clamp input is on and remains latched on when the input is released.
UnClamp Signal			This output is typically wired to actuate the clamping mechanism of an end effector tooling. It turns on when AD UnClamp input is on and remains latched on when the input is released.
Clamp / Unclamp Signal			This output is wired to actuate the clamping mechanism of an end effector tooling. This output offers a fail-safe (It does not unclamp when lifting a load – The internal Anti-drop algorithm ensures this). It is used along with the AD Clamp/Unclamp Input
Slack Detection			If the unit experiences slack, this output turns on.
Run Mode			If the unit is in Run Mode, the output is on.
In Motion			If the unit is in motion in any mode, this output is on.
Float Mode			If the unit is in float mode, this output turns on.
Upper Limit			If the unit reaches the upper limit, this output turns on.
Lower Limit			If the unit reaches the lower limit, this output turns on.
OPS Active			If the OPS is active, when the operator presence is detected, this output turns on.
E-Stop Pressed			If E-stop is engaged, this output turns off, otherwise it is always on.
External Control Output [Set] (There are two External Control Inputs that can be set – Set 0 and Set 1) NOTE: Set 0 has to be set before Set 1			When this input is on, a selected output on the PLC/Expansion block input/output module is on and vice versa.

APPENDIX C: I/O Default Configuration and Description (continued)

Fault Indicator	If there is a fault (error) in the unit, this output turns on.
Service Indicator	If the service duration that is set is reached, the output turns ON.
Setting Service Warning: To set the Service Warning speed, navigate to the Service Menu Tab on the Settings page. Click on the drop down to choose between Disabled or a specific Duration. (Eg: When the G-Force has been used for the specified 500 hrs, it will enable to output).	
IO CONFIG SETTINGS	
Clear All	Clears all the inputs and outputs.
Standard Presets	Resets the I/O to factory default.
Apply Settings and Restart	This must be pressed anytime the configuration is changed for changes to take effect.

LIMITED WARRANTY

It is agreed that the equipment purchased hereunder is subject to the following LIMITED warranty and no other. Gorbelt Incorporated ("Gorbelt") warrants the manual push-pull Work Station Cranes, Jib Crane, and Gantry Crane products to be free from defects in material or workmanship for a period of ten years or 20,000 hours use from date of shipment. Gorbelt warrants the Motorized Work Station Cranes and Jib Crane products to be free from defects in material or workmanship for a period of two years or 4,000 hours use from the date of shipment. Gorbelt warrants the G-Force® and Easy Arm™ products to be free from defects in material or workmanship for a period of one year or 2,000 hours use from the date of shipment. This warranty does not cover Gantry Crane wheels. This warranty shall not cover failure or defective operation caused by operation in excess of recommended capacities, misuses, negligence or accident, and alteration or repair not authorized by Gorbelt. No system shall be field modified after manufacture without the written authorization of Gorbelt, Inc. Any field modification made to the system without the written authorization of Gorbelt, Inc. shall void Gorbelt's warranty obligation. OTHER THAN AS SET FORTH HEREIN, NO OTHER EXPRESS WARRANTIES, AND NO IMPLIED WARRANTIES, ORAL OR WRITTEN, INCLUDING BUT NOT LIMITED TO THE WARRANTIES OF MERCHANTABILITY OR FITNESS FOR A PARTICULAR PURPOSE, ARE MADE BY GORBEL WITH RESPECT TO ITS PRODUCTS AND ALL SUCH WARRANTIES ARE HEREBY SPECIFICALLY DISCLAIMED. GORBEL SHALL NOT BE LIABLE UNDER ANY CIRCUMSTANCES FOR ANY INCIDENTAL, SPECIAL AND/OR CONSEQUENTIAL DAMAGES WHATSOEVER, WHETHER OR NOT FORESEEABLE, INCLUDING BUT NOT LIMITED TO DAMAGES FOR LOST PROFITS AND ALL SUCH INCIDENTAL, SPECIAL AND/OR CONSEQUENTIAL DAMAGES ARE HEREBY ALSO SPECIFICALLY DISCLAIMED. Gorbelt's obligation and Purchaser's or end user's sole remedy under this warranty is limited to the replacement or repair of Gorbelt's products at the factory, or at the discretion of Gorbelt, at a location designated by Gorbelt. Purchaser or end user shall be solely responsible for all freight and transportation costs incurred in connection with any warranty work provided by Gorbelt hereunder. Gorbelt will not be liable for any loss, injury or damage to persons or property, nor for damages of any kind resulting from failure or defective operation of any materials or equipment furnished hereunder. Components and accessories not manufactured by Gorbelt are not included in this warranty. Purchaser's or end user's remedy for components and accessories not manufactured by Gorbelt is limited to and determined by the terms and conditions of the warranty provided by the respective manufacturers of such components and accessories.

A) DISCLAIMER OF IMPLIED WARRANTY OF MERCHANTABILITY

Gorbelt and Purchaser agree that the implied warranty of merchantability is excluded from this transaction and shall not apply to the goods involved in this transaction.

B) DISCLAIMER OF IMPLIED WARRANTY OF FITNESS FOR PARTICULAR PURPOSE

Gorbelt and Purchaser agree that the implied warranty of fitness for particular purpose is excluded from this transaction and shall not apply to the goods involved in this transaction.

C) DISCLAIMER OF EXPRESS WARRANTY

Gorbelt's agents, or dealer's agents, or distributor's agents may have made oral statements about the machinery and equipment described in this transaction. Such statements do not constitute warranties, and Purchaser agrees not to rely on such statements. Purchaser also agrees that such statements are not part of this transaction.

D) DISCLAIMER OF SPECIAL, INCIDENTAL AND CONSEQUENTIAL DAMAGES

Gorbelt and Purchaser agree that any claim made by Purchaser which is inconsistent with Gorbelt's obligations and the warranty remedies provided with Gorbelt's products, and in particular, special, incidental and consequential damages, are expressly excluded.

E) DEALER OR DISTRIBUTOR NOT AN AGENT

Gorbelt and Purchaser agree that Purchaser has been put on notice that dealer or distributor is not Gorbelt's agent in any respect for any reason. Gorbelt and Purchaser also agree that Purchaser has been put on notice that dealer or distributor is not authorized to incur any obligations or to make any representations or warranties on Gorbelt's behalf other than those specifically set forth in Gorbelt's warranty provided in connection with its product.

F) MERGER

This warranty agreement constitutes a final and complete written expression of all the terms and conditions of this warranty and is a complete and exclusive statement of those terms.

G) PAINTING

Every crane (excluding components) receives a quality paint job before leaving the factory. Unfortunately, no paint will protect against the abuses received during the transportation process via common carrier. We have included at least one (1) twelve ounce spray can for touchup with each crane ordered (unless special paint was specified). If additional paint is required, contact a Gorbelt® Customer Service Representative at 1-800-821-0086 or 1-585-924-6262.

Title and Ownership:

Title to the machinery and equipment described in the foregoing proposal shall remain with Gorbelt and shall not pass to the Purchaser until the full amount herein agreed to be paid has been fully paid in cash.

Claims and Damages:

Unless expressly stated in writing, goods and equipment shall be at Purchaser's risk on and after Seller's delivery in good shipping order to the Carrier. Gorbelt shall in no event be held responsible for materials furnished or work performed by any person other than it or its authorized representative or agent.

Cancellations:

If it becomes necessary for the purchaser to cancel this order wholly or in part, he shall at once so advise Gorbelt in writing. Upon receipt of such written notice all work will stop immediately. If the order entails only stock items, a flat restocking charge of 15% of the purchase price will become due and payable by Purchaser to Gorbelt. Items purchased specifically for the canceled order shall be charged for in accordance with the cancellation charges of our supplier plus 15% for handling in our factory. The cost of material and/or labor expended in general fabrication for the order shall be charged for on the basis of total costs to Gorbelt up to the time of cancellation plus 15%.

Returns:

No equipment, materials or parts may be returned to Gorbelt without express permission in writing to do so.

Extra Charge Delay: If Purchaser delays or interrupts progress of Seller's performance, or causes changes to be made, Purchaser agrees to reimburse Gorbelt for expense, if any, incident to such delay.

Changes and Alterations:

Gorbelt reserves the right to make changes in the details of construction of the equipment, as in its judgment, will be in the interest of the Purchaser; will make any changes in or additions to the equipment which may be agreed upon in writing by the Purchaser; and Gorbelt is not obligated to make such changes in products previously sold any customer.

Third Party Action:

Should Gorbelt have to resort to third party action to collect any amount due after thirty (30) days from date of invoice, the Purchaser agrees to pay collection costs, reasonable attorney's fees, court costs and legal interest.

OSHA Responsibilities:

Gorbelt agrees to fully cooperate with Purchaser in the design, manufacture or procurement of safety features or devices that comply with OSHA regulations. In the event additional equipment or labor shall be furnished by Gorbelt, it will be at prices and standard rates then in effect, or as may be mutually agreed upon at the time of the additional installation.

Equal Employment Opportunity:

Gorbelt agrees to take affirmative action to ensure equal employment opportunity for all job applicants and employees without regard to race, color, age, religion, sex, national origin, handicap, veteran, or marital status. Gorbelt agrees to maintain non-segregated work facilities and comply with rules and regulations of the Secretary of Labor or as otherwise provided by law or Executive Order.

CE Declaration of Conformity

Hereby, Gorbel Inc., declares that this material handling equipment is in compliance with the essential requirements and other relevant provisions listed below.

EMC Directive:	2014/30/EU	
Emissions Testing for Industrial Environments:	EN 61000-6-4:2007+A1:2011	
ISM Radio Frequency Equipment:	EN 55011:2009+A1:2010	
Electromagnetic Compatibility	EN6100-6-2: 2005 EN 61000-4-2 EN 61000-4-3 EN 61000-4-4 EN 61000-4-5 EN 61000-4-6 EN 61000-4-8	Immunity for Industrial Environments: Electrostatic Discharge Radiated Susceptibility Radiated, Radio-Frequency Field Immunity Electrical Fast Transient/Burst Surge Surge Immunity Conducted Susceptibility Power & Frequency Immunity
Low Voltage Directive: 98/68/EEC	EN 61010	Equipment for Measurement, Control & Laboratory Use
Machinery Directive: Standard:	2014/35/EU EN 60204-1:2010 EN 14492-2:2006+A1:2009	Equipment for Safety of Machinery Cranes – Power Driven Winches & Hoists Part 2: Power Driven Hoists

Manufacturer's Name: **Gorbel Inc.**
Manufacturer's Address: 600 Fishers Run
Fishers, NY 14453-0593

Product: G-Force & Easy Arm
Model: Q2 & iQ2
Capacity: 75kg, 150kg, 300kg, 600kg

Signature: Blake Reese

Blake Reese
Product Development Senior Electrical Engineer
Gorbel Inc.
Phone: 585-924-6262



INSPECTION AND MAINTENANCE SCHEDULE

GORBEL G-FORCE® INSPECTION AND MAINTENANCE SCHEDULE			
ITEM	COMPONENT	MAINTENANCE	FREQUENCY*
1	Wire Rope	Look for any obvious external defects, damage or excessive wear. Check the lower end where it attaches to the handle, swivel assembly or tooling (by others) for signs of damage or excessive wear.	Start of Each Shift
2	Wire Rope	Expose as much of the wire rope as possible and wipe it off with a clean dry cloth. Use the jog button to pay out as much wire rope as possible.	Monthly
3	Wire Rope	Maintenance listed in (1) as well as reduction of rope diameter below nominal diameter due to loss of core support, internal or external corrosion, or wear of outside wires; severely corroded or broken wires at end connections; or severely corroded, cracked, bent, worn, or improperly applied end connections.	Periodically (to be determined by qualified persons only)
4	Coil Cord Assembly	Look for any obvious external defects or damage caused by the wire rope or other external causes. Make sure all coil cord clamps are in place.	Start of Each Shift
5	Slack Switch Check Adjustment	Using the handle, lower the wire rope until it goes slack. There should be no additional movement downward once it is slack. If the wire rope continues to pay out, stop immediately and perform the slack switch adjustment. Check the coil cord and air hose clamps on the wear ring to ensure the wear ring is moving freely inside the actuator opening.	Initial Install & Monthly
6	Handle	Check for smooth operation of the handle. <ul style="list-style-type: none"> Slide Handle Only - Check operator present sensor for correct operation. Use a gentle puff of compressed air or a soft cloth to clean the sensor. Do not apply any pressure to the lens or do anything that may scratch it. Verify proper handle swivel functionality. Pendant Handle Only - Check levers to make sure they function smoothly. 	Start of Each Shift
7	Handle I/O Connections	Check connections at handle (if equipped). Wipe off any oil or other contamination from either handle at this time. Clean the OLED screen as well.	Monthly
8	Air Hose (if equipped)	Look for any obvious external damage or wear caused by the wire rope or other external causes. Make sure the air hose is secured properly with the correct clamps	Start of Each Shift
9	Load Hook and/or Tooling (by others)	Check that the load hook is secured properly to the handle or swivel. Make sure lock washers are compressed completely and any other associated hardware is secure.	Start of Each Shift
10	Easy Arm® Assembly	Conduct a visual inspection of the entire Easy Arm® unit.	Start of Each Shift
11	Limit Switches	Verify that the upper and lower limit switches are operating properly. Verify that the slack switch is operating properly. Replace switches immediately if they are faulty.	Initial Install and Start of Each Shift

* Federal, state and local codes may require inspection and maintenance checks more often. Please check the federal, state and local code manuals in your area.

WARNING

Any changes in rotating effort or unusual noises must be immediately identified and corrected.

For additional service information, please consult the G-Force Q2 and iQ2 Series Service Manual. Contact the Gobel After the Sales Service group to request a copy.

GORBEL®
A CLASS ABOVE

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